

MAR GREGORIOS COLLEGE OF ARTS & SCIENCE

Block No.8, College Road, Mogappair West, Chennai – 37

Affiliated to the University of Madras
Approved by the Government of Tamil Nadu
An ISO 9001:2015 Certified Institution



DEPARTMENT OF MATHEMATICS

SUBJECT NAME: REAL ANALYSIS-II

SUBJECT CODE: SM26B

SEMESTER: VI

PREPARED BY: PROF.S.C.PREMILA

UNIVERSITY OF MADRAS
B.Sc. DEGREE COURSE IN MATHEMATICS
SYLLABUS WITH EFFECT FROM 2020-2021

CORE-XIV: REAL ANALYSIS-II
(Common to B.Sc. Maths with Computer Applications)

Inst.Hrs : 6

Credits : 4

Learning outcomes:

Students will acquire knowledge about

- The Real Numbers and the Analytic Properties of Real- Valued Functions.
- The Analytic concepts of Connectedness, Compactness, Completeness And Calculus.

UNIT I

Continuous Functions on Metric Spaces: Open sets- closed sets- Discontinuous function on \mathbb{R}^1 . Connectedness, Completeness and Compactness :More about open sets- Connected sets. Chapter 5 Section 5.4 to 5.6 Chapter 6 Section 6.1 and 6.2

UNIT II

Bounded sets and totally bounded sets: Complete metric spaces- compact metric spaces, continuous functions on a compact metric space, continuity of inverse functions, uniform continuity.

Chapter 6 Section 6.3 to 6.8

UNIT III

Calculus:Sets of measure zero, definition of the Riemann integral, existence of the Riemann integral- properties of Riemann integral.

Chapter 7 Section 7.1 to 7.4

UNIT IV

Derivatives- Rolle's theorem, Law of mean, Fundamental theorems of calculus.

Chapter 7 Section 7.5 to 7.8

UNIT V

Taylor's theorem- Pointwise convergence of sequences of functions, uniform convergence of sequences of functions.

Chapter 8 Section 8.5 Chapter 9 Section 9.1 and 9.2

Content and Treatment as in

“Methods of Real Analysis” - Richard R. Goldberg (Oxford and IBH Publishing Co)

Reference: -

1. Principles of Mathematical Analysis by Walter Rudin, TataMcGrawHill.
2. Mathematical Analysis Tom M Apostol, Narosa Publishing House.

Unit - I Metric Spaces

Introduction

A Metric Space is a set equipped with a distance function, also called a metric, which enables us to measure the distance between two elements in the set.

1.1 Definition And Examples

Definition 1.1.1 A Metric Space is a non empty set M together with a function $d : M \times M \rightarrow \mathbf{R}$ satisfying the following conditions.

- (i) $d(x, y) \geq 0$ for all $x, y \in M$
- (ii) $d(x, y) = 0$ if and only if $x = y$
- (iii) $d(x, y) = d(y, x)$ for all $x, y \in M$
- (iv) $d(x, z) \leq d(x, y) + d(y, z)$ for all $x, y, z \in M$ [**Triangle Inequality**] d is

called a **metric** or **distance function** on M and $d(x, y)$ is called the distance between x and y in M . The metric space M with the metric d is denoted by (M, d) or simply by M when the underlying metric is clear from the context.

Example 1.1.2 Let \mathbf{R} be the set of all real numbers. Define a function $d : M \times M \rightarrow \mathbf{R}$ by $d(x, y) = |x - y|$. Then d is a metric on \mathbf{R} called the usual metric on \mathbf{R} .

Proof.

Let $x, y \in \mathbf{R}$.

Clearly $d(x, y) = |x - y| \geq 0$.

Moreover, $d(x, y) = 0 \Leftrightarrow |x - y| = 0$.

$$\Leftrightarrow x - y = 0.$$

$$\Leftrightarrow x = y$$

$$d(x, y) = |x - y|$$

$$= |y - x|$$

$$= d(y, x).$$

$$\therefore d(x, y) = d(y, x).$$

Let $x, y, z \in \mathbf{R}$. $d(x, z)$

$$= |x - z|$$

$$\begin{aligned}
&= |x - y + y - z| \\
&\leq |x - y| + |y - z| \\
&= d(x, y) + d(y, z).
\end{aligned}$$

$$\therefore d(x, z) \leq d(x, y) + d(y, z).$$

Hence d is a metric on \mathbf{R} .

Note. When \mathbf{R} is considered as a metric space without specifying its metric, it is the usual metric.

Example 1.1.2

Let M be any non-empty set. Define a function $d : M \times M \rightarrow \mathbf{R}$ by $d(x, y) = \begin{cases} 0 & \text{if } x = y \\ 1 & \text{if } x \neq y \end{cases}$

Then d is a metric on M called the **discrete metric** or **trivial metric** on M .

Proof.

Let $x, y \in M$.

Clearly $d(x, y) \geq 0$ and $d(x, y) = 0 \Leftrightarrow x = y$.

$$\begin{aligned}
\text{Also, } d(x, y) &= \begin{cases} 0 & \text{if } x = y \\ 1 & \text{if } x \neq y \end{cases} \\
&= d(y, x).
\end{aligned}$$

Let $x, y, z \in M$.

We shall prove that $d(x, z) \leq d(x, y) + d(y, z)$.

Case (i) Suppose $x = y = z$.

Then $d(x, z) = 0, d(x, y) = 0, d(y, z) = 0$.

$$\therefore d(x, z) \leq d(x, y) + d(y, z).$$

Case (ii) Suppose $x = y$ and z distinct.

Then $d(x, z) = 1, d(x, y) = 0, d(y, z) = 1 \therefore d(x, z) \leq d(x, y) + d(y, z)$.

Case (iii) Suppose $x = z$ and y distinct.

Then $d(x, z) = 0, d(x, y) = 1, d(y, z) = 1$.

$$\therefore d(x, z) \leq d(x, y) + d(y, z).$$

Case (iv) Suppose $y = z$ and x distinct.

Then $d(x, z) = 1, d(x, y) = 1, d(y, z) = 0$.

$\therefore d(x, z) \leq d(x, y) + d(y, z)$.

Case (v) Suppose $x \neq y \neq z$.

Then $d(x, z) = 1, d(x, y) = 1, d(y, z) = 1. \therefore d(x, z) \leq d(x, y) + d(y, z)$.

In all the cases, $d(x, z) \leq d(x, y) + d(y, z)$.

Hence d is a metric on M .

1.2 OPEN SETS IN A METRIC SPACE

Definition 1.2.1 Let (M, d) be a metric space. Let $a \in M$ and r be a positive real number. The open ball or the open sphere with center a and radius r is denoted by $B_d(a, r)$ and is the subset of M defined by $B_d(a, r) = \{x \in M \mid d(a, x) < r\}$. We write $B(a, r)$ for $B_d(a, r)$ if the metric d under consideration is clear.

Note. Since $d(a, a) = 0 < r, a \in B_d(a, r)$.

Examples 1.2.2

1. In \mathbf{R} with usual metric $B(a, r) = (a - r, a + r)$.
2. In \mathbf{R}^2 with usual metric $B(a, r)$ is the interior of the circle with center a and radius r .

$$\begin{cases} M & \text{if } r > 1 \\ \{a\} & \text{if } r \leq 1 \end{cases}$$
3. In a discrete metric space $M, B(a, r) =$

Definition 1.2.3 Let (M, d) be a metric space. A subset A of M is said to be open in M if for each $x \in A$ there exists a real number $r > 0$ such that $B(x, r) \subseteq A$.

Note. By the definition of open set, it is clear that \emptyset and M are open sets.

Examples 1.2.3

1. Any open interval (a, b) is an open set in \mathbf{R} with usual metric.

For,

Let $x \in (a, b)$.

Choose a real number r such that $0 < r \leq \min\{x-a, b-x\}$.

Then $B(x, r) \subseteq (a, b). \therefore (a, b)$ is open in \mathbf{R} .
2. Every subset of a discrete metric space M is open.

For,

Let A be a subset of M .

If $A = \emptyset$, then A is open.

Otherwise, let $x \in A$.

Choose a real number r such that $0 < r \leq 1$.

Then $B(x, r) = \{x\} \subseteq A$ and hence A is open.

3. Set of all rational numbers \mathbf{Q} is not open in \mathbf{R} . For,
Let $x \in \mathbf{Q}$.

For any real number $r > 0$, $B(x, r) = (x - r, x + r)$ contains both rational and irrational numbers.

$\therefore B(x, r) \not\subseteq \mathbf{Q}$ and hence \mathbf{Q} is not open.

Theorem 1.2.4 Let (M, d) be a metric space. Then each open ball in M is an open set.

Proof.

Let $B(a, r)$ be an open ball in M .

Let $x \in B(a, r)$.

Then $d(a, x) < r$.

Take $r_1 = r - d(a, x)$. Then $r_1 > 0$.

We claim that $B(x, r_1) \subseteq B(a, r)$.

Let $y \in B(x, r_1)$. Then $d(x, y) < r_1$.

Now, $d(a, y) \leq d(a, x) + d(x, y)$

$< d(a, x) + r_1$

$= d(a, x) + r - d(a, x) = r$.

$\therefore d(a, y) < r$.

$\therefore y \in B(a, r)$.

$\therefore B(x, r_1) \subseteq B(a, r)$.

Hence $B(a, r)$ is an open ball.

Theorem 1.2.5 In any metric space M , the union of open sets is open.

Proof.

Let $\{A_\alpha\}$ be a family of open sets in M .

We have to prove $A = \bigcup A_\alpha$ is open in M .

Let $x \in A$.

Then $x \in A_\alpha$ for some α .

Since A_α is open, there exists an open ball $B(x, r)$ such that $B(x, r) \subseteq A_\alpha$.

$\therefore B(x, r) \subseteq A$.

Hence A is open in M .

Theorem 1.2.6 In any metric space M , the intersection of a finite number of open sets is open.

Proof.

Let A_1, A_2, \dots, A_n be open sets in M .

We have to prove $A = A_1 \cap A_2 \cap \dots \cap A_n$ is open in M .

Let $x \in A$.

Then $x \in A_i \quad \forall i = 1, 2, \dots, n$.

Since each A_i is open, there exists an open ball $B(x, r_i)$ such that $B(x, r_i) \subseteq A_i$.

Take $r = \min \{ r_1, r_2, \dots, r_n \}$.

Clearly $r > 0$ and $B(x, r) \subseteq B(x, r_i) \quad \forall i = 1, 2, \dots, n$.

Hence $B(x, r) \subseteq A_i \quad \forall i = 1, 2, \dots, n$.

$\therefore B(x, r) \subseteq A$.

$\therefore A$ is open in M .

Theorem 1.2.7 Let (M, d) be a metric space and $A \subseteq M$. Then A is open in M if and only if A can be expressed as union of open balls.

Proof.

Suppose that A is open in M .

Then for each $x \in A$ there exists an open ball $B(x, r_x)$ such that $B(x, r_x) \subseteq A$.

$\therefore A = \bigcup_{x \in A} B(x, r_x)$.

Thus A is expressed as union of open balls.

Conversely, assume that A can be expressed as union of open balls.

Since open balls are open and union of open sets is open, A is open.

1.3 Interior of a set

Definition 1.3.1 Let (M, d) be a metric space and $A \subseteq M$. A point $x \in A$ is said to be an interior point of A if there exists a real number $r > 0$ such that $B(x, r) \subseteq A$. The set of all interior points is called as interior of A and is denoted by $\text{Int } A$.

Note 1.3.2 $\text{Int } A \subseteq A$.

Example 1.3.3 In \mathbf{R} with usual metric, let $A = [1, 2]$. 1 is not an interior point of A , since for any real number $r > 0$, $B(1, r) = (1 - r, 1 + r)$ contains real numbers less than 1. Similarly, 2 is also not an interior point of A . In fact every point of $(1, 2)$ is a limit point of A . Hence $\text{Int } A = (1, 2)$.

Note 1.3.4(1) $\text{Int } \emptyset = \emptyset$ and $\text{Int } M = M$.

(2) A is open $\Leftrightarrow \text{Int } A = A$.

(3) $A \subseteq B \Rightarrow \text{Int } A \subseteq \text{Int } B$

Theorem 1.3.5 Let (M, d) be a metric space and $A \subseteq M$. Then $\text{Int } A =$ Union of all open sets contained in A .

Proof.

Let $G = \bigcup \{ B \mid B \text{ is an open set contained in } A \}$ We have to prove $\text{Int } A = G$.

Let $x \in \text{Int } A$.

Then x is an interior point of A .

\therefore there exists a real number $r > 0$ such that $B(x, r) \subseteq A$.

Since open balls are open, $B(x, r)$ is an open set contained in A .

$\therefore B(x, r) \subseteq G$.

$\therefore x \in G$.

$\therefore \text{Int } A \subseteq G$ (1)

Let $x \in G$.

Then there exists an open set B such that $B \subseteq A$ and $x \in B$.

Since B is open and $x \in B$, there exists a real number $r > 0$ such that $B(x, r) \subseteq B \subseteq A$.

$\therefore x$ is an interior point of A .

$\therefore x \in \text{Int } A$.

$\therefore G \subseteq \text{Int } A$ (2) From (1) and (2), we get

$\text{Int } A = G$.

Note1.3.6 $\text{Int } A$ is an open set and it is the largest open set contained in A .

Theorem1.3.7 Let M be a metric space and $A, B \subseteq M$. Then

$$(1) \quad \text{Int } (A \cap B) = (\text{Int } A) \cap (\text{Int } B) \quad (2)$$

$\text{Int } (A \cup B) \supseteq (\text{Int } A) \cup (\text{Int } B)$ **Proof.**

$$(1) \quad A \cap B \subseteq A \Rightarrow \text{Int } (A \cap B) \subseteq \text{Int } A .$$

Similarly, $\text{Int } (A \cap B) \subseteq \text{Int } B .$

$$\therefore \text{Int } (A \cap B) \subseteq (\text{Int } A) \cap (\text{Int } B) \quad \dots\dots\dots (a) \quad \text{Int } A \subseteq A \text{ and } \text{Int } B \subseteq B .$$

$$\therefore (\text{Int } A) \cap (\text{Int } B) \subseteq A \cap B$$

Now, $(\text{Int } A) \cap (\text{Int } B)$ is an open set contained in $A \cap B .$

But, $\text{Int } (A \cap B)$ is the largest open set contained in $A \cap B .$

$$\therefore (\text{Int } A) \cap (\text{Int } B) \subseteq \text{Int } (A \cap B) \quad \dots\dots\dots (b)$$

From (a) and (b) , we get $\text{Int } (A \cap B) = (\text{Int } A) \cap (\text{Int } B)$

$$(2) \quad A \subseteq A \cup B \Rightarrow \text{Int } A \subseteq \text{Int } (A \cup B)$$

Similarly, $\text{Int } B \subseteq \text{Int } (A \cup B)$

$$\therefore \text{Int } (A \cup B) \supseteq (\text{Int } A) \cup (\text{Int } B)$$

Note1.3.8 $\text{Int } (A \cup B)$ need not be equal to $(\text{Int } A) \cup (\text{Int } B)$

For,

In \mathbf{R} with usual metric, let $A = (0, 1]$ and $B = (1, 2)$.

$$A \cup B = (0, 2).$$

$$\therefore \text{Int } (A \cup B) = (0, 2)$$

Now, $\text{Int } A = (0, 1)$ and $\text{Int } B = (1, 2)$ and hence $(\text{Int } A) \cup (\text{Int } B) = (0, 2) - \{ 1 \}$.

$$\therefore \text{Int } (A \cup B) \neq (\text{Int } A) \cup (\text{Int } B)$$

1.4 Subspace

Definition1.4.1 Let (M, d) be a metric space. Let M_1 be a nonempty subset of M . Then M_1 is also a metric space under the same metric d . We call (M_1, d) is a subspace of (M, d) .

Theorem1.4.2 Let M be a metric space and M_1 a subspace of M . Let $A \subseteq M_1$. Then A is open in M_1 if and only if $A = G \cap M_1$ where G is open in M .

Proof.

Let $B_1(a, r)$ be the open ball in M_1 with center a and radius r .

Then $B_1(a, r) = B(a, r) \cap M_1$ where $B(a, r)$ is the open ball in M with center a and radius r .

Let A be an open set in M_1 .

$$\begin{aligned} \text{Then } A &= \bigcup_{x \in A} B_1(x, r(x)) \\ &= \bigcup_{x \in A} [B(x, r(x)) \cap M_1] \\ &= [\bigcup_{x \in A} B(x, r(x))] \cap M_1 \\ &= G \cap M_1 \text{ where } G = \bigcup_{x \in A} B(x, r(x)) \text{ which is open in } M. \end{aligned}$$

Conversely, let $A = G \cap M_1$ where G is open in M .

We shall prove that A is open in M_1 .

Let $x \in A$.

Then $x \in G$ and $x \in M_1$.

Since G is open in M , there exists an open ball $B(x, r)$ such that $B(x, r) \subseteq G$.

$$\therefore B(x, r) \cap M_1 \subseteq G \cap M_1.$$

i.e. $B_1(x, r) \subseteq A$.

$\therefore A$ is open in M_1 .

Example 1.4.3 Consider the subspace $M_1 = [0, 1] \cup [2, 3]$ of \mathbf{R} .

$A = [0, 1]$ is open in M_1 since $A = (-\frac{1}{2}, \frac{3}{2}) \cap M_1$ where $(-\frac{1}{2}, \frac{3}{2})$ is open in \mathbf{R} .

Similarly, $B = [2, 3]$, $C = [0, \frac{1}{2}]$, $D = (\frac{1}{2}, 1]$ are open in M_1 .

Note that A, B, C, D are not open in \mathbf{R} .

1.5 Closed Sets.

Definition 1.5.1 A subset A of a metric space M is said to be closed in M if its complement is open in M .

Examples 1.5.2

1. In \mathbf{R} with usual metric any closed interval $[a, b]$ is closed. For,

$$[a, b]^c = \mathbf{R} - [a, b] = (-\infty, a) \cup (b, \infty).$$

$(-\infty, a)$ and (b, ∞) are open sets in \mathbf{R} and hence $(-\infty, a) \cup (b, \infty)$ is open in \mathbf{R} . i.e. $[a, b]^c$ is open

in \mathbf{R} .

$\therefore [a, b]$ is open in \mathbf{R} .

2. Any subset A of a discrete metric space M is closed since A^c is open as every subset of M is open.

Note. In any metric space M , \emptyset and M are closed sets since $\emptyset^c = M$ and $M^c = \emptyset$ which are open in M . Thus \emptyset and M are both open and closed in M .

Theorem 1.5.3 In any metric space M , the union of a finite number of closed sets is closed.

Proof.

Let A_1, A_2, \dots, A_n be closed sets in a metric space M .

Let $A = A_1 \cup A_2 \cup \dots \cup A_n$.

We have to prove A is open in M .

Now, $A^c = [A_1 \cup A_2 \cup \dots \cup A_n]^c$
 $= A_1^c \cap A_2^c \cap \dots \cap A_n^c$ [By De Morgan's law.] Since

A_i is closed in M , A_i^c is open in M .

Since finite intersection of open sets is open, $A_1^c \cap A_2^c \cap \dots \cap A_n^c$ is open in M . i.e. A^c is open in M .

$\therefore A$ is closed in M .

Theorem 1.5.4 In any metric space M , the intersection of closed sets is closed.

Proof.

Let $\{A_\alpha\}$ be a family of closed sets in M .

We have to prove $A = \bigcap A_\alpha$ is open in M .

Now, $A^c = (\bigcap A_\alpha)^c$
 $= \bigcup A_\alpha^c$ [By De Morgan's law.]

Since A_α is closed in M , A_α^c is open in M . Since union of open sets is open, $\bigcup A_\alpha^c$ is open.

i.e. A^c is open in M .

$\therefore A$ is closed in M .

Theorem 1.5.5 Let M_1 be a subspace of a metric space M . Let $F_1 \subseteq M_1$. Then F_1 is closed in M_1 if and only if $F_1 = F \cap M_1$ where F is a closed set in M .

Proof.

Suppose that F_1 is closed in M_1 .

Then $M_1 - F_1$ is open in M_1 .

$\therefore M_1 - F_1 = A \cap M_1$ where A is open in M .

Now, $F_1 = A^c \cap M_1$.

Since A is open in M , A^c is closed in M .

Thus, $F_1 = F \cap M_1$ where $F = A^c$ is closed in M .

Conversely, assume that $F_1 = F \cap M_1$ where F is closed in M .

Since F is closed in M , F^c is open in M .

$\therefore F^c \cap M_1$ is open in M_1 .

Now, $M_1 - F_1 = F^c \cap M_1$ which is open in M_1 .

$\therefore F_1$ is closed in M_1 .

1.6 Closure.

Definition 1.6.1 Let A be a subset of a metric space (M, d) . The closure of A , denoted by A_- , is defined as the intersection of all closed sets which contain A .

i.e. $A_- = \cap \{B \mid B \text{ is closed in } M \text{ and } B \supseteq A\}$

Note 1.6.2

- (1) Since intersection of closed sets is closed, A_- is a closed set.
- (2) $A^- \supseteq A$.
- (3) A_- is the smallest closed set containing A .
- (4) A is closed $\Leftrightarrow A = A_-$.
- (5) $\overline{A} = A_-$.

Theorem 1.6.3 Let (M, d) be a metric space. Let $A, B \subseteq M$. Then

\subseteq	\supseteq	(1)	$A \subseteq B \Rightarrow A_- \subseteq B_-$
\cup	\cap	(2)	$A_- \cup B_- = (A \cup B)_-$
\cap	\cup	(3)	$A \cap B \subseteq A_- \cap B_-$

Proof.

- (1) Let $A \subseteq B$. $B^- \supseteq B \supseteq A$.

Thus B_- is a closed set containing A .

But A_- is the smallest closed set containing A .

$$\therefore A^- \subseteq B_-.$$

$$(2) A \subseteq A \cup B.$$

$$\therefore \text{by (1), } A_- \subseteq A_- \cup B_-.$$

Similarly, $B_- \subseteq A_- \cup B_-.$

$$\therefore A^- \cup B_- \subseteq A_- \cup B_- \dots\dots\dots (a)$$

A_- is a closed set containing A and B_- is a closed set containing B .

$$\therefore A^- \cup B_- \text{ is a closed set containing } A \cup B.$$

But $A_- \cup B_-$ is the smallest closed set containing $A \cup B$.

$$\therefore A^- \cup B_- \subseteq A_- \cup B_- \dots\dots\dots (b) \text{ From (a) and (b)}$$

we get $A_- \cup B_- = A^- \cup B_-.$

$$(3) A \cap B \subseteq A.$$

$$\therefore A \cap B \subseteq A_-.$$

Similarly, $A \cap B \subseteq B_-.$

$$\therefore A \cap B \subseteq A^- \cap B_-.$$

Note 1.6.4 $A \cap B$ need not be equal to $A^- \cap B_-.$

For example, in \mathbf{R} with usual metric take $A = (0, 1)$ and $B = (1, 2).$

$$A \cap B = \emptyset \Rightarrow A \cap B \subseteq \emptyset.$$

$$\text{But } A^- \cap B_- = [0, 1] \cap [1, 2] = \{1\}.$$

$$\therefore A \cap B \subseteq A^- \cap B_-.$$

1.7 Limit Point.

Definition 1.7.1 Let (M, d) be a metric space and $A \subseteq M$. A point $x \in M$ is said to be a limit point of A if every open ball with center x contains a point of A other than x .

i.e. $B(x, r) \cap (A - \{x\}) \neq \emptyset$ for all $r > 0$.

The set of all limit points of A is denoted by A' .

Example 1.7.2 In \mathbf{R} with usual metric let $A = (0, 1)$.

Every open ball with center 0, $B(0, r) = (-r, r)$ contains points of $(0, 1)$ other than 0.

$\therefore 0$ is a limit point of A .

Similarly, 1 is a limit point of A and in fact every point of A is also a limit Point of A . For each real

number $x < 0$, if we choose r such that $0 < r \leq -x$, then $B(x, r)$

2 contains no point of $(0, 1)$, and hence x is not a limit point of A .

Similarly, every real number $x > 0$ is not a limit point of A .

Hence $A_i = [0, 1]$.

Example 1.7.3 In \mathbf{R} with usual metric, \mathbf{Z} has no limit point.

For,

Let x be any real number.

If x is an integer, then $B(x, \frac{1}{2}) = (x - \frac{1}{2}, x + \frac{1}{2})$ has no integer other than x . $\therefore x$ is not a limit point of \mathbf{Z} .

If x is not an integer, choose r such that $0 < r < |x - n|$ where n is the integer closest to x .

Then $B(x, r) = (x - r, x + r)$ contains no integer.

Hence x is not a limit point of \mathbf{Z} .

Thus no real number x is a limit point of \mathbf{Z} .

$\therefore \mathbf{Z}_i = \emptyset$.

Example 1.7.4 In \mathbf{R} with usual metric, every real number is a limit point of \mathbf{Q} .

For,

Let x be any real number.

Every open ball $B(x, r) = (x - r, x + r)$ contains infinite number of rational numbers.

$\therefore x$ is a limit point of \mathbf{Q} .

$\therefore \mathbf{Q} = \mathbf{R}$.

Theorem 1.7.5 Let (M, d) be a metric space and $A \subseteq M$. Then x is a limit point of A if and only if every open ball with center x contains infinite number of points of A .

Proof.

Let x be a limit point of A .

We have to prove every open ball with center x contains infinite number of points of A .

Suppose not.

Then there exists an open ball $B(x, r)$ contains only a finite number of points of A and hence of $(A - \{x\})$.

Let $B(x, r) \cap (A - \{x\}) = \{x_1, x_2, \dots, x_n\}$.

Let $r_1 = \min \{ d(x, x_i) / i = 1, 2, \dots, n \}$.

Since $x \neq x_i, d(x, x_i) > 0 \forall i = 1, 2, \dots, n$ and hence $r_1 > 0$.

Moreover, $B(x, r_1) \cap (A - \{x\}) = \emptyset \therefore x$ is not a limit point of A .

This is a contradiction.

\therefore every open ball with center x contains infinite number of points of A .

Conversely, assume that every open ball with center x contains infinite number of points of A .

Then, every open ball with center x contains infinite number of points of $A - \{x\}$.

Hence x is a limit point of A .

Note 1.7.6 Any finite subset of a metric space has no limit points.

Theorem 1.7.7 Let M be a metric space and $A \subseteq M$. Then $A = A \cup A'$.

Proof.

Let $x \in A \cup A'$.

We claim that $x \in \overline{A}$.

Suppose $x \notin \overline{A}$.

Then, $x \in M - \overline{A}$.

Since \overline{A} is closed, $M - \overline{A}$ is open.

\therefore there exists an open ball $B(x, r)$ such that $B(x, r) \subseteq M - \overline{A}$.

$\therefore B(x, r) \cap \overline{A} = \emptyset$.

$\therefore B(x, r) \cap A = \emptyset$. [$\because A \subseteq \overline{A}$].

$\therefore x \notin A \cup A'$, which is a contradiction.

$\therefore x \in \overline{A}$.

$\therefore A \cup A' \subseteq \overline{A}$ (1)

Let $x \in \overline{A}$.

We have to prove $x \in A \cup A'$.

If $x \in A$, then $x \in A \cup A'$.

Suppose $x \notin A$.

We claim that $x \in A'$.

Suppose $x \notin A'$.

Then there exists an open ball $B(x, r)$ such that $B(x, r) \cap (A - \{x\}) = \emptyset$.

$\therefore B(x, r) \cap A = \emptyset$. [$\because x \notin A$]. $\therefore A \subseteq B(x, r)^c$.

Since $B(x, r)$ is open, $B(x, r)^c$ is closed.

Thus $B(x, r)^c$ is a closed set containing A .

But, \bar{A} is the smallest closed set containing A .

Hence $\bar{A} \subseteq B(x, r)^c$.

Now, $x \notin B(x, r)^c$.

$\therefore x \notin \bar{A}$, which is a contradiction.

$\therefore x \in A'$ and hence $x \in A \cup A'$.

$$\bar{A} \subseteq A \cup A' \quad \dots\dots\dots (2)$$

From (1) and (2), we get $A = \bar{A} \cup A'$.

Corollary 1.7.8 A is closed if and only if A contains all its limit points.

Proof.

$$A \text{ is closed} \Leftrightarrow A = \bar{A}$$

$$\Leftrightarrow A = A \cup A'$$

$$\Leftrightarrow A \subseteq A$$

Corollary 1.7.9 $x \in \bar{A} \Leftrightarrow B(x, r) \cap A \neq \emptyset \forall r > 0$.

Proof.

$$x \in \bar{A} \Rightarrow x \in A \cup A'$$

$\therefore x \in A$ or $x \in A'$.

If $x \in A$, then $x \in B(x, r) \cap A$.

If $x \in A$, then $B(x, r) \cap (A - \{x\}) \neq \emptyset \forall r > 0$.

Thus $B(x, r) \cap A \neq \emptyset \forall r > 0$.

Conversely, let $B(x, r) \cap A \neq \emptyset \forall r > 0$.

We have to prove $x \in \overline{A}$.

If $x \in A$, then $x \in \overline{A}$.

If $x \notin A$, then $A = A - \{x\}$.

$\therefore B(x, r) \cap (A - \{x\}) \neq \emptyset \forall r > 0$.

$\therefore x$ is a limit point of A .

$\therefore x \in A'$.

$\therefore x \in \overline{A}$.

Corollary 1.7.10 $x \in \overline{A} \Leftrightarrow \overline{G} \cap A \neq \emptyset$ for all open set G containing x .

Proof.

Let $x \in \overline{A}$.

We have to prove $G \cap A \neq \emptyset$ for all open set G containing x .

Let G be an open set containing x .

Then there exists an open ball $B(x, r)$ such that $B(x, r) \subseteq G$.

Since $x \in \overline{A}$, $B(x, r) \cap A \neq \emptyset$ and hence $G \cap A \neq \emptyset$.

Conversely, assume that $G \cap A \neq \emptyset$ for every open set containing x .

Then $B(x, r) \cap A \neq \emptyset \forall r > 0$.

$\therefore x \in \overline{A}$.

1.8 Bounded Sets in a Metric space.

Definition 1.8.1 Let (M, d) be a metric space. A subset A of M is said to be bounded if there exists a positive real number k such that $d(x, y) \leq k \forall x, y \in A$.

Example 1.8.2 Any finite subset A of a metric space (M, d) is bounded.

For,

Let A be any finite subset of M .

If $A = \emptyset$ then A is obviously bounded.

Let $A \neq \emptyset$. Then $\{d(x, y)/x, y \in A\}$ is a finite set of real numbers.

Let $k = \max \{d(x, y)/x, y \in A\}$.

Clearly $d(x, y) \leq k$ for all $x, y \in A$.

$\therefore A$ is bounded.

Example 1.8.3 $[0,1]$ is a bounded subset of \mathbf{R} with usual metric since $d(x, y) \leq 1$ for all $x, y \in [0,1]$.

Example 1.8.4 $(0, \infty)$ is an unbounded subset of \mathbf{R} .

Example 1.8.5 Any subset A of a discrete metric space M is bounded since $d(x, y) \leq 1$ for all $x, y \in A$.

Note 1.8.6 Every open ball $B(x, r)$ in a metric space (M, d) is bounded.

For,

Let $s, t \in B(x, r)$.

$d(s, t) \leq d(s, x) + d(x, t) < r + r$.

$\therefore d(s, t) < 2r$.

Hence $B(x, r)$ is bounded.

Definition 1.8.7 Let (M, d) be a metric space and $A \subseteq M$. The diameter of A , denoted by $d(A)$, is defined by $d(A) = \text{l.u.b } \{d(x, y)/x, y \in A\}$.

Example 1.8.8 In \mathbf{R} with usual metric the diameter of any interval is equal to the length of the interval. The diameter of $[0, 1]$ is 1.

1.9 Complete Metric Spaces.

Definition 1.9.1 Let (M, d) be a metric space. Let (x_n) be a sequence in M . Let $x \in M$. We say that (x_n) converges to x if for every $\varepsilon > 0$ there exists a positive integer N such that $d(x_n, x) < \varepsilon$ for all $n \geq N$. If (x_n) converges to x , then x is called a limit of (x_n) and we write $\lim_{n \rightarrow \infty} x_n = x$ or $x_n \rightarrow x$.

Note 1.9.2 (1) $x_n \rightarrow x$ if and only if for every $\varepsilon > 0$ there exists a positive integer N such that $x_n \in B(x, \varepsilon) \forall n \geq N$. Thus, the open ball $B(x, r)$ contains all but a finite number of terms of the sequence.

(2) $x_n \rightarrow x$ if and only if $(d(x_n, x)) \rightarrow 0$.

Theorem 1.9.3 The limit of a convergent sequence in a metric space is unique.

Proof.

Let (M, d) be a metric space and let (x_n) be a sequence in M .

Suppose that (x_n) has two limits say x and y .

Let $\varepsilon > 0$ be given.

Since $x_n \rightarrow x$, there exists a positive integer N_1 such that $d(x_n, x) < \varepsilon/2$ for all $n \geq N_1$.

Since $x_n \rightarrow y$, there exists a positive integer N_2 such that $d(x_n, y) < \varepsilon/2$ for all $n \geq N_2$.

Let $N = \max \{ N_1, N_2 \}$.

Then, $d(x, y) \leq d(x, x_N) + d(x_N, y)$

$$< \varepsilon/2 + \varepsilon/2 \therefore d(x,$$

$y) < \varepsilon.$

Since $\varepsilon > 0$ is arbitrary, $d(x, y) = 0$.

$\therefore x = y.$

Theorem 1.9.4 Let (M, d) be a metric space and $A \subseteq B$. Then

- (i) x is a limit point of $A \Leftrightarrow$ there exists a sequence (x_n) of distinct points in A such that $x_n \rightarrow x$.
- (ii) $x \in \overline{A} \Leftrightarrow$ there exists a sequence (x_n) in A such that $x_n \rightarrow x$.

Proof.

- (i) Let x be a limit point of A .

Then every open ball $B(x, r)$ contains infinite number of points of A .

Thus, for each natural number n , we can choose $x_n \in B(x, \frac{1}{n})$ such that

$$x_n \neq x_1, x_2, x_3, \dots, x_{n-1}.$$

Now, (x_n) is a sequence of distinct points in A and $d(x_n, x) < \frac{1}{n} \forall n$.

$$\therefore (d(x_n, x)) \rightarrow 0. \therefore x_n \rightarrow x.$$

Conversely, assume that there exists a sequence (x_n) of distinct points in A such that $x_n \rightarrow x$.

We have to prove x is a limit point of A .

Let it be given an open ball $B(x, \varepsilon)$.

Since $x_n \rightarrow x$, there exists a positive integer N such that $d(x_n, x) < \varepsilon \forall n \geq N$.

$$\therefore x_n \in B(x, \varepsilon) \forall n \geq N.$$

Since x_n are distinct points of A , $B(x, \varepsilon)$ contains infinite number of points of A .

Thus, every open ball with center x contains infinite number of points of A .

Hence x is a limit point of A .

(ii) Let $x \in \overline{A}$.

Then $x \in A \cup A'$.

If $x \in A$ then the constant sequence x, x, x, \dots is a sequence in A converges to x .

If $x \notin A$, then $x \in A'$.

$\therefore x$ is a limit point of A .

\therefore by (i), there exists a sequence (x_n) in A converges to x .

Conversely, assume that there exists a sequence (x_n) in A such that $x_n \rightarrow x$.

Then every open ball $B(x, \varepsilon)$ contains points in the sequence and hence points of A .

$\therefore x \in A$.

Definition 1.9.5 Let (M, d) be a metric space. Let (x_n) be a sequence in M . Then (x_n) is said to be a Cauchy sequence in M if for every $\varepsilon > 0$ there exists a positive integer N such that $d(x_n, x_m) < \varepsilon$ for all $n, m \geq N$.

Theorem 1.9.6 Every convergent sequence in a metric space (M, d) is a Cauchy sequence.

Proof. Let (x_n) be a convergent sequence in M converges to $x \in M$.

We have to prove (x_n) is Cauchy.

Let $\varepsilon > 0$ be given.

Since $x_n \rightarrow x$, there exists a positive integer N such that $d(x_n, x) < \varepsilon/2$ for all $n \geq N$.

$\therefore d(x_n, x_m) \leq d(x_n, x) + d(x, x_m) < \varepsilon/2 +$

$\varepsilon/2$ for all $n, m \geq N$.

$\therefore d(x_n, x_m) < \varepsilon$ for all $n, m \geq N$.

Hence (x_n) is a Cauchy sequence.

Definition 1.9.7 A metric space M is said to be complete if every Cauchy sequence in M converges to a point in M .

Example 1.9.8 \mathbf{R} with usual metric is complete.

Theorem 1.9.9 A subset A of a complete metric space M is complete if and only if A is closed.

Proof.

Suppose that A is complete.

We have to prove A is closed.

For that it is enough to prove A contains all its limit points.

Let x be a limit point of A.

Then there exists a sequence (x_n) in A such that $x_n \rightarrow x$.

Since A is complete $x \in A$.

\therefore A contains all its limit points.

Hence A is closed.

Conversely, assume that A is a closed subset of M.

Let (x_n) be a Cauchy sequence in A.

Then (x_n) be a Cauchy sequence in M.

Since M is complete, there exists $x \in M$ such that $x_n \rightarrow x$.

Thus (x_n) is a sequence in A such that $x_n \rightarrow x$.

$\therefore x \in \bar{A}$.

Since A is closed $A = \bar{A}$ hence $x \in A$.

Thus every Cauchy sequence (x_n) in A converges to a point in A.

\therefore A is complete.

Note 1.9.10 Every closed interval $[a, b]$ with usual metric is complete since it is a closed subset of the complete metric space \mathbf{R} .

Theorem 1.9.11 [Cantor’s Intersection Theorem]

Let M be a metric space. Then M is complete if and only if for every sequence (F_n) of nonempty closed subsets of M such that $F_1 \supseteq F_2 \supseteq \dots \supseteq F_n \supseteq \dots$ and $(d(F_n)) \rightarrow 0$, $\bigcap_{n=1}^{\infty} F_n \neq \emptyset$.

Proof.

Let M be a complete metric space.

Let (F_n) be a sequence of nonempty closed subsets of M such that

$$F_1 \supseteq F_2 \supseteq \dots \supseteq F_n \supseteq \dots \quad \dots \dots \dots (1)$$

$$\text{and } (d(F_n)) \rightarrow 0, \quad \dots \dots \dots (2)$$

We have to prove $\bigcap_{n=1}^{\infty} F_n \neq \emptyset$.

For each natural number n , we choose a point x_n in F_n .

By (1), $x_n, x_{n+1}, x_{n+2}, \dots$ all lie in F_n .

i.e. $x_m \in F_n \forall m \geq n$ (3) We claim that (x_n) is a

Cauchy sequence in M .

Let $\varepsilon > 0$ be given.

Since $(d(F_n)) \rightarrow 0$, there exists a positive integer N such that $d(F_n) < \varepsilon \forall n \geq$

N .

In particular, $d(F_N) < \varepsilon$ (4) Now, let $m, n \geq N$.

Then by (3), $x_m, x_n \in F_N$.

$\therefore d(x_m, x_n) < \varepsilon$. [By (4)]

Thus $d(x_m, x_n) < \varepsilon \forall m, n \geq N$.

$\therefore (x_n)$ is a Cauchy sequence in M .

Since M is complete, there exists $x \in M$ such that $x_n \rightarrow x$.

We show that $x \in \bigcap_{n=1}^{\infty} F_n$.

For any natural number n , x_n, x_{n+1}, x_{n+2} is a sequence in F_n converges to x .

$\therefore x \in \overline{F_n}$.

Since F_n is closed, $F_n = \overline{F_n}$.

$\therefore x \in F_n$.

$\therefore x \in \bigcap_{n=1}^{\infty} F_n$.

Hence $\bigcap_{n=1}^{\infty} F_n \neq \emptyset$.

Conversely, assume that for every sequence (F_n) of nonempty closed subsets of M such that $F_1 \supseteq F_2 \supseteq \dots \supseteq F_n \supseteq \dots$ and $(d(F_n)) \rightarrow 0$, $\bigcap_{n=1}^{\infty} F_n \neq \emptyset$.

We have to prove M is complete.

Let (x_n) be a Cauchy sequence in M .

We claim that $x_n \rightarrow x$ for some $x \in M$.

Define a decreasing sequence of sets $F_1 \supseteq F_2 \supseteq \dots \supseteq F_n \dots$ as follows

$$F_1 = \{x_1, x_2, \dots, x_n, \dots\}.$$

$$F_2 = \{x_2, x_3, \dots, x_n, \dots\}.$$

.....

.....

$$F_n = \{x_n, x_{n+1}, \dots, \dots\}$$

.....

$$\therefore \overline{F_1} \supseteq \overline{F_2} \supseteq \dots \supseteq \overline{F_n} \dots$$

Thus $(\overline{F_n})$ is a decreasing sequence of closed sets.

Since (x_n) is a Cauchy sequence, for given $\varepsilon > 0$ there exists a positive integer N such that $d(x_n, x_m) < \varepsilon \forall n, m \geq N$. $\therefore d(F_N) < \varepsilon$.

Now, $F_n \subseteq F_N \forall n \geq N \Rightarrow d(F_n) < \varepsilon \forall n \geq N$.

But $d(F_n) = d(\overline{F_n})$.

$$\therefore d(\overline{F_n}) < \varepsilon \forall n \geq N \dots \dots \dots (5)$$

$$\therefore (d(\overline{F_n})) \rightarrow 0.$$

Hence by hypothesis, $\bigcap_{n=1}^{\infty} \overline{F_n} \neq \emptyset$.

Let $x \in \bigcap_{n=1}^{\infty} \overline{F_n}$.

Then $x, x_n \in \overline{F_n}$. $\therefore d(x_n,$

$$x) \leq d(\overline{F_n}).$$

$$\therefore d(x_n, x) < \varepsilon \forall n \geq N \text{ [By (5)] } \therefore \rightarrow x_n$$

x .

$\therefore M$ is complete.

Note 1.9.12 In the above theorem $\bigcap_{n=1}^{\infty} F_n$ contains exactly one point, since if it contains distinct points x and y , then $d(F_n) \geq d(x, y)$ for all n and hence $(d(F_n))$ does not converge to 0.

1.10 Baire's Category Theorem.

Definition 1.10.1 A subset A of a metric space M is said to be nowhere dense in M if

$$\text{Int } \overline{A} = \emptyset.$$

Definition 1.10.2 A subset A of a metric space M is said to be of first category in M if A can be expressed as a countable union of nowhere dense sets.

If A is not of first category, then we say it is of second category.

Example 1.10.3 In \mathbf{R} with usual metric, every finite subset A is nowhere dense.

Example 1.10.4 In \mathbf{R} with usual metric, the subset \mathbf{Q} is of first category.

For,

Since \mathbf{Q} is countable it can be expressed as countable union of singleton sets and each singleton set is nowhere dense in \mathbf{R} . Thus, \mathbf{Q} is countable union of nowhere dense sets. Hence \mathbf{Q} is of first category.

Example 1.10.5 If M is a discrete metric space, then any nonempty subset A of M is not nowhere dense set. Also A is of second category.

Theorem 1.10.6 Let M be a metric space and $A \subseteq M$. Then A is nowhere dense if and only if each nonempty open set contains an open ball disjoint from A .

Proof.

Suppose that A is nowhere dense.

Let G be a nonempty open set.

Since A is nowhere dense, $\text{Int } \overline{A} = \emptyset$.

$\therefore \overline{A}$ does not contain G .

\therefore there exists $x \in G$ such that $x \notin \overline{A}$.

$x \notin \overline{A} \Rightarrow$ there exists an open ball $B(x, r_1)$ such that $B(x, r_1) \cap A = \emptyset$.

G is open \Rightarrow there exists an open ball $B(x, r_2)$ such that $B(x, r_2) \subseteq G$.

Let $r = \min \{ r_1, r_2 \}$.

Then G contains $B(x, r)$ and disjoint from A .

Conversely, assume every nonempty open set contains an open ball disjoint from A .

We claim that $\text{Int } A = \overline{\emptyset}$.

Let $x \in \overline{A}$.

We claim that x is not an interior point of \overline{A} .

Suppose x is an interior point.

Then there exists an open ball $B(x, r)$ such that $B(x, r) \subseteq \overline{A}$.

Now, every open ball in $B(x, r)$ intersects with A , which is a contradiction.

Hence x is not an interior point of \overline{A} .

$\therefore \text{Int } \overline{A} = \emptyset$.

$\therefore A$ is nowhere dense set.

Theorem 1.10.7 [Baire's Category Theorem] Any

complete metric space is of second category.

Proof.

Let M be a complete metric space.

We claim that M is not of first category.

Let (A_n) be a countable collection of nowhere dense sets in M .

We shall prove that $\bigcup_{n=1}^{\infty} A_n \neq M$.

Since M is open and A_1 is nowhere dense, there exists an open ball B_1 of radius less than 1 such that $B_1 \cap A_1 = \emptyset$.

Let F_1 be the concentric closed ball whose radius is $\frac{1}{2}$ times that of B_1 .

Now, $\text{Int } F_1$ is open and A_2 is nowhere dense.

$\therefore \text{Int } F_1$ contains an open ball B_2 of radius less than $\frac{1}{2}$ such that $B_2 \cap A_2 = \emptyset$.

Let F_2 be the concentric closed ball whose radius is $\frac{1}{2}$ times that of B_2 .

Now, $\text{Int } F_2$ is open and A_3 is nowhere dense.

$\therefore \text{Int } F_2$ contains an open ball B_3 of radius less than $\frac{1}{4}$ such that $B_3 \cap A_3 = \emptyset$.

Let F_3 be the concentric closed ball whose radius is $\frac{1}{2}$ times that of B_3 .

Proceeding like this we get a sequence of nonempty closed balls F_n such that

$$F_1 \supseteq F_2 \supseteq \dots \supseteq F_n \supseteq \dots \text{ and } d(F_n) < \frac{1}{2^n}. \quad -$$

$$\therefore (d(F_n)) \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Since M is complete, By Cantor's intersection theorem, there exists a point $x \in M$

$$\text{Such that } x \in \bigcap_{n=1}^{\infty} F_n.$$

$$\text{Moreover, } F_n \cap A_n = \emptyset \forall n.$$

$$\therefore x \notin A_n \forall n.$$

$$\therefore x \notin \bigcup_{n=1}^{\infty} A_n.$$

$$\therefore \bigcup_{n=1}^{\infty} A_n \neq M.$$

Hence M is of second category.

Corollary 1.10.8 \mathbf{R} is of second category.

Proof.

\mathbf{R} is a complete metric space. Hence, \mathbf{R} is of second category.

Unit II CONTINUITY

2.1 Continuity of functions.

Definition 2.1.1 Let (M_1, d_1) and (M_2, d_2) be two metric spaces. Let $a \in M_1$. A function $f : M_1 \rightarrow M_2$ is said to be **continuous at a** if for each $\varepsilon > 0$, there exists $\delta > 0$ such that $0 < d_1(x, a) < \delta \Rightarrow d_2(f(x), f(a)) < \varepsilon$. The function f is said to be continuous if it is continuous at every point of M_1 .

Note 2.1.2 $d_1(x, a) < \delta \Rightarrow d_2(f(x), f(a)) < \varepsilon \Leftrightarrow x \in B(a, \delta) \Rightarrow f(x) \in B(f(a), \varepsilon)$

$$\Leftrightarrow f(B(a, \delta)) \subseteq B(f(a), \varepsilon).$$

Theorem 2.1.3 Let (M_1, d_1) and (M_2, d_2) be two metric spaces. A function $f : M_1 \rightarrow M_2$ is continuous if and only if $f^{-1}(V)$ is open in M_1 whenever V is open in M_2 .

Proof. Assume that f is continuous.

Let V be open in M_2 .

We have to prove $f^{-1}(V)$ is open in M_1 .

If $f^{-1}(V) = \phi$, then it is open.

Let $f^{-1}(V) \neq \phi$.

We shall prove that for each $x \in f^{-1}(V)$ there exists an open ball $B(x, \delta)$ such that $B(x, \delta)$

$\subseteq f^{-1}(V)$.

Let $x \in f^{-1}(V)$. Then $f(x) \in V$.

Since V is open, there exists an open ball $B(f(x), \varepsilon)$ such that

$B(f(x), \varepsilon) \subseteq V$(1)

Now, since f is continuous, there exists an open ball $B(x, \delta)$ such that $f(B(x, \delta)) \subseteq$

$B(f(x), \varepsilon)$.

By (1), $f(B(x, \delta)) \subseteq V$ and hence $B(x, \delta) \subseteq f^{-1}(V)$.

$\therefore f^{-1}(V)$ is open.

Conversely, assume that $f^{-1}(V)$ is open in M_1 whenever V is open in M_2 .

To prove f is continuous, we shall prove that f is continuous at every point of M_1 .

Let $x \in M_1$ and let $\varepsilon > 0$ be given.

We know that, $B(f(x), \varepsilon)$ is an open set in M_2 .

By hypothesis, $f^{-1}(B(f(x), \varepsilon))$ is open in M_1 .

Also, $x \in f^{-1}(B(f(x), \varepsilon))$.

\therefore there exists $\delta > 0$ such that $B(x, \delta) \subseteq f^{-1}(B(f(x), \varepsilon))$.

$\therefore f(B(x, \delta)) \subseteq B(f(x), \varepsilon)$.

$\therefore f$ is continuous at x .

Since $x \in M_1$ is arbitrary, f is continuous on M_1 .

Note 2.1.4 f is continuous if and only if inverse image of every open set is open.

Theorem 2.1.5 Let (M_1, d_1) and (M_2, d_2) be two metric spaces. A function $f : M_1 \rightarrow M_2$ is continuous if and only if $f^{-1}(W)$ is closed in M_1 whenever W is closed in M_2 .

Proof. Assume that f is continuous.

Let W be a closed set in M_2 .

Then W^c is an open set in M_2 .

By hypothesis, $f^{-1}(W^c)$ is open in M_1 .

But $f^{-1}(W^c) = [f^{-1}(W)]^c$.

$\therefore [f^{-1}(W)]^c$ is open in M_1 . $\therefore f^{-1}(W)$ is closed in

M_1 .

Conversely, assume that $f^{-1}(W)$ is closed in M_1 whenever W is closed in M_2 .

To prove f is continuous, we shall prove that $f^{-1}(V)$ is open in M_1 whenever V is open in M_2 .

Let V be an open set in M_2 .

C

$\therefore V$ is a closed set in M_2 .

By hypothesis, $f^{-1}(V^c)$ is a closed set in M_1 .

(i.e) $\left[f^{-1}(V) \right]^c$ is a closed set in M_1 .

$\therefore f^{-1}(V)$ is an open set in M_1 .

Thus, inverse image of every open set is open under f . $\therefore f$ is continuous.

Note 2.1.6 f is continuous if and only if inverse image of every closed set is closed.

Theorem 2.1.7 Let (M_1, d_1) and (M_2, d_2) be two metric spaces. Then $f : M_1 \rightarrow M_2$ is continuous if and only if $f(A^-) \subseteq f_-(A_-)$ for all $A \subseteq M_1$.

Proof. Assume that f is continuous.

We have to prove $f(A^-) \subseteq f_-(A_-)$ for all $A \subseteq M_1$.

Let $A \subseteq M_1$. Then $f(A) \subseteq M_2$.

$f_-(A_-)$ is a closed set in M_2 .

Since f is continuous, $f^{-1}(f_-(A_-))$ is closed in M_1 .

Since $f_-(A_-) \supseteq f(A)$, $f^{-1}(f_-(A_-)) \supseteq A$.

But A_- is the smallest closed set containing A .

$\therefore A_- \subseteq f^{-1}(f_-(A_-))$.

$\therefore f(A_-) \subseteq f_-(A_-)$.

Conversely, let $f(A^-) \subseteq f_-(A_-)$ for all $A \subseteq M_1$.

To prove f is continuous, we shall prove that $f^{-1}(W)$ is closed in M_1 whenever W is closed in M_2 .

Let W be a closed set in M_2 .

By hypothesis, $f(f^{-1}(W)) \subseteq \overline{ff^{-1}(W)}$.

$$\subseteq W_-$$

= W (Since W is closed.).

Thus, $f^{-1}(W)$
 $\subseteq \overline{f^{-1}(W)} \subseteq f^{-1}(W)$.

Also, $f^{-1}(W) \subseteq \overline{f^{-1}(W)}$
 $f^{-1}(W) \subseteq f^{-1}(W) \subseteq \overline{f^{-1}(W)}$.

Hence $f^{-1}(W)$ is closed.

$\therefore f$ is continuous.

Theorem 2.1.8 Let (M_1, d_1) and (M_2, d_2) be two metric spaces. Let $x \in M_1$. A function $f : M_1 \rightarrow M_2$ is continuous at x if and only if $x_n \rightarrow x$ in $M_1 \Rightarrow f(x_n) \rightarrow f(x)$ in M_2 .

Proof.

Suppose that f is continuous at x .

Let (x_n) be a sequence in M_1 such that $x_n \rightarrow x$.

We shall prove that $f(x_n) \rightarrow f(x)$.

Let $\epsilon > 0$ be given.

Since f is continuous at x , there exists $\delta > 0$ such that $d_1(y, x) < \delta \Rightarrow d_2(f(y), f(x)) < \epsilon$ (1).

Since $x_n \rightarrow x$, there exists positive integer N such that $d_1(x_n, x) < \delta \forall n \geq N$.

$\therefore d_2(f(x_n), f(x)) < \epsilon \forall n \geq N$. [By (1)]

$\therefore f(x_n) \rightarrow f(x)$.

Conversely, assume that $x_n \rightarrow x \Rightarrow f(x_n) \rightarrow f(x)$.

We have to prove f is continuous at x .

Suppose not. Then there exists $\epsilon > 0$ such that for all $\delta > 0$ $f(B(x, \delta)) \not\subseteq B(f(x), \epsilon)$.

Thus for each natural number n , $f(B(x, \frac{1}{n})) \not\subseteq B(f(x), \epsilon)$.

Choose x_n such that $x_n \in B(x, \delta)$ but $f(x_n) \notin B(f(x), \epsilon)$. $\therefore d_1(x_n, x) < \delta$ for all n and $d_2(f(x_n), f(x)) \geq \epsilon$ for all n .

$\therefore x_n \rightarrow x$ and $f(x_n)$ does not converge to $f(x)$.

This is a contradiction.

$\therefore f$ is continuous at x .

Problem 2.1.9 Let (M_1, d_1) and (M_2, d_2) be two metric spaces. Then prove that any constant function $f : M_1 \rightarrow M_2$ is continuous.

Solution.

Let $f : M_1 \rightarrow M_2$ be given by $f(x) = c$ where $c \in M_2$ is a constant.

We have to show that f is continuous.

Let V be an open set in M_2 .

$$\text{Now, } f^{-1}(V) = \begin{cases} \emptyset & \text{if } c \notin V \\ M_1 & \text{if } c \in V \end{cases}$$

In both cases, $f^{-1}(V)$ is an open set.

Thus, inverse image of every open set is open under f .

$\therefore f$ is continuous.

Problem 2.1.10 Let M_1, M_2, M_3 be metric spaces. If $f : M_1 \rightarrow M_2$ and $g : M_2 \rightarrow M_3$ are continuous, then prove that $g \circ f : M_1 \rightarrow M_3$ is also continuous.

i.e. composition of two continuous functions is continuous.

Solution.

Let W be an open set in M_3 .

Since g is continuous, $g^{-1}(W)$ is open in M_2 .

Since f is continuous, $f^{-1}(g^{-1}(W))$ is open in M_1 .

$$\text{Now, } f^{-1}(g^{-1}(W)) = (g \circ f)^{-1}(W).$$

$\therefore (g \circ f)^{-1}(W)$ is open in M_1 .

Hence $g \circ f$ is continuous.

Problem 2.1.11 Let f be a continuous real valued function defined on a metric space M . Let $A = \{x \in M \mid f(x) \geq a \text{ where } a \in \mathbf{R}\}$. Prove that A is closed.

Solution.

$$\begin{aligned} A &= \{x \in M \mid f(x) \geq a \text{ where } a \in \mathbf{R}\} \\ &= \{x \in M \mid f(x) \in [a, \infty)\} \\ &= f^{-1}([a, \infty)). \end{aligned}$$

Now, $[a, \infty)$ is a closed subset of \mathbf{R} .

Since f is continuous, $f^{-1}([a, \infty))$ is a closed subset of M .

$\therefore A$ is closed.

Problem 2.1.12 Let $f : M \rightarrow \mathbf{R}$ and $g : M \rightarrow \mathbf{R}$ be continuous functions. Prove that $f+g : M \rightarrow \mathbf{R}$ is continuous.

Solution.

Let $x \in M$.

We show that $f+g$ is continuous at x .

Let x_n be a sequence in M such that $x_n \rightarrow x$.

Since f and g are continuous, $f(x_n) \rightarrow f(x)$ and $g(x_n) \rightarrow g(x)$. $\therefore f(x_n) + g(x_n) \rightarrow f(x) + g(x)$.

i.e. $(f+g)(x_n) \rightarrow (f+g)(x)$. $\therefore f+g$ is continuous at x .

Note 2.1.13 In a similar way, we can prove that $f - g$, cf if $c \in \mathbf{R}$ and f

if $g(x) \neq 0 \forall x \in M$ are continuous.

2.2 Homeomorphism.

Definition 2.2.1 Let (M_1, d_1) and (M_2, d_2) be two metric spaces.

A function $f : M_1 \rightarrow M_2$ is said to be a homeomorphism if the following holds.

- (1) f is a bijection.
- (2) f is continuous.
- (3) f^{-1} is continuous.

M_1 and M_2 are said to be homeomorphic if there exists a homeomorphism between them.

Definition 2.2.2 A function $f : M_1 \rightarrow M_2$ is said to be an open mapping if for every open set G in M_1 , $f(G)$ is open in M_2 .

i.e. image of every open set in M_1 under f is open in M_2 .

Definition 2.2.3 A function $f : M_1 \rightarrow M_2$ is said to be a closed mapping if for every closed set F in M_1 , $f(F)$ is closed in M_2 .

i.e. image of every closed set in M_1 under f is closed in M_2 .

Theorem 2.2.4 Let $f : M_1 \rightarrow M_2$ be a bijection. Then the following are equivalent.

- (1) f is a homeomorphism
- (2) f is a continuous open map
- (3) f is a continuous closed map **Proof.**

We shall prove that (1) \Leftrightarrow (2) and (1) \Leftrightarrow (3) .

Suppose that f is a homeomorphism.

Then f and f^{-1} are continuous.

We have to prove f is an open mapping.

Let G be an open set in M_1 .

Since $f^{-1} : M_2 \rightarrow M_1$ is continuous, $(f^{-1})^{-1}(G)$ is open in M_1 .

i.e. $f(G)$ is open in M_2 .

$\therefore f$ is an open map.

Conversely, assume that f is a continuous open map.

We prove that f^{-1} is continuous.

Let G be an open set in M_1 .

Since f is an open mapping, $f(G)$ is open in M_2 .

i.e. $(f^{-1})^{-1}(G)$ is open in M_2 .

$\therefore f^{-1}$ is continuous.

The proof of (1) \Leftrightarrow (3) is similar.

Note 2.2.5 Let $f : M_1 \rightarrow M_2$ be a homeomorphism. Then a subset G of M_1 is open in M_1 if and only if $f(G)$ is open in M_2 .

For,

Since f is a homeomorphism, f is a continuous open mapping.

Since f is open mapping, G is open in $M_1 \Rightarrow f(G)$ is open in M_2 .

Since f is continuous, $f(G)$ is open in $M_2 \Rightarrow f^{-1}(f(G)) = G$ is open in M_1 .

$\therefore G$ is open in $M_1 \Leftrightarrow f(G)$ is open in M_2 .

Thus a homeomorphism $f : M_1 \rightarrow M_2$ gives not only a 1 – 1 correspondence between the elements of the two spaces but also a 1 – 1 correspondence between their open sets.

Note 2.2.6 Let $f : M_1 \rightarrow M_2$ be a homeomorphism. Then a subset F of M_1 is closed in M_1 if and only if $f(F)$ is closed in M_2 .

Example 2.2.7 The metric spaces $(0, 1)$ and $(0, \infty)$ with usual metric are homeomorphic.

For, Define $f : (0, 1) \rightarrow (0, \infty)$ by $f(x) = \frac{x}{1-x}$.

1-x

We show that f is 1 – 1 and on to.

Let $x, y \in (0, 1)$.

$$\begin{aligned} f(x) = f(y) &\Rightarrow \frac{x}{1-x} = \frac{y}{1-y} \\ &\Rightarrow x(1-y) = y(1-x) \\ &\Rightarrow x - xy = y - xy \\ &\Rightarrow x = y. \end{aligned}$$

Hence f is 1 – 1.

Let $y \in (0, \infty)$.

$$\begin{aligned} \text{Now, } f(x) = y &\Rightarrow \frac{x}{1-x} = y \\ &\Rightarrow x = y(1-x) \\ &\Rightarrow x = y - xy \end{aligned}$$

$$\Rightarrow x + xy = y$$

$$\Rightarrow x(1 + y) = y$$

$$\Rightarrow x = \frac{y}{1+y}$$

$\therefore \frac{y}{1+y} \in (0, 1)$ is the pre image of y under f .

$\therefore f$ is onto. Thus f is a bijection and hence $f^{-1}: (0, 1) \rightarrow (0, \infty)$ by $f(x) = \frac{1}{1+x}$ is a

bijection.

$$1 + x$$

Also, f and f^{-1} are continuous.

$\therefore f$ is a homeomorphism.

2.3 Uniform Continuity.

Definition 2.3.1 Let (M_1, d_1) and (M_2, d_2) be a metric space. A function $f: M_1 \rightarrow M_2$ is said to be uniformly continuous on M_1 , if for every $\epsilon > 0$ there exists $\delta > 0$ such that $d_1(x, y) < \delta \Rightarrow d_2(f(x), f(y)) < \epsilon$.

Note 2.3.2 Every uniformly continuous function is continuous but the converse need not be true.

Example 2.3.3 The function $f: [0, 1] \rightarrow \mathbf{R}$ given by $f(x) = x^2$ is uniformly continuous on $[0, 1]$.

For,

Let $\epsilon > 0$ be given.

Let $x, y \in [0, 1]$.

$$\begin{aligned} \text{Now, } |f(x) - f(y)| &= |x^2 - y^2| \\ &= |x + y| |x - y| \\ &\leq 2 |x - y| \end{aligned}$$

Choose $\delta = \frac{\epsilon}{2}$.

Then, $|x - y| < \delta \Rightarrow |f(x) - f(y)| < \epsilon$. $\therefore f$ is uniformly continuous on $[0, 1]$.

2.4 Discontinuities of \mathbf{R}

Definition 2.4.1

A function $f: \mathbb{R} \rightarrow \mathbb{R}$ is said to approach to a limit ℓ as x tends to a if given $\varepsilon > 0$ there exists $\delta > 0$ such that $0 < |x-a| < \delta \implies |f(x) - \ell| < \varepsilon$ and we write $\lim_{x \rightarrow a} f(x) = \ell$.

Definition 2.4.2

A function f is that to have ℓ as the right limit at $x=a$ if given $\varepsilon > 0$ there exists $\delta > 0$ such that $a < x < a + \delta \implies |f(x) - \ell| < \varepsilon$ and we write $\lim_{x \rightarrow a^+} f(x) = \ell$

Also we denote the right limit ℓ by $f(a+)$

A function f is that to have ℓ as the left limit at $x=a$ if given $\varepsilon > 0$ there exists $\delta > 0$ such that $a - \delta < x < a \implies |f(x) - \ell| < \varepsilon$ and we write $\lim_{x \rightarrow a^-} f(x) = \ell$

Also we denote the left limit ℓ by $f(a-)$

Note 1

$$\lim_{x \rightarrow a} f(x) = \ell \text{ if and only if } \lim_{x \rightarrow a^+} f(x) = \lim_{x \rightarrow a^-} f(x) = \ell.$$

i.e.

$\lim_{x \rightarrow a} f(x) = \ell$ if and only if the left and right limits of $f(x)$ at $x = a$ exist and are equal.

Note 2

The definition of continuity of f at $x=a$ can be formulated as follows. f is continuous at a if and only if $f(a+) = f(a-) = f(a)$.

Note 3

If $\lim_{x \rightarrow a} f(x)$ does not exist then one of the following happens.

1. $\lim_{x \rightarrow a^+} f(x)$ does not exist.
2. $\lim_{x \rightarrow a^-} f(x)$ does not exist.
3. $\lim_{x \rightarrow a^+} f(x)$ and $\lim_{x \rightarrow a^-} f(x)$ exist and are not equal.

Definition 2.4.3

If a function f is discontinuous at a then a is called a point of discontinuity for the function.

If a is a point of discontinuity of a function then any one of the following cases arises.

- i. $\lim_{x \rightarrow a} f(x)$ exists but is not equal to $f(a)$.
- ii. $\lim_{x \rightarrow a^+} f(x)$ and $\lim_{x \rightarrow a^-} f(x)$ exist and are not equal.
- iii. Either $\lim_{x \rightarrow a^-} f(x)$ or $\lim_{x \rightarrow a^+} f(x)$ does not exist.

Definition 2.4.4

Let a be a point of discontinuity for $f(x)$. a is said to be a point of discontinuity of the first kind if $\lim_{x \rightarrow a^+} f(x)$ and $\lim_{x \rightarrow a^-} f(x)$ exists and both of them are finite and not equal. a is said to be a point of discontinuity of the second kind if either $\lim_{x \rightarrow a^+} f(x)$ or $\lim_{x \rightarrow a^-} f(x)$ does not exist.

Definition 2.4.5

Let $A \subseteq \mathbb{R}$. A function $f : A \rightarrow \mathbb{R}$ is called monotonic increasing if $x, y \in A$ and $x < y \implies f(x) \leq f(y)$.

f is called monotonic decreasing if $x, y \in A$ and $x > y \implies f(x) \geq f(y)$.

f is called monotonic if it is either monotonic increasing or monotonic decreasing.

Theorem 2.4.6

Let $f : [a, b] \rightarrow \mathbb{R}$ be a monotonic increasing function. Then f has a left limit and a right limit at every point of (a, b) . Also f has a right limit at a and f has a left limit at b . Further

$$x < y \implies f(x+) \leq f(y-)$$

Similar result is true for monotonic decreasing functions.

Proof

Let $f : [a, b] \rightarrow \mathbb{R}$ be monotonic increasing.

Let $x \in [a, b]$. Then $\{f(t) \mid a \leq t < x\}$ is bounded above by $f(x)$.

We claim that $f(x-) = \ell$

Let $\epsilon > 0$ be given. By definition of l.u.b there exists t such that $a \leq t < x$ and $\ell - \epsilon < f(t) \leq \ell$.

$$\therefore t < u < x \implies \ell - \epsilon < f(t) \leq f(u) \leq \ell$$

($\because f$ is monotonic increasing)

$$\implies \ell - \epsilon < f(u) \leq \ell$$

$$\therefore x - \delta < u < x \implies \ell - \epsilon < f(u) \leq \ell \text{ where } \delta = x - t$$

$$\therefore f(x-) = \ell$$

Similarly we can prove that $f(x+) = \text{g.l.b. } \{f(t) \mid x < t \leq b\}$.

Now we shall prove that $x < y \implies f(x+) \leq f(y-)$ Let $x < y$.

Now, $f(x+) = \text{g.l.b. } \{f(t) \mid x < t \leq b\}$

$$= \text{g.l.b. } \{f(t) \mid x < t \leq y\} \tag{1}$$

($\because f$ is monotonic increasing)

Also $f(y-) = \text{l.u.b. } \{f(t) \mid a \leq t < y\}$

$$= \text{l.u.b. } \{f(t) \mid x \leq t < y\} \tag{2}$$

$$\therefore f(x+) \leq f(y-) \text{ [by (1) and (2)]}$$

The proof for monotonic decreasing functions is similar.

Theorem 2.4.7

Let $f: [a, b] \rightarrow \mathbb{R}$ be a monotonic function. Then the set of points of $[a, b]$ at which f is discontinuous is countable.

Proof

We shall prove the theorem for a monotonic increasing function.

Let $E = \{x \mid x \in [a, b] \text{ and } f \text{ is discontinuous at } x\}$.

Let $x \in E$. Then $f(x+)$ and $f(x-)$ exists and $f(x-) \leq f(x) \leq f(x+)$

If $f(x-) = f(x+)$ then $f(x-) = f(x) = f(x+)$

$\therefore f$ is continuous at x , which is a contradiction.

$\therefore f(x-) \neq f(x+)$

$\therefore f(x-) < f(x+)$

Now choose a rational number $r(x)$ such that $f(x-) < r(x) < f(x+)$

This defines a map r from E to \mathbb{Q} which maps x to $r(x)$.

We claim that r is 1-1.

Let $x_1 < x_2$.

$\therefore f(x_1+) < f(x_2-)$.

Also $f(x_1-) < r(x_1) < f(x_1+)$

And $f(x_2-) < r(x_2) < f(x_2+)$

$\therefore r(x_1) < f(x_1+) < f(x_2-) < r(x_2)$ Thus

$x_1 < x_2 \implies r(x_1) < r(x_2)$. $\therefore r: E \rightarrow \mathbb{Q}$ is 1-1

$\therefore E$ is countable.

2.5 Connectedness

Definition 2.5.1 A separation of a metric space M is a pair A, B of nonempty disjoint open subsets of M whose union is M .

M is said to be a connected metric space if there is no separation for M .

Example 2.5.2 Any discrete metric space with more than one element is connected.

For,

Let M be a metric space with more than two elements.

Choose an element $a \in M$ and let $A = \{a\}$.

Then A^c is a proper subset of M .

Now, A and A^c forms a separation of M .

$\therefore M$ is not connected.

Theorem 2.5.3 Let (M, d) be a metric space. Then M is connected if and only if \emptyset and M are the only sets which are both open and closed in M .

Proof.

Suppose that M is connected.

We have to prove \emptyset and M are the only sets which are both open and closed in M .

Suppose not.

Then there exists a proper subset A of M which is both open and closed in M .

Now, A and A^c forms a separation of M , which is a contradiction.

Conversely, assume that \emptyset and M are the only sets which are both open and closed in M .

We have to prove M is connected.

Suppose not.

Then there exists a separation A, B of M .

A is a proper subset of M which is both open and closed in M , a contradiction.

$\therefore M$ is connected.

Theorem 2.5.4 Let (M, d) be a metric space. Then the following are equivalent.

- (i) The sets A and B form a separation of M .
- (ii) A and B are nonempty disjoint closed sets in M whose union is M .
- (iii) A and B are nonempty disjoint sets in M whose union is M and $A \cap B = \emptyset$.

Proof.

We shall prove that (i) \Leftrightarrow (ii) and (ii) \Leftrightarrow (iii) (i) \Rightarrow (ii).

Suppose that A and B forms a separation of M .

Then A and B are nonempty disjoint sets in M whose union is M .

We have to prove A and B are closed in M .

Now, $A = B^c$ and $B = A^c$.

Since A and B are open in M , A^c and B^c are closed in M .

i.e., A and B are closed in M .

\therefore (i) \Rightarrow (ii).

The proof of (ii) \Rightarrow (i) is similar.

(ii) \Rightarrow (iii).

Suppose that A and B are nonempty disjoint closed sets in M whose union is M .

We have to prove $A \cap B_{_} = A_{_} \cap B = \emptyset$.

Since B is closed, $B = B_{_}$.

$\therefore A \cap B_{_} = A \cap B = \emptyset$.

Similarly, $A_{_} \cap B = \emptyset$.

(iii) \Rightarrow (i).

Suppose that A and B are nonempty disjoint sets in M whose union is M and

$A \cap B_{_} = A_{_} \cap B = \emptyset$.

We have to prove A and B are closed in M .

Let $x \in A_{_}$.

Since $A_{_} \cap B = \emptyset$, $x \notin B$.

Since $A \cup B = M$, $x \in A$.

$\therefore A_{_} \subseteq A$.

But $A \subseteq A_{_}$.

$\therefore A = A_{_}$ and hence A is closed.

Similarly, B is closed.

Theorem 2.5.5 Let M be a connected metric space. Let A be a connected subset of M . If B is a subset of M such that $A \subseteq B \subseteq A_{_}$ then B is connected. In particular, $A_{_}$ is connected.

Proof.

Suppose B is not connected.

Then there exists a separation B_1, B_2 of B .

Since B_1 and B_2 are open in B , $B_1 = G_1 \cap B$ and $B_2 = G_2 \cap B$, where G_1 and G_2 are open in M .

Now, $B = B_1 \cup B_2 = (G_1 \cap B) \cup (G_2 \cap B) = (G_1 \cup G_2) \cap B$.

$\therefore B \subseteq G_1 \cup G_2$ and hence $A \subseteq G_1 \cup G_2$.

Take $A_1 = G_1 \cap A$ and $A_2 = G_2 \cap A$.

Then A_1 and A_2 are open in A .

$$\begin{aligned}
\text{Also, } A_1 \cup A_2 &= (G_1 \cap A) \cup (G_2 \cap A) \\
&= (G_1 \cup G_2) \cap A \\
&= A \text{ [Since } A \subseteq G_1 \cup G_2 \text{]} \\
A_1 \cap A_2 &= (G_1 \cap A) \cap (G_2 \cap A) \\
&= (G_1 \cap G_2) \cap A \\
&\subseteq (G_1 \cap G_2) \cap B \text{ [Since } A \subseteq B \text{]} \\
&= (G_1 \cap B) \cap (G_2 \cap B) \\
&= B_1 \cap B_2 \\
&= \emptyset.
\end{aligned}$$

Since A is connected, either $A_1 = \emptyset$ or $A_2 = \emptyset$. Without loss of generality, assume that $A_1 = \emptyset$.

$$\text{i.e. } G_1 \cap A = \emptyset.$$

Since G_1 is open, $G_1 \cap A__ = \emptyset$.

$$\therefore G_1 \cap B = \emptyset. \text{ [Since } B \subseteq A__ \text{]}$$

i.e. $B_1 = \emptyset$, which is a contradiction.

$\therefore B$ is connected.

2.6 Connected subsets of \mathbf{R} .

Theorem 2.6.1 A subspace of \mathbf{R} is connected if and only if it is an interval.

Proof.

Suppose that A is a connected subset of \mathbf{R} .

We have to prove A is an interval.

Suppose not.

Then, there exists $a, b, c \in \mathbf{R}$ such that $a < b < c$ and $a, c \in A$ but $b \notin A$.

Define $A_1 = (-\infty, b) \cap A$ and $A_2 = (b, \infty) \cap A$.

Since $(-\infty, b)$ and (b, ∞) are open in \mathbf{R} , A_1 and A_2 are open in A .

Moreover, $A_1 \cap A_2 = \emptyset$ and $A_1 \cup A_2 = A$.

Clearly $a \in A_1$ and $c \in A_2$.

$\therefore A_1 \neq \emptyset$ and $A_2 \neq \emptyset$.

Thus, A is the union of a pair of nonempty disjoint open sets A_1 and A_2 .

$\therefore A$ is not connected, which is a contradiction.

Hence A is an interval.

Conversely, assume that A is an interval.

We have to prove A is connected.

Suppose not.

Then, there exists nonempty disjoint closed sets A_1 and A_2 in A such that $A = A_1 \cup A_2$.

Choose $x \in A_1$ and $z \in A_2$. Since $A_1 \cap A_2 = \emptyset$, $x \neq z$. $\therefore x < z$ or $z < x$.

Without loss of generality we assume that $x < z$.

Now, $x, z \in A$ and A is an interval.

$\therefore [x, z] \subseteq A \subseteq A_1 \cup A_2$.

Hence every element of $[x, z]$ is either in A_1 or in A_2 .

Let $y = \text{l.u.b.} \{ [x, z] \cap A_1 \}$.

Clearly $x \leq y \leq z$.

By the definition of l.u.b., for each $\epsilon > 0$ there exists $t \in [x, z] \cap A_1$ such that $y - \epsilon < t \leq y$.

$\therefore (y - \epsilon, y + \epsilon) \cap ([x, z] \cap A_1) \neq \emptyset \quad \forall \epsilon > 0$.

$\therefore y \in \overline{[x, z] \cap A_1}$.

Since $[x, z] \cap A_1$ is closed in A , $y \in [x, z] \cap A_1$

$\therefore y \in A_1$ (1)

Again, by the definition of y , for each $\epsilon > 0$ there exists $s \in A_2$ such that $y \leq s < y + \epsilon$.

$\therefore (y - \epsilon, y + \epsilon) \cap A_2 \neq \emptyset \quad \forall \epsilon > 0$.

$\therefore y \in \overline{A_2}$.

Since A_2 is closed in A , $y \in A_2 \dots\dots\dots (2) \therefore y \in A_1 \cap A_2$ [

By (1) & (2)].

This is a contradiction to $A_1 \cap A_2 = \emptyset$.

Hence A is connected.

2.7 Connectedness and continuity.

Theorem 2.7.1 Let M_1 be a connected metric space. Let M_2 be any metric space. Let $f : M_1 \rightarrow M_2$ be a continuous function. Then $f(M_1)$ is a connected subset of M_2 .

i.e. continuous image of a connected set is connected.

Proof.

Let $f(M_1) = A$ so that f is a continuous function from M_1 on to A .

We claim that A is connected.

Suppose A is not connected.

Then, there exists a proper subset B of A which is both open and closed in A .

Hence $f^{-1}(B)$ is a proper subset of M_1 which is both open and in M_1 .

$\therefore M_1$ is not connected which is a contradiction.

Hence A is connected.

Theorem 2.7.2 [intermediate value Theorem]

Let f be a real valued continuous function defined on an interval \mathbf{I} . Then f takes every value between any two value it assumes.

Proof.

Let $a, b \in \mathbf{I}$ and let $f(a) \neq f(b)$.

Without loss of generality we assume that $f(a) < f(b)$.

Let c be a real number such that $f(a) < c < f(b)$.

The interval \mathbf{I} is a connected subset of \mathbf{R} .

Since f is continuous, $f(\mathbf{I})$ is a connected subset of \mathbf{R} .

Hence $f(\mathbf{I})$ is an interval.

Also $f(a), f(b) \in f(\mathbf{I}) \therefore [f(a), f(b)] \subseteq f(\mathbf{I}) \therefore c \in f(\mathbf{I})$. [Since $f(a) < c < f(b)$] $\therefore c = f(x)$ for some $x \in \mathbf{I}$.

Unit III Compactness

3.1 Compact Metric Spaces.

Definition 3.1.1 Let M be a metric space. A collection of open sets $\{G_\alpha\}$ is said to be an **open cover** for M if $\bigcup G_\alpha = M$. A sub collection of $\{G_\alpha\}$ which itself is an open cover is called a **subcover**.

Definition 3.1.2 A metric space M is said to be **compact** if every open cover for M has a finite subcover.

i.e. for each collection of open sets $\{G_\alpha\}$ such that $\bigcup G_\alpha = M$, there exists a finite sub collection $\{G_{\alpha_1}, G_{\alpha_2}, \dots, G_{\alpha_n}\}$ such that $\bigcup_{i=1}^n G_{\alpha_i} = M$.

Theorem 3.1.3 Let M be a metric space. Let $A \subseteq M$. Then A is compact if and only if for every collection $\{G_\alpha\}$ of open sets in M such that $\bigcup G_\alpha \supseteq A$ there exists a finite sub collection $\{G_{\alpha_1}, G_{\alpha_2}, \dots, G_{\alpha_n}\}$ such that $\bigcup_{i=1}^n G_{\alpha_i} \supseteq A$.

i.e. A is compact if and only if every open cover for A by sets open in M has a finite subcover.

Proof.

Let A be a compact subset of M .

Let $\{G_\alpha\}$ be a collection of open sets in M such that $\bigcup G_\alpha \supseteq A$.

Then $(\bigcup G_\alpha) \cap A = A$.

$\therefore \bigcup (G_\alpha \cap A) = A$.

Since G_α is open in M , $G_\alpha \cap A$ is open in A .

$\therefore \{G_\alpha \cap A\}$ is an open cover for A .

Since A is compact, this open cover has a finite subcover say

$\{G_{\alpha_1} \cap A, G_{\alpha_2} \cap A, \dots, G_{\alpha_n} \cap A\}$.

$\therefore \bigcup_{i=1}^n (G_{\alpha_i} \cap A) = A$.

$\therefore (\bigcup_{i=1}^n G_{\alpha_i}) \cap A = A$.

$\therefore \bigcup_{i=1}^n G_{\alpha_i} \supseteq A$.

Conversely, assume that for every collection $\{G_\alpha\}$ of open sets in M such that $\bigcup G_\alpha \supseteq A$ there exists a finite sub collection $\{G_{\alpha_1}, G_{\alpha_2}, \dots, G_{\alpha_n}\}$ such that $\bigcup_{i=1}^n G_{\alpha_i} \supseteq A$.

We have to prove A is compact.

Let $\{H_\alpha\}$ be an open cover for A .

Then H_α is open in $A \forall \alpha$.

$\therefore H_\alpha = G_\alpha \cap A$ where G_α is open in $M \forall \alpha$.

Now $\bigcup H_\alpha = A \Rightarrow \bigcup (G_\alpha \cap A) = A$.

$$\Rightarrow (\bigcup G_\alpha) \cap A = A.$$

$$\Rightarrow \bigcup G_\alpha \supseteq A.$$

Hence by our assumption, there exists a finite sub collection $\{G_{\alpha_1}, G_{\alpha_2}, \dots, G_{\alpha_n}\}$ such that $\bigcup_{i=1}^n G_{\alpha_i} \supseteq A$.

$$\therefore (\bigcup_{i=1}^n G_{\alpha_i}) \cap A = A.$$

$$\therefore \bigcup_{i=1}^n (G_{\alpha_i} \cap A) = A.$$

$$\bigcup_{i=1}^n H_{\alpha_i} = A.$$

Thus $\{H_{\alpha_1}, H_{\alpha_2}, \dots, H_{\alpha_n}\}$ is a finite subcover of the given open cover $\{H_\alpha\}$ of A .

$\therefore A$ is compact.

Theorem 3.1.4 Any compact subset A of a metric space (M, d) is closed.

Proof.

We shall prove that A^c is open.

Let $y \in A^c$.

Now, for each $x \in A, x \neq y$.

$$\therefore d(x, y) = r_x > 0 \text{ and } B(x, \frac{r_x}{2}) \cap B(y, \frac{r_x}{2}) = \emptyset.$$

Clearly the collection $\{B(x, \frac{r_x}{2}) \mid x \in A\}$ is an open cover for A by sets open in M .

Since A is compact, there exists $x_1, x_2, \dots, x_n \in A$ such that

$$\bigcup_{i=1}^n B(x, \frac{r_{x_i}}{2}) \supseteq A \quad \dots\dots\dots (1)$$

$$\text{Let } V_y = \bigcap_{i=1}^n B(y, \frac{r_{x_i}}{2}).$$

Then V_y is an open set containing y .

$$\text{Since } B(x, \frac{r_{x_i}}{2}) \cap B(y, \frac{r_{x_i}}{2}) = \emptyset, V_y \cap B(x, \frac{r_{x_i}}{2}) = \emptyset \quad \forall i = 1, 2, \dots, n.$$

$$\therefore V_y \cap [\bigcup_{i=1}^n B(x, \frac{r_{x_i}}{2})] = \emptyset.$$

$$\therefore V_y \cap A = \emptyset. \quad [\text{By (1)}]$$

$$\therefore V_y \subseteq A^c.$$

Thus, for each $y \in A^c$ there exists an open set V_y containing y such that $V_y \subseteq A^c$.

$$\therefore A^c = \bigcup_{y \in A^c} V_y.$$

$\therefore A^c$ is open.

Hence A is closed.

Theorem 3.1.5 Any compact subset A of a metric space M is bounded.

Proof.

Let $x \in A$.

Now, $\{ B(x, n) / n \in \mathbb{N} \}$ is an open cover for A by sets open in M .

Since A is compact, there exists natural numbers n_1, n_2, \dots, n_k , such that $\bigcup_{i=1}^k B(x, n_i) \supseteq A$.

$$\text{Let } N = \max \{ n_1, n_2, \dots, n_k \}.$$

$$\text{Then } \bigcup_{i=1}^k B(x, n_i) = B(x, N).$$

$$\therefore B(x, N) \supseteq A.$$

Since $B(x, N)$ is bounded and subset of a bounded set is bounded, A is bounded.

Theorem 3.1.6 A closed subset A of a compact metric space M is compact.

Proof.

Let $\{G_\alpha\}$ be a collection of open sets in M such that $\bigcup G_\alpha \supseteq A$.

$$\therefore A^c \cup \bigcup G_\alpha = M.$$

Since A is closed, A^c is open.

$\therefore \{G_\alpha\} \cup \{A^c\}$ is an open cover for M .

Since M is compact this open cover has a finite subcover say

$$\{G_{\alpha_1}, G_{\alpha_2}, \dots, G_{\alpha_n}, A^c\}.$$

$$\therefore (\bigcup_{i=1}^n G_{\alpha_i}) \cup A^c = M.$$

$$\therefore \bigcup_{i=1}^n G_{\alpha_i} \supseteq A.$$

Hence A is compact.

Theorem 3.1.7 [Heine Borel Theorem]

Any closed interval $[a, b]$ is a compact subset of \mathbf{R} .

Proof.

Let $\{G_\alpha\}$ be a collection of open sets in \mathbf{R} such that $\bigcup G_\alpha \supseteq \mathbf{R}$. Let $S = \{x \in [a, b] /$

$[a, x]$ can be covered by a finite number of G_α 's. }

Clearly $a \in S$ and hence $S \neq \emptyset$.

Since S is bounded above by b , l.u.b of S exists.

Let $c =$ l.u.b of S .

Clearly $c \in [a, b]$.

$\therefore c \in G_{\alpha_1}$ for some index α_1 .

Since G_{α_1} is open, there exists $\varepsilon > 0$ such that $B(x, \varepsilon) \subseteq G_{\alpha_1}$.

i.e. $(c - \varepsilon, c + \varepsilon) \subseteq G_{\alpha_1}$.

Choose $x_1 \in [a, b]$ such that $x_1 < c$ and $[x_1, c] \subseteq G_{\alpha_1}$.

Since $x_1 < c$, $[a, x_1]$ is covered by a finite number of G_α 's.

These finite number of G_α 's together with G_{α_1} covers $[a, c]$.

\therefore by the definition of S , $c \in S$.

Now, we claim that $c = b$.

Suppose $c \neq b$.

Then choose $x_2 \in [a, b]$ such that $x_2 > c$ and $[c, x_2] \subseteq G_{\alpha_1}$.

Since $[a, c]$ is covered by a finite number of G_α 's, these finite number of G_α 's together with G_{α_1} covers $[a, x_2]$.

$\therefore x_2 \in S$, which is a contradiction to c is l.u.b of S [$\because x_2 > c$].

Hence $c = b$.

$\therefore [a, x]$ can be covered by a finite number of G_α 's.

$\therefore [a, b]$ is a compact subset of \mathbf{R} .

Theorem 3.1.8 A subset A of \mathbf{R} is compact if and only if A is closed and bounded.

Proof.

If A is compact, then A is closed and bounded.

Conversely, assume that A is closed and bounded subset of \mathbf{R} .

Since A is bounded, A has a lower bound and an upper bound say a and b respectively.

Then $A \subseteq [a, b]$.

Since A is closed in \mathbf{R} , $A \cap [a, b]$ is closed in $[a, b]$. I.e. A is

closed in $[a, b]$.

Thus, A is a closed subset of the compact space $[a, b]$.

Hence A is compact.

3.2 Compactness and Continuity.

Theorem 3.2.1 Let M_1 be a compact metric space and M_2 be any metric space. Let $f : M_1 \rightarrow M_2$ be a continuous function. Then $f(M_1)$ is compact.

i.e. Continuous image of a compact metric space is compact.

Proof.

Without loss of generality we assume that $f(M_1) = M_2$.

Let $\{G_\alpha\}$ be a collection of open sets in M_2 such that $\bigcup G_\alpha = M_2$.

$\therefore \bigcup G_\alpha = f(M_1)$.

$\therefore f^{-1}(\bigcup G_\alpha) = M_1$. $\therefore \bigcup f^{-1}(G_\alpha) = M_1$.

$f^{-1}(G_\alpha) = M_1$.

Since f is continuous, $f^{-1}(G_\alpha)$ is open in $M_1 \forall \alpha$.

$\therefore \{f^{-1}(G_\alpha)\}$ is an open cover for M_1 .

Since M_1 is compact, this open cover has a finite subcover say $\{f^{-1}(G_{\alpha_1}), f^{-1}(G_{\alpha_2}), \dots, f^{-1}(G_{\alpha_n})\}$.

$\therefore f^{-1}(\bigcup_{i=1}^n G_{\alpha_i}) = M_1$.

$\bigcup_{i=1}^n G_{\alpha_i} = f(M_1) = M_2$.

Thus $\{G_{\alpha_1}, G_{\alpha_2}, \dots, G_{\alpha_n}\}$ is a finite subcover for the given open cover $\{G_\alpha\}$ of M_2 .

Hence M_2 is compact.

Corollary 3.2.2 Let f be a continuous map from a compact metric space M_1 into any metric space M_2 . Then $f(M_1)$ is closed and bounded.

Proof.

Since f is continuous, $f(M_1)$ is compact and hence closed and bounded.

Theorem 3.2.3 Any continuous mapping f defined on a compact metric space (M_1, d_1) into any other metric space (M_2, d_2) is uniformly continuous on M_1 .

Proof.

Let $\epsilon > 0$ be given.

Let $x \in M_1$.

Since f is continuous at x , for $\epsilon/2 > 0$, there exists $\delta_x > 0$ such that

$d_1(x, y) < \delta_x \Rightarrow d_2(f(x), f(y)) < \epsilon/2$ (1) Clearly, $\{B(x,$

$\frac{\delta_x}{2}) / x \in M_1\}$ is an open cover for M_1 .

Since M_1 is compact, there exists $x_1, x_2, \dots, x_n \in M_1$ such that

$\bigcup_{i=1}^n B(x_i, \frac{\delta_{x_i}}{2}) = M_1$.

Let $\delta = \min \{ \frac{\delta_{x_1}}{2}, \frac{\delta_{x_2}}{2}, \dots, \frac{\delta_{x_n}}{2} \}$.

Now, we shall prove that $d_1(p, q) < \delta \Rightarrow d_2(f(p), f(q)) < \varepsilon \forall p, q \in M_1$.

Let $p, q \in M_1$ such that $d_1(p, q) < \delta$

$$\begin{aligned}
 p \in M_1 &\Rightarrow p \in \bigcup_{i=1}^n B(x_i, \frac{\delta_{x_i}}{2}) \\
 &\Rightarrow p \in B(x_i, \frac{\delta_{x_i}}{2}) \text{ for some } i \text{ such that } 1 \leq i \leq n \\
 &\Rightarrow \delta_{x_i} < \delta_{x_i} \quad \overline{d_1(p, x_i)} < 2
 \end{aligned}$$

$$\therefore \text{by (1), } d_2(f(p), f(x_i)) < \varepsilon/2 \quad \dots\dots\dots (2)$$

$$\text{Similarly, } d_2(f(q), f(x_i)) < \varepsilon/2 \quad \dots\dots\dots (3)$$

$$\begin{aligned}
 \text{Now, } d_2(f(p), f(q)) &\leq d_2(f(p), f(x_i)) + d_2(f(x_i), f(q)) \\
 &< \varepsilon/2 + \varepsilon/2 \quad [\text{By (2) and (3)}] \therefore d_2(f(p), f(q)) < \varepsilon.
 \end{aligned}$$

Thus, $d_1(p, q) < \delta \Rightarrow d_2(f(p), f(q)) < \varepsilon \forall p, q \in M_1$.

Hence f is uniformly continuous.

3.3 Equivalent forms of Compactness.

Definition 3.3.1 A collection \mathbf{F} of subsets of a set M is said to have finite intersection property if the intersection of any finite number of elements of \mathbf{F} is nonempty.

Theorem 3.3.2 A metric space M is compact if and only if every collection of closed sets in M with finite intersection property has nonempty intersection.

Proof.

Suppose that M is compact.

Let $\{F_\alpha\}$ be a collection of closed subsets of M with finite intersection property.

We have to prove $\bigcap F_\alpha \neq \emptyset$.

Suppose $\bigcap F_\alpha = \emptyset$.

Then $(\bigcap F_\alpha)^c = M$.

$$\therefore \bigcup F_\alpha^c = M. \quad [\text{By De Morgan's laws}]$$

Since each F_α is closed, each F_α^c is open.

Thus, $\{F_\alpha^c\}$ is an open cover for M .

Since M is compact, this open cover has a finite subcover say

$$\{F_{\alpha_1}^c, F_{\alpha_2}^c, \dots, F_{\alpha_n}^c\}.$$

$$\therefore \bigcup_{i=1}^n F_{\alpha_i}^c = M.$$

$$\therefore (\bigcap_{i=1}^n F_{\alpha_i})^c = M.$$

$$\therefore \bigcap_{i=1}^n F_{\alpha_i} = \emptyset.$$

This is a contradiction to the collection $\{F_\alpha\}$ has finite intersection property.

$$\therefore \bigcap F_\alpha \neq \emptyset.$$

Conversely, assume that every collection of closed sets in M with finite intersection property has nonempty intersection.

We have to prove M is compact.

Let $\{G_\alpha\}$ be an open cover for M .

$$\therefore \bigcup G_\alpha = M.$$

$$\therefore (\bigcup G_\alpha)^c = \emptyset.$$

$$\therefore \bigcap G_\alpha^c = \emptyset.$$

Since each G_α is open, each G_α^c is closed.

Hence $\mathbb{F} = \{G_\alpha^c\}$ is a collection of closed sets whose intersection is empty. \therefore by hypothesis,

this collection does not have finite intersection property.

Hence there exists a finite sub collection $\{G_{\alpha_1}^c, G_{\alpha_2}^c, \dots, G_{\alpha_n}^c\}$ such that $\bigcap_{i=1}^n G_{\alpha_i}^c = \emptyset$

$$\therefore (\bigcup_{i=1}^n G_{\alpha_i})^c = \emptyset.$$

$$\therefore \bigcup_{i=1}^n G_{\alpha_i} = M.$$

Thus the given open cover $\{G_\alpha\}$ of M has a finite subcover $\{G_{\alpha_1}, G_{\alpha_2}, \dots, G_{\alpha_n}\}$.

Hence M is compact.

Definition 3.3.3 A metric space M is said to be totally bounded if for every

$\epsilon > 0$, there exists a finite number of elements $x_1, x_2, \dots, x_n \in M$ such that

$$B(x_1, \varepsilon) \cup B(x_2, \varepsilon) \cup \dots \cup B(x_n, \varepsilon) = M.$$

A nonempty subset A of a metric space M is said to be totally bounded if the subspace A is totally bounded metric space.

Theorem 3.3.4 Any compact metric space is totally bounded.

Proof.

Let M be a compact metric space.

We have to prove M is totally bounded.

Let $\varepsilon > 0$ be given.

Now, $\{ B(x, \varepsilon) / x \in M \}$ is an open cover for M .

Since M is compact, there exists points $x_1, x_2, \dots, x_n \in M$ such that

$$M = B(x_1, \varepsilon) \cup B(x_2, \varepsilon) \cup \dots \cup B(x_n, \varepsilon).$$

Hence M is totally bounded.

Theorem 3.3.5 Any totally bounded subset A of a metric space M is bounded.

Proof.

Let A be a totally bounded subset of a metric space M .

Then for given $\varepsilon > 0$, there exists points $x_1, x_2, \dots, x_n \in A$ such that

$$A = B_1(x_1, \varepsilon) \cup B_1(x_2, \varepsilon) \cup \dots \cup B_1(x_n, \varepsilon) \text{ where } B_1(x_i, \varepsilon) \text{ are open balls in } A.$$

Since open balls are bounded sets and finite union of bounded sets is bounded, A is bounded.

Note 3.3.6 The converse of the above theorem is not true. For,

Let M be an infinite set with discrete metric.

Then M is bounded.

$$\text{Also, } B(x, 1) = \{ x \} \text{ for all } x \in M.$$

Since M is infinite, M cannot be expressed as finite union of open balls of radius 1.

Hence M is not totally bounded.

Definition 3.3.7 Let (x_n) be a sequence in a metric space M . If $n_1 < n_2 < \dots < n_k < \dots$ is a sequence of positive integers, then (x_{n_k}) is a subsequence of (x_n) .

Theorem 3.3.8 A metric space M is totally bounded if and only if every sequence in M contains a Cauchy subsequence.

Proof.

Suppose that every sequence in M contains a Cauchy subsequence.

We have to prove M is totally bounded.

Let $\varepsilon > 0$ be given.

Choose $x_1 \in M$.

If $B(x_1, \varepsilon) = M$, then M is totally bounded.

If $B(x_1, \varepsilon) \neq M$, Then choose $x_2 \in B(x_1, \varepsilon) - M$ so that $d(x_1, x_2) \geq \varepsilon$.

If $B(x_1, \varepsilon) \cup B(x_2, \varepsilon) = M$, then M is totally bounded.

Otherwise, choose $x_3 \in [B(x_1, \varepsilon) \cup B(x_2, \varepsilon)] - M$ so that $d(x_3, x_1) \geq \varepsilon$ and $d(x_3, x_2) \geq \varepsilon$.

We proceed this process and if the process is terminated at a finite stage means M is totally bounded.

Suppose not, then we get a sequence (x_n) in M such that $d(x_n, x_m) \geq \varepsilon$ if $n \neq m$

.

$\therefore (x_n)$ cannot be a Cauchy sequence, which is a contradiction.

Conversely, suppose that M is totally bounded.

Let $S_1 = \{x_{11}, x_{12}, \dots, x_{1n}, \dots\}$ be a sequence in M .

If one of the terms in the sequence is repeated infinitely, then S_1 contains a constant subsequence which is in fact a Cauchy sequence.

So, we assume that no terms of S_1 is repeated infinitely so that the range of S_1 is infinite.

Since M is totally bounded, M can be covered by a finite number of open balls of radius $\frac{1}{2}$.

Hence one of these balls contains infinite number of terms of the sequence S_1 .

$\therefore S_1$ contains a subsequence $S_2 = \{x_{21}, x_{22}, \dots, x_{2n}, \dots\}$ which lies within an open ball of radius $\frac{1}{2}$.

Similarly, S_2 contains a subsequence $S_3 = \{x_{31}, x_{32}, \dots, x_{3n}, \dots\}$ which lies within an open ball of radius $\frac{1}{3}$.

We repeat the process of forming successive subsequences and finally we take the diagonal sequence $S = \{x_{11}, x_{22}, \dots, x_{nn}, \dots\}$.

We claim that S is a Cauchy subsequence of S_1 .

If $m > n$ then both x_m and x_n lie within an open ball of radius $\frac{\epsilon}{2}$.

$$\therefore d(x_m, x_n) < \frac{\epsilon}{2}.$$

$$\therefore d(x_m, x_n) < \epsilon \quad \forall m, n \geq \frac{2}{\epsilon}.$$

Hence S is a Cauchy subsequence of S_1 .

Thus every sequence in M has a convergent subsequence.

Corollary 3.3.9 A nonempty subset of a totally bounded set is totally bounded.

Proof.

Let A be a totally bounded subset of a metric space M .

Let B be a nonempty subset of A .

Let (x_n) be a sequence in B .

Since $B \subseteq A$, (x_n) is a sequence in A .

Since A is totally bounded, (x_n) has a Cauchy subsequence.

Thus every sequence in B has a Cauchy subsequence.

$\therefore B$ is totally bounded.

3.4 Sequentially Compact.

Definition 3.4.1 A metric space M is said to be sequentially compact if every sequence in M has a convergent subsequence.

Theorem 3.4.2 Let (x_n) be a Cauchy sequence in a metric space M . If (x_n) has a subsequence (x_{n_k}) converges to x , then (x_n) converges to x .

Proof.

Suppose that (x_n) has a subsequence (x_{n_k}) which converges to x .

We have to prove $x_n \rightarrow x$.

Let $\epsilon > 0$ be given.

Since (x_n) is a Cauchy sequence, there exists a positive integer N such that $d(x_n, x_m) < \frac{\varepsilon}{2} \forall n, m \geq N_1$ (1) Since $x_{n_k} \rightarrow x$, there exists a positive integer N_2 such

that $d(x_{n_k}, x) < \frac{\varepsilon}{2} \forall n_k \geq N_2$ (2)

Let $N = \max \{ N_1, N_2 \}$. Fix $n_k \geq N$.

Now. $d(x_n, x) \leq d(x_n, x_{n_k}) + d(x_{n_k}, x)$

$$< \frac{\varepsilon}{2} + \frac{\varepsilon}{2} \forall n \geq N$$

$\therefore d(x_n, x) < \varepsilon \forall n \geq N$.

$\therefore x_n \rightarrow x$.

Definition 3.4.3 A metric space M has Bolzano – Weierstrass property if every infinite subset of M has a limit point.

Theorem 3.4.4 In a metric space M the following are equivalent.

- (i) M is compact.
- (ii) M has Bolzano – Weierstrass property
- (iii) M is sequentially compact
- (iv) M is totally bounded and complete.

Proof.

(i) \Rightarrow (ii)

Let M be compact metric space.

Let A be an infinite subset of M .

Suppose that A has no limit point.

Let $x \in M$.

Since x is not a limit point of A , there exists an open ball $B(x, r_x)$ such that

$$B(x, r_x) \cap (A - \{x\}) = \emptyset.$$

$B(x, r_x)$ contains at most one point of A (contains x if $x \in A$).

Now, $\{ B(x, r_x) / x \in M \}$ is an open cover for M .

Since M is compact, there exists points $x_1, x_2, \dots, x_n \in M$ such that

$$M = B(x_1, r_{x1}) \cup B(x_2, r_{x2}) \cup \dots \cup B(x_n, r_{xn}).$$

$\therefore A \subseteq B(x_1, r_{x1}) \cup B(x_2, r_{x2}) \cup \dots \cup B(x_n, r_{xn})$.

Since each $B(x_i, r_{xi})$ has at most one point of A , A must be finite.

This is a contradiction to A is infinite.

Hence A has a limit point.

(ii) \Rightarrow (iii)

Suppose that M has Bolzano – Weierstrass property.

We have to prove M is sequentially compact.

Let (x_n) be a sequence in M .

If the range of (x_n) is finite, then a term of the sequence is repeated infinitely and hence (x_n) has a constant subsequence which is convergent.

Otherwise (x_n) has infinite number of distinct terms.

By hypothesis, this infinite set has a limit point say x .

\therefore for any $r > 0$, the open ball $B(x, r)$ contains infinite number of terms of the sequence (x_n) .

Choose a positive integer n_1 such that $x_{n_1} \in B(x, 1)$.

Now, choose $n_2 > n_1$ such that $x_{n_2} \in B(x, \frac{1}{2})$.

In general, for each positive integer k we choose $n_k > n_{k-1}$ such that $x_{n_k} \in B(x, \frac{1}{k})$.

Then (x_{n_k}) is a subsequence of (x_n) and $d(x_{n_k}, x) < \frac{1}{k} \forall k$.

$\therefore x_{n_k} \rightarrow x$.

Thus (x_{n_k}) is a convergent subsequence of (x_n) .

Hence M is sequentially compact.

(iii) \Rightarrow (iv)

Suppose that M is sequentially compact.

Then every sequence in M has a convergent subsequence.

We have every Cauchy sequence is convergent.

Thus, every sequence in M has a Cauchy subsequence.

Hence M is totally bounded.

Now, we prove that M is complete.

Let (x_n) be a Cauchy sequence in M .

By hypothesis, (x_n) contains a convergent subsequence (x_{n_k}) .

Let $x_{n_k} \rightarrow x$.

Then $x_n \rightarrow x$.

$\therefore M$ is complete.

(iv) \Rightarrow (i)

Suppose that M is totally bounded and complete.

We have to prove M is compact.

Suppose not.

Then there exists an open cover $\{G_\alpha\}$ for M which has no finite subcover.

Take $r_n = \frac{1}{2^n}$.

Since M is totally bounded, M can be covered by a finite number of open balls of radius r_1 .

Since M is not covered by a finite number of G_α 's, at least one of these open balls say $B(x_1, r_1)$ cannot be covered by finite number of G_α 's.

Now, $B(x_1, r_1)$ is totally bounded.

Hence as before we can find $x_2 \in B(x_1, r_1)$ such that $B(x_2, r_2)$ cannot be covered by finite number of G_α 's.

Proceeding like this we get a sequence (x_n) in M such that $B(x_n, r_n)$ cannot be covered by finite number of G_α 's and $x_{n+1} \in B(x_n, r_n)$.

Let m and n be positive integers with $n < m$.

Now, $d(x_n, x_m) \leq d(x_n, x_{n+1}) + d(x_{n+1}, x_{n+2}) + \dots + d(x_{m-1}, x_m)$

$$< r_n + r_{n+1} + \dots + r_{m-1}$$

$$< \frac{1}{2^n} + \frac{1}{2^{n+1}} + \dots + \frac{1}{2^{m-1}}$$

$$< \frac{1}{2^{n-1}} (\frac{1}{2^n} + \frac{1}{2^n} + \dots)$$

$$< \frac{1}{2^{n-1}}$$

$\therefore (x_n)$ is a Cauchy sequence in M .

Since M is complete, there exists $x \in M$ such that $x_n \rightarrow x$.

Now, $x \in G_\alpha$ for some α .

Since G_α is open, there exists $\varepsilon > 0$ such that $B(x, \varepsilon) \subseteq G_\alpha$.

We have $x_n \rightarrow x$ and $r_n = \frac{1}{2^n} \rightarrow 0$.

\therefore there exists a positive integer N such that

$$d(x_n, x) < \frac{\varepsilon}{2} \text{ and } r_n < \frac{\varepsilon}{2} \quad \forall n \geq N.$$

Fix $n \geq N$.

We claim that $B(x_n, r_n) \subseteq B(x, \varepsilon)$. $y \in B(x_n, r_n)$,

$$r_n) \Rightarrow d(x_n, y) < r_n < \frac{\varepsilon}{2}$$

$$\Rightarrow d(x_n, x) + d(x_n, y) < \frac{\varepsilon}{2} + \frac{\varepsilon}{2}$$

$$\Rightarrow d(x, y) < \varepsilon$$

$$\Rightarrow y \in B(x, \varepsilon).$$

$\therefore B(x_n, r_n) \subseteq B(x, \varepsilon) \subseteq G_\alpha$.

Thus, $B(x_n, r_n)$ is covered by a single G_α , which is a contradiction.

Hence M is compact.

UNIT-IV

DERIVATIVES

CONTInuity and Differentiation

Let X, Y be the metric spaces. Suppose $E \subset X$, f maps E into Y and p is a limit point of E we write $f(x) \rightarrow q$ as $x \rightarrow p$ or

$$\lim_{x \rightarrow p} f(x) = q.$$

If there is a point $q \in Y$ with the following property, for every $\epsilon > 0$ there exists $S > 0$ such that $d_Y(f(x), q) < \epsilon \forall x \in E$ for which $0 < d_X(x, p) < S$. (i.e.)

$$\lim_{x \rightarrow p} f(x) = q.$$

if given $\epsilon > 0$ there exists $S > 0$ such that $0 < d_X(x, p) < S \Rightarrow d_Y(f(x), q) < \epsilon$.

Definition 3.1 Let X and Y be any two metric spaces and $E \subset X$. Let f and g be any complex functions defined on E then we define $f + g$ as follows.
 $(f + g)(x) = f(x) + g(x)$

Theorem 3.2 Let X and Y be any two metric spaces and $E \subset X$. p is a limit point of E . Then

$$\lim_{x \rightarrow p} f(x) = q \text{ iff } \lim_{n \rightarrow \infty} f(p_n) = q$$

for every sequence $\{p_n\}$ in E such that $p_n \neq p$ and

$$\lim_{n \rightarrow \infty} p_n = p.$$

Proof: Suppose

$$\lim_{x \rightarrow p} f(x) = q$$

\Rightarrow Given $\epsilon > 0$, there exists $S > 0$ such that $0 < d_X(x, p) < S \Rightarrow d_Y(f(x), q) < \epsilon \forall x \in E \dots (1)$

$\{p_n\}$ is a sequence of points in E such that $\{p_n\} \rightarrow p$ as $n \rightarrow \infty$ ($p_n \neq p$) (This is possible $\because p$ is a limit point of E) \Rightarrow there exists N depending on S such that $d_X(p_n, p) < S \forall n \geq N$. Now By (1) we have, $d_Y(f(p_n), q) < \epsilon \forall n \geq N$ (i.e.)

$$\lim_{n \rightarrow \infty} f(p_n) = q.$$

Conversely, Suppose

$$\lim_{n \rightarrow \infty} f(p_n) = q$$

for every $\{p_n\}$ in E such that $p_n \neq p$ and

$$\lim_{n \rightarrow \infty} p_n = p$$

To Prove

$$\lim_{x \rightarrow p} f(x) = q$$

Suppose this result is false, for some $\epsilon > 0$ and for every $S > 0$ such that $d_X(x, p) < S \Rightarrow d_Y(f(x), q) \geq \epsilon$. Let $S_n = \frac{1}{n}$, $n = 1, 2, 3, \dots$. For $S > 0$ without loss of generality choose a point $p \in E$ such that $d_X(p_1, p) < S_1 (= 1) \Rightarrow d_Y(f(p_1), q) \geq \epsilon$. Similarly, for $S_2 > 0$ choose a point $p_2 \in E$ such that $d_X(p_2, p) < S_2 = (1/2) \Rightarrow d_Y(f(p_2), q) \geq \epsilon$. Proceeding for $S_n > 0$, choose a point $p_n \in E$ such that $d_X(p_n, p) < S_n (= 1/n) \Rightarrow d_Y(f(p_n), q) \geq \epsilon$. \therefore we have a sequence $\{p_n\}$ in E such that $d_X(p_n, p) < \frac{1}{n} \Rightarrow d_Y(f(p_n), q) \geq \epsilon$. Now $\{p_n\} \rightarrow p$ as $n \rightarrow \infty$ [$\because 1/n \rightarrow 0$ as $n \rightarrow \infty$]. But $f(p_n)$ does not converge to q \therefore our assumption is wrong. Hence for every $\epsilon > 0$ there exists $S > 0$ such that $d_X(x, p) < S \Rightarrow d_Y(f(x), q) < \epsilon \quad \forall x \in E$.

$$\therefore \lim_{x \rightarrow p} f(x) = q.$$

Corollary 3.3 *If f has a limit at p then this limit is unique.*

Proof: Suppose q is a limit of f at p . (i.e.)

$$\lim_{x \rightarrow p} f(x) = q.$$

\therefore By the previous theorem, we have

$$\lim_{n \rightarrow \infty} f(p_n) = q$$

for every $\{p_n\}$ in E such that $p_n \neq p$ and $p_n \rightarrow p$. But we know that, Every convergence sequence converges to a unique limit. $\therefore f$ has a unique limit at p .

Definition 3.4 *Suppose we have two complex f and g then $f \pm g, fg, \lambda f, \frac{f}{g}$ ($g \neq 0$) are defined on a set E as follows.*

1. $(f + g)(x) = f(x) + g(x)$.
2. $(f \cdot g)(x) = f(x) \cdot g(x)$
3. $(\lambda f)(x) = \lambda f(x)$
4. $(\frac{f}{g})(x) = \frac{f(x)}{g(x)}, g(x) \neq 0$.

Similarly we define \bar{f}, \bar{g} map E into \mathbb{R}^k . Then we can define $\bar{f} \pm \bar{g}, \bar{f}\bar{g}, \lambda\bar{f}, \frac{\bar{f}}{\bar{g}}$, ($\bar{g} \neq 0$).

Definition 3.5 Continuous at a point: *Suppose X, Y are metric spaces and $E \subset X, p \in E$ and f maps E into Y . Then f is said to be continuous at p if for every $\epsilon > 0$, there exists a $S > 0 \Rightarrow 0 < d_X(x, p) < S \Rightarrow d_Y(f(x), f(p)) < \epsilon \quad \forall x \in E$.*

Remark 3.6 Suppose f is continuous at $p \Rightarrow$ for every $\epsilon > 0$ there exists $S > 0$ such that $0 < d_X(x, p) < S \Rightarrow d_Y(f(x), f(p)) < \epsilon \forall x \in E \Rightarrow x \in N_S(p) \Rightarrow f(x) \in N_\epsilon(f(p)) \forall x \in E \Rightarrow f(N_S(p)) \subset N_\epsilon(f(p))$.

Theorem 3.7 Let X, Y be metric space and $E \subset X$. p is a limit point of E and $f : E \rightarrow Y$. Then f is continuous at p iff

$$\lim_{x \rightarrow p} f(x) = f(p)$$

Proof: Suppose f is continuous at p . \Leftrightarrow for every $\epsilon > 0$ there exists $S > 0$ such that $0 < d_X(x, p) < S \Rightarrow d_Y(f(x), f(p)) < \epsilon \forall x \in E \Leftrightarrow$

$$\lim_{x \rightarrow p} f(x) = f(p)$$

Theorem 3.8 Suppose X, Y, Z are metric space and $E \subset E$. f maps E into Y , g maps the range of f into Z and h is a mapping of E into Z defined by $h(x) = g(f(x))$. If f is continuous at $p \in E$ and if g is continuous at $f(p)$ then h is continuous at p . (The function h is called composite of f and g and we write as $h = g \circ f$)

Proof: Let $\epsilon > 0$ be given and g is continuous at $f(p)$. $\therefore \eta > 0$ such that $d_Z(g(y), g(f(p))) < \epsilon, y \in f(E)$ (1)

Since f is continuous at p for this $\eta > 0$, there exists $S > 0$ such that $d_X(x, p) < S \Rightarrow d_Y(f(x), f(p)) < \eta \forall x, y \in E$

$$\begin{aligned} & \text{(i.e.) } d_Y(f(x), f(p)) < \eta, f(x) \in f(E) \\ & \Rightarrow d_Z(g(f(x)), g(f(p))) < \epsilon \text{ by (1)} \\ & \Rightarrow d_Z(g \circ f(x), (g \circ f)(p)) < \epsilon \\ & \Rightarrow d_Z(h(x), h(p)) < \epsilon \text{ (} h = g \circ f \text{)}. \end{aligned}$$

\therefore we have, $d_X(x, p) < S \Rightarrow d_Z(h(x), h(p)) < \epsilon \forall x \in E \Rightarrow h$ is continuous at p .

Theorem 3.9 A mapping f of a metric space X into a metric space Y is continuous on X iff $f^{-1}(E)$ is open in X for every open set E in Y .

Proof: Suppose f is continuous on X . Let V be a open set in Y . To Prove: $f^{-1}(V)$ is open in X . Let $p \in f^{-1}(V)$; $p \in f^{-1}(V) \Rightarrow f(p) \in V$. Since V is open, there exists $\epsilon > 0$ such that $N_\epsilon(f(p)) \subset V$ (1)

Since f is continuous at p , for $\epsilon > 0$ there exists $S > 0$ such that $f(N_S(p)) \subset N_\epsilon(f(p))$ (2)

From (1) and (2), $\Rightarrow f(N_S(p)) \subset V \Rightarrow N_S(p) \subset f^{-1}V \Rightarrow p$ is an interior point of $f^{-1}(V)$. Since p is arbitrary, $f^{-1}(V)$ is open in X . Conversely: Suppose $f^{-1}(V)$ is open in X for every open set V in Y . To Prove: f is continuous at $p, p \in X$. Let $\epsilon > 0$ be given. Consider an open set $N_\epsilon(f(p))$ in Y , $f^{-1}(N_\epsilon(f(p)))$ is open in X . Now, $\Rightarrow p \in f^{-1}(N_\epsilon(f(p))) \Rightarrow p$ is an interior point of $f^{-1}(N_\epsilon(f(p))) \Rightarrow$ there exists $S > 0$ such that $N_S(p) \subset f^{-1}(N_\epsilon(f(p))) \Rightarrow f(N_S(p)) \subset N_\epsilon(f(p)) \Rightarrow f$ is continuous at p .

Corollary 3.10 *A mapping f of a metric space X into a metric space Y is continuous iff $f^{-1}(C)$ is closed in X for every closed set C in Y .*

Proof: Let C be a closed set in Y . C^c is open in $Y \Rightarrow f^{-1}(C^c)$ is open in X . (by Theorem 3.9) $\Rightarrow [f^{-1}(C)]^c$ is open in $X \Rightarrow f^{-1}(C)$ is closed in X . Conversely: Suppose $f^{-1}(C)$ is closed in X for every closed set C in Y . To Prove: f is continuous on X . Let A be an open set in $Y \Rightarrow A^c$ is closed in $Y \Rightarrow f^{-1}(A^c)$ is closed in X . (by our assumption) $\Rightarrow [f^{-1}(A)]^c$ is closed in $X \Rightarrow f^{-1}(A)$ is open in X . $\Rightarrow f$ is continuous on X . (by the previous theorem)

Theorem 3.11 *Let f and g be complex continuous function in a metric space X , then $f + g, f \cdot g, \frac{f}{g} (g \neq 0)$ are continuous on X .*

Proof: At isolated point of X there is nothing prove. Fix a point $p \in X$ and suppose p is a limit point of X . Since f and g are continuous at p .

$$\lim_{x \rightarrow p} f(x) = f(p); \quad \lim_{x \rightarrow p} g(x) = g(p)$$

Now,

$$\lim_{x \rightarrow p} (f + g)(x) = \lim_{n \rightarrow \infty} (f + g)p_n$$

where $p_n \rightarrow p$ as $n \rightarrow \infty$ and $p_n \neq p$

$$\begin{aligned} \lim_{x \rightarrow p} (f + g)(x) &= \lim_{n \rightarrow \infty} (f(p_n) + g(p_n)) \\ &= \lim_{n \rightarrow \infty} f(p_n) + \lim_{n \rightarrow \infty} g(p_n) \\ &= f(p) + g(p) \end{aligned}$$

similarly the other results follow.

Theorem 3.12 *Let f_1, f_2, \dots, f_k be real functions in a metric space X . Let \bar{f} be the mapping X into \mathbb{R}^k . defined by $\bar{f}(x) = (f_1(x), f_2(x), \dots, f_k(x)) x \in X$. Then*

- (a) \bar{f} is continuous iff each of the functions f_1, f_2, \dots, f_k is continuous.
 (b) \bar{f} and \bar{g} are continuous mapping of X into \mathbb{R}^k then $\bar{f} + \bar{g}, \bar{f} \cdot \bar{g}$ are continuous on X (f_1, f_2, \dots, f_k are called components of \bar{f}).

Proof: Suppose \bar{f} is continuous at every $p \in X$. Then given $\epsilon > 0$ there exists $S > 0$ such that

$$\begin{aligned} |\bar{f}(x) - \bar{f}(p)| &< \epsilon \quad \text{if } 0 < d_X(x, p) < S \\ \Rightarrow \left(\sum_{i=1}^k (f_i(x) - f_i(p))^2 \right)^{1/2} &< \epsilon \quad \text{if } 0 < d_X(x, p) < S \\ \Rightarrow |f_i(x) - f_i(p)| &< \left(\sum_{i=1}^k (f_i(x) - f_i(p))^2 \right)^{1/2} < \epsilon \quad \forall i = 1, 2, \dots, k \\ \Rightarrow |f_i(x) - f_i(p)| &< \epsilon \quad \forall i = 1, 2, \dots, k \quad \text{if } 0 < d_X(x, p) < S \end{aligned}$$

\Rightarrow each f_i is continuous at p , ($1 \leq i \leq k$, $p \in X$) \Rightarrow each f_i is continuous on X , ($1 \leq i \leq k$). Conversely, Suppose f_i is continuous on X for each $i = 1, \dots, k \Rightarrow f_i$ is continuous at every $p \in X \Rightarrow$ Given $\epsilon > 0$ there exists $S_i > 0$ such that $0 < d_X(x, p) < S_i \Rightarrow |f_i(x) - f_i(p)| < \frac{\epsilon}{\sqrt{k}} \forall i = 1, 2, \dots, k$. Let $S = \min(S_1, S_2, \dots, S_k)$. Now,

$$\begin{aligned} 0 < d_X(x, p) < S_i &\Rightarrow |f_i(x) - f_i(p)| < \frac{\epsilon}{\sqrt{k}} \forall i = 1, 2, \dots, k \\ &\Rightarrow |f_i(x) - f_i(p)|^2 < \frac{\epsilon^2}{(\sqrt{k})^2} \\ &\Rightarrow \sum_{i=1}^k |f_i(x) - f_i(p)|^2 < \frac{\epsilon^2}{k} \cdot k \\ &= \epsilon^2 \\ &\Rightarrow \sqrt{\sum_{i=1}^k |f_i(x) - f_i(p)|^2} < \epsilon \\ &\Rightarrow |\bar{f}(x) - \bar{f}(p)| < \epsilon \\ (i.e.) 0 < d_X(x, p) < S &\Rightarrow |\bar{f}(x) - \bar{f}(p)| < \epsilon \end{aligned}$$

$\Rightarrow \bar{f}$ is continuous at every $p \in X \Rightarrow \bar{f}$ is continuous on X

(b) Let $\bar{f} = (f_1, f_2, \dots, f_k)$ and $\bar{g} = (g_1, g_2, \dots, g_k)$. Now, $\bar{f} + \bar{g} = (f_1 + g_1, f_2 + g_2, \dots, f_k + g_k)$; $\bar{f} \cdot \bar{g} = (f_1 \cdot g_1, f_2 \cdot g_2, \dots, f_k \cdot g_k)$. Given \bar{f} and \bar{g} are continuous. by (a), each f_i, g_i are continuous ($1 \leq i \leq k$) (by Theorem 3.11) $\Rightarrow f_i + g_i, f_i \cdot g_i$ are continuous. (by (a))

Theorem 3.13 Let $\bar{x} = (x_1, x_2, \dots, x_k) \in \mathbb{R}^k$ define $\phi_i : \mathbb{R}^k \rightarrow \mathbb{R}$ by $\phi_i(\bar{x}) = x_i$, ($i = 1, 2, \dots, k$). ϕ_i is called the coordinate function, then ϕ_i is continuous.

Proof: Let $\bar{x}, \bar{y} \in \mathbb{R}^k$. Given $\epsilon > 0$ choose $S = \epsilon$ such that

$$\begin{aligned} |\bar{x} - \bar{y}| &< S \\ \Rightarrow |\phi_i(\bar{x}) - \phi_i(\bar{y})| &= |x_i - y_i| \\ &< \left(\sum_{i=1}^k |x_i - y_i|^2 \right)^{1/2} \\ &= |\bar{x} - \bar{y}| \\ &< \epsilon \end{aligned}$$

$\Rightarrow \phi_i$ is continuous on \mathbb{R}^k

Theorem 3.14 Every polynomial in \mathbb{R}^k is continuous.

Proof: By the above theorem $\phi_i : \mathbb{R}^k \rightarrow \mathbb{R}$ is continuous for every i . Now, $\phi_i^2(\bar{x}) = \phi_i(\bar{x}) \cdot \phi_i(\bar{x}) = x_i \cdot x_i = x_i^2 \forall i$. In general $\phi_i^{n_i}(\bar{x}) = x_i^{n_i} \forall i$. By

Theorem [3.14](#), $\phi_i^{n_i}$ is continuous. Now,

$$\begin{aligned} (\phi_1^{n_1} \cdot \phi_2^{n_2} \cdots \phi_k^{n_k})\bar{x} &= \phi_1^{n_1}(\bar{x}) \cdot \phi_2^{n_2}(\bar{x}) \cdots \phi_k^{n_k}(\bar{x}) \\ &= x_1^{n_1} \cdot x_2^{n_2} \cdots x_k^{n_k} \end{aligned}$$

Now $\phi_1^{n_1} \cdot \phi_2^{n_2} \cdots \phi_k^{n_k}$ is a monomial function, where n_1, n_2, \dots, n_k are positive integers. Every monomial function is continuous C_{n_1, n_2, \dots, n_k} is a complex constant $\Rightarrow C_{n_1, n_2, \dots, n_k} \cdot x_1^{n_1} \cdot x_2^{n_2} \cdots x_k^{n_k}$ is continuous on \mathbb{R}^k . $\Rightarrow \sum C_{n_1, n_2, \dots, n_k} \cdot x_1^{n_1} \cdot x_2^{n_2} \cdots x_k^{n_k}$ is continuous on \mathbb{R}^k . \Rightarrow Every polynomial is continuous on \mathbb{R}^k .

Continuity and Compact: A mapping \bar{f} on a set E into X is said to be bounded, if there is a real number m such that $|\bar{f}(x)| < m \forall x \in X$.

Theorem 3.15 Suppose f is continuous function on a compact metric space X into a metric space Y . Then $f(X)$ is compact. (i.e., continuous image of a compact metric space is compact)

Proof: Given that X is compact. To Prove: $f(X)$ is compact. Let $\{V_\alpha\}$ be an open cover for $f(X) \Rightarrow$ each V_α is open in Y . Now, Given f is continuous $\Rightarrow f^{-1}(V_\alpha)$ is open in X for each $\alpha \Rightarrow \{f^{-1}(V_\alpha)\}$ is open cover for X . Since X is compact, there exists finitely many indices $\alpha_1, \alpha_2, \dots, \alpha_n$ such that

$$\begin{aligned} X &\subset f^{-1}(V_{\alpha_1}) \cup f^{-1}(V_{\alpha_2}) \cup \cdots \cup f^{-1}(V_{\alpha_n}) \\ &= \bigcup_{i=1}^n f^{-1}(V_{\alpha_i}) \\ \Rightarrow f(X) &\subset \bigcup_{i=1}^n f f^{-1}(V_{\alpha_i}) \subset \bigcup_{i=1}^n V_{\alpha_i} \end{aligned}$$

$\Rightarrow \{V_\alpha\} \Rightarrow$ has a finite sub cover. $\therefore f(X)$ is compact.

Theorem 3.16 If \bar{f} is continuous mapping of a compact metric space X into \mathbb{R}^k . Then $\bar{f}(X)$ is closed and bounded. $\therefore \bar{f}$ is bounded.

Proof: Given \bar{f} is continuous and X is compact. $\Rightarrow \bar{f}(x)$ is a compact subset of \mathbb{R}^k . $\Rightarrow \bar{f}(x)$ is closed and bounded. (by Heine Borel theorem) Now, in particular $\Rightarrow \bar{f}(x)$ is bounded $\Rightarrow \bar{f}$ is bounded.

Theorem 3.17 Suppose f is a continuous real function on a compact metric space X and $M = \sup_{p \in X} f(p)$ and let $m = \inf_{p \in X} f(p)$. Then, there exists a points $p, q \in X$ such that $f(p) = M$, $f(q) = m$ (i.e., f attains maximum M at p and minimum m at q)

Proof: We know that, If E is bounded and $y = \sup E$ and $X = \inf E$ then $x, y \in \bar{E}$. Since f is continuous and X is compact $\Rightarrow f(X)$ is closed and bounded [By the above Theorem [3.16](#)] and since $f(X)$ is bounded. $m, M \in \overline{f(X)} = f(X)$ ($\because f(X)$ is closed) $\Rightarrow m, M \in f(X) \Rightarrow$ there exists $p, q \in X$ such that $M = f(p)$, $m = f(q)$.

Theorem 3.18 Suppose f is continuous 1-1 mapping of a compact metric space X into a metric space Y . Then the inverse mapping f^{-1} defined on Y by $f^{-1}(f(X)) = X$ is a continuous mapping of Y onto X .

Proof: Suppose f is a continuous 1-1 mapping of a compact metric space X into a metric space Y and also $f^{-1}(f(X)) = X$. To Prove: f^{-1} is continuous on Y , it is enough to prove that $(f^{-1})(V)$ is open in Y for every open set V in X . Let V be a open set in $X \Rightarrow V^c$ is closed in X . Since X is compact, V^c is compact in X . Since f is continuous, $f(V^c)$ is compact in $Y \Rightarrow f(V^c)$ is closed in $Y \Rightarrow (f(V^c))^c$ is closed in $Y \Rightarrow f(V)$ is open in Y . ($\because f$ is 1-1 and onto) $\Rightarrow (f^{-1}(V))^{-1}$ is open in $Y \Rightarrow f^{-1}$ is continuous on Y .

Definition 3.19 (Uniformly Continuous) Let X and Y be any two metric space then the $f : X \rightarrow Y$ is said it to be uniformly continuous on X if for every $\epsilon > 0$ there exists a $\delta > 0$ such that $d_X(p, q) < \delta \Rightarrow d_Y(f(p), f(q)) < \epsilon \forall p, q \in X$.

Theorem 3.20 Let f be a continuous mapping of a compact metric space X into a metric space Y then f is uniformly continuous. (i.e.) Continuous function defined on a compact metric space is uniformly continuous.

Proof: Let $\epsilon > 0$ be given let f is continuous on $X \Rightarrow f$ is continuous at every point $p \in X$. Now, f is continuous at $p \Rightarrow$ there exists a positive real $\phi(p)$ such that $d_X(p, q) < \phi(p) \Rightarrow d_Y(f(p), f(q)) < \epsilon \forall q \in X \dots \dots (1)$
Let $J(p) = N_{\frac{\phi(p)}{2}}\{p\} \Rightarrow J(p)$ is a closed in $X \Rightarrow J(p)$ is a open in X . $\therefore \{J(p) | p \in X\}$ is an open cover for X . Since X is compact, there exists finitely many $p \in X$. p_1, p_2, \dots, p_n such that $X \subset \bigcup_{i=1}^n J(p_i)$. Let $S = \min\{\frac{\phi(p)}{2}, \dots, \frac{\phi(p)}{2}\}$. Clearly, $S > 0$. Let p, q be points in X such that $d_X(p, q) < S$. Now,

$$\begin{aligned} p \in X &\subset \bigcup_{i=1}^n J(p_i) \\ &\Rightarrow p \in J(p_m) \text{ for some } m, 1 \leq m \leq n \\ &\Rightarrow d_X(p, p_m) < \frac{\phi(p_m)}{2} < \phi(p_m) \\ &\Rightarrow d_Y(f(p), f(p_m)) < \epsilon/2 \dots \dots (2) \text{ (by(1))} \\ \text{Now } d_X(q, p_m) &< d_X(q, p) + d(p, p_m) \\ &< S + \frac{\phi(p_m)}{2} \\ &< \frac{\phi(p_m)}{2} + \frac{\phi(p_m)}{2} \\ &= \phi(p_m) \\ \text{(i.e.) } d_X(q, p_m) &< \phi(p_m) \\ &\Rightarrow d_Y(f(q), f(p_m)) < \epsilon/2 \text{ by(1)} \dots \dots (3) \end{aligned}$$

$$\begin{aligned} \Rightarrow d_Y(f(p), f(q)) &< d_Y(f(q), f(p_m)) + d_Y(f(p_m), f(q)) \\ &= \epsilon/2 + \epsilon/2 \text{ (by (2) and (3))} \\ \therefore d_X(p, q) < S &\Rightarrow d_Y(f(p), f(q)) < \epsilon \end{aligned}$$

$\Rightarrow f$ is uniformly continuous on X .

Theorem 3.21 Let E be a non-compact set in \mathbb{R}^1 . Then

- (a) there exists a continuous function on E which is not bounded,
- (b) there exists continuous and bounded function on which has no maximum if in addition E is bounded,
- (c) there exists a continuous function on E which is not uniformly continuous.

Proof: Case(i): Suppose E is bounded.

(a) To Prove: f is continuous but not bounded. Since E is bounded, there exists a limit point of x_0 of E such that $x_0 \notin E$. [$\because E$ is not closed]. Define a map $f : E \rightarrow \mathbb{R}^1$ by $f(x) = \frac{1}{x-x_0}$, $x \in E$. $\therefore f$ is continuous on E . To Prove: f is unbounded on E . Since x_0 is a limit point of E . $N_r(x_0) \cap E \neq \emptyset \forall r > 0 \Rightarrow$ there exists x_1 such that $x_1 \in N_r(x_0) \cap E \Rightarrow x_1 \in N_r(x_0)$ and $x_1 \in E$

$$\begin{aligned} \Rightarrow |x_1 - x_0| &< r \text{ and } x_1 \in E \\ \Rightarrow \frac{1}{|x_1 - x_0|} &> \frac{1}{r} \text{ and } x_1 \in E \\ \Rightarrow |f(x_1)| &> \frac{1}{r} \text{ and } x_1 \in E \forall r > 0 \end{aligned}$$

$\forall r > 0$ there exists $x \in E$ such that $|f(x)| > \frac{1}{r} \Rightarrow f$ is unbounded on E .

(b) Define $g : E \rightarrow \mathbb{R}$ by $g(x) = \frac{1}{1+(x-x_0)^2}$, $x \in E$. Clearly, g is continuous. Now, $0 < g(x) < 1 \Rightarrow g(x)$ is a bounded function. Clearly, $\sup_{x \in E} g(x) = 1$. But $g(x) < 1 \forall x \in E$. $\therefore g$ has no maximum on E .

(c) Let $f : E \rightarrow \mathbb{R}$ be defined by $f(x) = \frac{1}{x-x_0}$, $x \in E$, where x_0 is a limit point of E . Clearly, f is continuous on E . Let $\epsilon > 0$ be given. Let $S > 0$ be arbitrary choose a point $x \in E$ such that $|x - x_0| < S$ and taking t very close to x_0 so as to satisfy $|t - x| < S$. Then,

$$\begin{aligned} |f(t) - f(x)| &= \left| \frac{1}{t-x_0} - \frac{1}{x-x_0} \right| \\ &= \left| \frac{x-x_0-t+x_0}{(t-x_0)(x-x_0)} \right| \\ &= \frac{|x-t|}{|t-x_0||x-x_0|} \\ &> \frac{1}{t-x_0} > \epsilon \end{aligned}$$

(If we choose $x \in (x_0 - S, x_0)$, $t \in (x_0, x_0 + S)$ and $|x - t| < S$ or $t \in (x_0 - S, x_0)$, $x \in (x_0, x_0 + S)$ and $|x - t| < S \Rightarrow |t - x| > |x - x_0|$) So we

have taken t very close to x_0 and we made the difference $|f(t) - f(x)| > \epsilon$ although $|t - x| < S$. Since this is true for every $S > 0 \Rightarrow f$ is not uniformly continuous.

Case(ii): Suppose E is not bounded.

(a) Define $f : E \rightarrow R$ by $f(x) = x$. Clearly, f is continuous on E and f is not bounded on E . \therefore there exists function on E which is not bounded.

(b) Define $g : E \rightarrow R$ by $g(x) = \frac{x^2}{1+x^2} \Rightarrow g$ is continuous. Now, as $x^2 < 1 + x^2 \Rightarrow g(x) = \frac{x^2}{1+x^2} < 1$. $\therefore 0 < g(x) < 1 \quad \forall x \in E$. $\therefore g$ is a bounded. $\therefore g$ is a continuous and bounded function. $\sup_{x \in E} g(x) = 1$. But g has no maximum on E .

(c) If the boundedness is omitted then the result fails. Let E be the set of all integers. Then every function defined on E is uniformly continuous on $E \Rightarrow$ for every $\epsilon > 0$ choose $S < 1$ such that $|X - Y| < S \Rightarrow |f(x) - f(y)| = 0 < \epsilon$

Continuity and Connectedness:

Theorem 3.22 *If f is a continuous mapping on a metric space X into a metric space Y and E is a connected subset of X . Then $f(E)$ is connected. i.e., continuous image of a connected subset of a metric space is connected.*

Proof: Given E is connected subset of X . To Prove: $f(E)$ is a connected subset of Y . Suppose $f(E)$ is not connected. $\Rightarrow f(E) = A \cup B$ where A and B are non-empty separated sets. Put $G = E \cap f^{-1}(A)$ and $H = E \cap f^{-1}(B)$

$$\begin{aligned} G \cup H &= (E \cap f^{-1}(A)) \cup (E \cap f^{-1}(B)) \\ &= E \cap (f^{-1}(A) \cup f^{-1}(B)) \\ &= E \cap (f^{-1}(A \cup B)) \\ &= E \cap E \\ G \cup H &= E \end{aligned}$$

Clearly $G \neq \emptyset$ $H \neq \emptyset$ ($\because A \neq \emptyset, B \neq \emptyset$). Claim: G and H are separated

sets. i.e., To Prove $\bar{G} \cap H = \emptyset, G \cap \bar{H} = \emptyset$. Now

$$\begin{aligned}
G &= E \cap f^{-1}(A) \\
\Rightarrow G &\subset f^{-1}(A) \subset f^{-1}(\bar{A}) \\
\Rightarrow \bar{G} &\subset \overline{f^{-1}(\bar{A})} = f^{-1}(\bar{A}) \quad [\because \bar{A} \text{ is closed and} \\
&\qquad\qquad\qquad f \text{ is continuous} \Rightarrow f^{-1}(\bar{A})] \\
\Rightarrow f(\bar{G}) &\subset f f^{-1}(\bar{A}) \subset \bar{A} \\
\Rightarrow f(\bar{G}) &\subset \bar{A} \\
H &= E \cap f^{-1}(B) \\
\Rightarrow H &\subset f^{-1}(B) \Rightarrow f(H) \subset f f^{-1}(B) = B \\
\Rightarrow f(H) &\subset B \\
\Rightarrow f(\bar{G}) \cap f(H) &\subset \bar{A} \cap B = \emptyset \quad (\because A \text{ and } B \text{ are separated sets}) \\
\Rightarrow f(\bar{G}) \cap f(H) &= \emptyset \\
\Rightarrow f(\bar{G} \cap H) &= \emptyset \\
\Rightarrow \bar{G} \cap H &= \emptyset \\
\text{similarly, } G \cap \bar{H} &= \emptyset
\end{aligned}$$

$\therefore G$ and H are separated sets. $\Rightarrow E$ can be expressed as a union of two non-empty separated sets. $\Rightarrow E$ is not connected. $\Rightarrow \Leftarrow$ to E is connected. $\therefore f(E)$ is connected.

Theorem 3.23 Intermediate Value Theorem: Let f be a continuous real valued function on $[a, b]$. If $f(a) < f(b)$ and c is the number such that $f(a) < c < f(b)$ then there exists a point $x \in (a, b)$ such that $f(x) = c$.

Proof: Every interval in \mathbb{R} is connected and f is continuous. By the previous theorem, $f[a, b]$ is connected in \mathbb{R} . $\Rightarrow f[a, b]$ is interval in \mathbb{R} . Let $f(a), f(b) \in f[a, b] \Rightarrow [f(a), f(b)] \subset f[a, b]$. Now, $f(a) < c < f(b) \Rightarrow c \in f[a, b] \Rightarrow c = f(x)$ for some $x \in [a, b]$.

Remark 3.24 Converse not true.

Proof: If any two points x_1 and x_2 and for any member c between $f(x_1)$ and $f(x_2)$ there is a point x in $[x_1, x_2]$ such that $f(x) = c$ then f may be discontinuous. For example:

$$f(x) = \begin{cases} \sin \frac{1}{x} & x \neq 0 \\ 0 & x = 0 \end{cases}$$

Choose $x_1 \in (-\frac{\pi}{2}, 0), x_2 \in (0, \frac{\pi}{2})$. Clearly $x_1 < x_2$; $f(x_1)$ =negative $f(x_2)$ =positive. $\therefore f(0) = 0$. f is continuous all the points except at 0.

Differentiation:

Definition 3.25 Let f be real value function defined on $[a, b]$, for any $x \in [a, b]$ form the quotient $\phi(t) = \frac{f(t)-f(x)}{t-x}$, $a < t < b, t \neq x$, and defined

$$f'(x) = \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x}$$

provided the limit exists.

Remark 3.26 1. If f' is defined at a point, we say that f is differentiable at x .

2. If f' is defined at every point of a set $E \subset [a, b]$, we say that f is differentiable on E .

Theorem 3.27 Let f be defined on $[a, b]$. If f is differentiable at a point x in $[a, b]$, then f is continuous at x .

Proof: Given f is differentiable at x . (i.e.)

$$f'(x) = \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} \text{ exists.}$$

To Prove: f is continuous at x (i.e.) To Prove

$$\lim_{t \rightarrow x} f(t) = f(x)$$

Now

$$\begin{aligned} f(t) - f(x) &= \frac{f(t) - f(x)}{t - x} (t - x) \\ \lim_{t \rightarrow x} (f(t) - f(x)) &= \lim_{t \rightarrow x} \left[\frac{f(t) - f(x)}{t - x} (t - x) \right] \\ &= \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} \cdot \lim_{t \rightarrow x} (t - x) \\ &= f'(x) \cdot 0 \\ &= 0 \\ \lim_{t \rightarrow x} (f(t) - f(x)) &= 0 \\ \text{(or)} \quad \lim_{t \rightarrow x} f(t) &= f(x) \end{aligned}$$

$\therefore f$ is continuous at x .

Remark 3.28 Converse of above theorem is not true. For example $f(x) = |x|$ is continuous but not differentiable at origin.

Theorem 3.29 Suppose f and g are defined on $[a, b]$ and are differentiable at at point x in $[a, b]$ then $f + g, fg, \frac{f}{g}$ are differentiable at x .

$$(a) \quad (f + g)'(x) = f'(x) + g'(x)$$

$$(b) \quad (fg)'(x) = f'(x)g(x) + f(x)g'(x)$$

$$(c) \quad \left(\frac{f}{g}\right)'(x) = \frac{g(x)f'(x) - g'(x)f(x)}{g^2(x)}, \quad g(x) \neq 0.$$

Proof: Given f and g are differentiable at x .

$$(i.e.) f'(x) = \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} \quad \text{and} \quad g'(x) = \lim_{t \rightarrow x} \frac{g(t) - g(x)}{t - x} \quad \text{exists.}$$

(a)

$$\begin{aligned} \phi(t) &= \frac{(f+g)(t) - (f+g)(x)}{t-x} \\ &= \frac{f(t) + g(t) - (f(x) + g(x))}{t-x} \\ \phi(t) &= \frac{f(t) - f(x)}{t-x} + \frac{g(t) - g(x)}{t-x} \end{aligned}$$

Taking limits as $t \rightarrow x$

$$\begin{aligned} \lim_{t \rightarrow x} \phi(t) &= \lim_{t \rightarrow x} \left\{ \frac{f(t) - f(x)}{t-x} + \frac{g(t) - g(x)}{t-x} \right\} \\ &= \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t-x} + \lim_{t \rightarrow x} \frac{g(t) - g(x)}{t-x} \\ (i.e.) (f+g)'(x) &= f'(x) + g'(x) \end{aligned}$$

(i.e.) $(f+g)$ is differentiable at x .

(b) $(fg)'(x) = f'(x)g(x) + f(x)g'(x)$. Let $h = fg$. Now,

$$\begin{aligned} (h(t) - h(x)) &= (fg)(t) - (fg)(x) \\ &= f(t)g(t) - f(x)g(x) \\ &= f(t)g(t) - f(t)g(x) + f(t)g(x) - f(x)g(x) \\ &= f(t)(g(t) - g(x)) + g(x)(f(t) - f(x)) \\ \frac{h(t) - h(x)}{t-x} &= f(t) \frac{(g(t) - g(x))}{t-x} + g(x) \frac{(f(t) - f(x))}{t-x} \\ \lim_{t \rightarrow x} \frac{h(t) - h(x)}{t-x} &= \lim_{t \rightarrow x} \left\{ f(t) \frac{g(t) - g(x)}{t-x} + g(x) \frac{f(t) - f(x)}{t-x} \right\} \\ &= \lim_{t \rightarrow x} f(t) \lim_{t \rightarrow x} \frac{g(t) - g(x)}{t-x} + \lim_{t \rightarrow x} g(x) \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t-x} \\ h'(x) &= f(x)g'(x) + g(x)f'(x) \\ (fg)'(x) &= f(x)g'(x) + g(x)f'(x) \end{aligned}$$

fg is differentiable at x .

(c) $\left(\frac{f}{g}\right)'(x) = \frac{g(x)f'(x) - g'(x)f(x)}{g^2(x)}$. Let $h = \frac{f}{g}$.

$$\begin{aligned} (h(t) - h(x)) &= \frac{f}{g}(t) - \frac{f}{g}(x) \\ &= \frac{f(t)}{g(t)} - \frac{f(x)}{g(x)} \\ &= \frac{f(t)g(x) - f(x)g(x) + f(x)g(x) - f(x)g(t)}{g(t)g(x)} \\ &= \frac{g(x)(f(t) - f(x)) - f(x)(g(t) - g(x))}{g(t)g(x)} \\ \frac{h(t) - h(x)}{t - x} &= \frac{g(x)(f(t) - f(x)) - f(x)(g(t) - g(x))}{g(t)g(x)(t - x)} \\ \lim_{t \rightarrow x} \frac{h(t) - h(x)}{t - x} &= \lim_{t \rightarrow x} \frac{g(x)}{g(t)g(x)} \left(\frac{f(t) - f(x)}{t - x} \right) - \lim_{t \rightarrow x} \frac{f(x)}{g(t)g(x)} \left(\frac{g(t) - g(x)}{t - x} \right) \\ &= \frac{g(x)}{g^2(x)} \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} - \frac{f(x)}{g^2(x)} \lim_{t \rightarrow x} \frac{g(t) - g(x)}{t - x} \\ h'(x) &= \frac{g(x)f'(x) - g'(x)f(x)}{g^2(x)} \\ \left(\frac{f}{g}\right)'(x) &= \frac{g(x)f'(x) - g'(x)f(x)}{g^2(x)} \end{aligned}$$

Since $f'(x), g'(x)$ exists and $g(x) \neq 0$, $\left(\frac{f}{g}\right)'(x)$ exists.

Example 3.30 (1) The derivative of any constant is zero.

(2) $f(x) = x \Rightarrow f'(x) = 1$

(3) $f(x) = x^n \Rightarrow f'(x) = nx^{n-1}$

Theorem 3.31 Chain Rule: Suppose f is continuous on $[a, b]$, $f'(x)$ exists at some point x in $[a, b]$, g is defined on an interval I which contains the range of f , and g is differentiable at the point $f(x)$. If $h(t) = g(f(t))$, $a \leq t \leq b$ then h is differentiable at x , and $h'(x) = g'(f(x))f'(x)$.

Proof: Given

$$f'(x) = \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} \text{ exists, } t \in [a, b].$$

Let $h(t) = g(f(t))$. To Prove: $h'(x) = g'(f(x))f'(x)$. Since f is differentiable at $x \in [a, b]$

$$\begin{aligned} f'(x) &= \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} \text{ exists, } t \in [a, b] \text{ exists.} \\ (\text{i.e.}) f'(x) + u(t) &= \frac{f(t) - f(x)}{t - x}, t \in [a, b] \text{ where } \lim_{t \rightarrow x} u(t) = 0 \\ \Rightarrow (f'(x) + u(t))(t - x) &= f(t) - f(x) \dots (1) \end{aligned}$$

Let $y = f(x)$. Now g is differentiable at $y (= f(x))$

$$g'(y) = \lim_{s \rightarrow y} \frac{g(s) - g(y)}{s - y}, s \in I$$

$$(i.e.) g'(y) + v(s) = \frac{g(s) - g(y)}{s - y}, s \in I \text{ where } \lim_{s \rightarrow y} v(s) = 0$$

$$(g'(y) + v(s))(s - y) = g(s) - g(y) \dots \dots (2)$$

Let $s = f(t)$. Now,

$$\begin{aligned} h(t) - h(x) &= g(f(t)) - g(f(x)) \\ &= (g'(f(x)) + v(s))(s - y) \text{ (by(2))} \end{aligned}$$

$$\begin{aligned} h(t) - h(x) &= g'(f(x) + v(s))(f(t) - f(x)) \\ &= g'(f(x) + v(s))(f'(x) + u(t))(t - x) \text{ (by(1))} \end{aligned}$$

$$\frac{h(t) - h(x)}{t - x} = g'(f(x) + v(s))(f'(x) + u(t))$$

$$\lim_{t \rightarrow x} \frac{h(t) - h(x)}{t - x} = \lim_{t \rightarrow x} \{g'(f(x) + v(s))(f'(x) + u(t))\}$$

$$h'(x) = \lim_{t \rightarrow x} g'(f(x) + v(s)) \lim_{t \rightarrow x} (f'(x) + u(t))$$

$$= \lim_{s \rightarrow y} (g'(f(x)) + v(s)) f'(x)$$

$$= g'(f(x)) f'(x)$$

$$\therefore h'(x) = g'(f(x)) f'(x)$$

Example 3.32 Let

$$f(x) = \begin{cases} x \sin \frac{1}{x} & x \neq 0 \\ 0 & x = 0 \end{cases}$$

Find $f'(x)$ ($x \neq 0$), and show that $f'(0)$ does not exist.

Solution:

$$f(x) = x \sin \frac{1}{x}$$

$$f'(x) = x \cos \left(\frac{1}{x} \right) \left(\frac{-1}{x^2} \right) + \sin \left(\frac{1}{x} \right)$$

$$= -\frac{1}{x} \cos \left(\frac{1}{x} \right) + \sin \left(\frac{1}{x} \right)$$

$$= \sin \left(\frac{1}{x} \right) - \left(\frac{1}{x} \right) \cos \left(\frac{1}{x} \right), x \neq 0.$$

since $x \neq 0$ $f'(x)$ exists. To Prove: $f'(0)$ does not exist.

$$\begin{aligned} f'(0) &= \lim_{t \rightarrow 0} \frac{f(t) - f(0)}{t - 0} \\ &= \lim_{t \rightarrow 0} \frac{t \sin \frac{1}{t} - 0}{t - 0} \\ &= \lim_{t \rightarrow 0} \sin \frac{1}{t} \text{ which does not exist.} \end{aligned}$$

$\therefore f'(0)$ does not exist.

Example 3.33 Let

$$f(x) = \begin{cases} x^2 \sin \frac{1}{x} & x \neq 0 \\ 0 & x = 0 \end{cases}$$

Find $f'(x)$ ($x \neq 0$), show that $f'(0) = 0$

Solution: Let

$$\begin{aligned} f(x) &= x^2 \sin \frac{1}{x} \\ f'(x) &= x^2 \left(\cos \left(\frac{1}{x} \right) \right) \left(\frac{-1}{x^2} \right) + 2x \cdot \sin \frac{1}{x} \\ &= 2x \cdot \sin \frac{1}{x} - \cos \frac{1}{x}, x \neq 0 \\ f'(0) &= \lim_{t \rightarrow 0} \frac{f(t) - f(0)}{t - 0} \\ &= \lim_{t \rightarrow 0} \frac{x^2 \sin \frac{1}{t} - 0}{t - 0} \\ &= \lim_{t \rightarrow 0} t \sin \frac{1}{t} \\ &= 0 \left(\because \left| t \sin \frac{1}{t} \right| \leq 1 \right) \end{aligned}$$

$$\therefore f'(0) = 0$$

Mean Value Theorems:

Definition 3.34 Local Maximum, Local Minimum: Let f be a real function defined on a metric space X . We say that f has local maximum at a point p in X if there exists $\delta > 0$ such that $f(q) \leq f(p) \forall q \in X$ with $d(p, q) < \delta$. f has a local minimum at p in X , if $f(p) \leq f(q) \forall q \in X$ such that $d(p, q) < \delta$.

Theorem 3.35 Let f be defined on $[a, b]$; if f has a local maximum at a point $x \in (a, b)$ and if f' exists, then $f'(x) = 0$. The analogous statement for local minimum is also true.

Proof: Case (i) Assume that f has local maximum at x . To Prove: $f'(x) =$

0. Since f has local maximum at x , there exists $\delta > 0$ such that $(q, x) < \delta \Rightarrow f(q) \leq f(x)$

$$\begin{aligned} \text{If } x - \delta < t < x \text{ then } \frac{f(t) - f(x)}{t - x} &\geq 0 \\ \Rightarrow \lim_{t \rightarrow x} \frac{h(t) - h(x)}{t - x} &\geq 0 \\ \text{(i.e.) } f'(x) &\geq 0 \dots\dots(1) \end{aligned}$$

$$\begin{aligned} \text{If } t^x < x^t < x + \delta \text{ then } \frac{f(t) - f(x)}{t - x} &\leq 0 \\ \Rightarrow \lim_{t \rightarrow x} \frac{h(t) - h(x)}{t - x} &\leq 0 \\ \Rightarrow f'(x) &\leq 0 \dots\dots(2) \end{aligned}$$

Since $f'(x)$ exists, (1),(2) $\Rightarrow f'(x) = 0$.

Case(ii) Assume that f has a local minimum at x . We show that $f'(x)=0$. Then there exists $\delta > 0$ such that $d(q, x) < \delta \Rightarrow f(q) \geq f(x)$

$$\begin{aligned} \text{If } x - \delta < t < x \text{ then } \frac{f(t) - f(x)}{t - x} &\leq 0 \\ \Rightarrow \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} &\leq 0 \\ \text{(i.e.) } f'(x) &\leq 0 \dots\dots(3) \end{aligned}$$

$$\begin{aligned} \text{If } x < t < x + \delta \text{ then } \frac{f(t) - f(x)}{t - x} &\geq 0 \\ \Rightarrow \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} &\geq 0 \\ \Rightarrow f'(x) &\geq 0 \dots\dots(4) \end{aligned}$$

Since $f'(x)$ exists, and from (3) and (4) we get $f'(x)=0$.

Theorem 3.36 Generalised Mean Value Theorem: *If f and g are continuous real functions on $[a, b]$, which are differentiable in (a, b) , then there is a point $x \in (a, b)$ at which $[f(b) - f(a)]g'(x) = [g(b) - g(a)]f'(x)$.*

proof: Let $h(t) = [f(b) - f(a)]g(t) - [g(b) - g(a)]f(t)$, $t \in [a, b]$. Since f and g are differentiable in (a, b) , $h(t)$ is also differentiable in (a, b) . Now,

$$\begin{aligned} h(a) &= [f(b) - f(a)]g(a) - [g(b) - g(a)]f(a) \\ &= f(b)g(a) - f(a)g(a) - g(b)f(a) + g(a)f(a) \\ &= f(b)g(a) - g(b)f(a) \\ h(b) &= [f(b) - f(a)]g(b) - [g(b) - g(a)]f(b) \\ &= f(b)g(b) - f(a)g(b) - g(b)f(b) + g(a)f(b) \\ &= g(a)f(b) - f(a)g(b) \end{aligned}$$

Claim: $h'(x) = 0$ for some $x \in (a, b)$. If $h(t)$ is a constant then $h'(x) = 0 \forall x \in (a, b)$. If $h(t) < h(a), a < t < b$, then by Intermediate value theorem, there exists x in (a, b) at which h is minimum. $\therefore h'(x) = 0$ (by Theorem 3.35). If $h(t) > h(a)$ then h attains its maximum at some point $x \in (a, b)$. $\therefore h'(x) = 0$ (by Theorem 3.35) (i.e.)

$$\begin{aligned}(f(b) - f(a))g'(x) - (g(b) - g(a))f'(x) &= 0 \\ (f(b) - f(a))g'(x) &= (g(b) - g(a))f'(x)\end{aligned}$$

Theorem 3.37 Mean Value Theorem: If f is a real continuous function on $[a, b]$ which is differentiable at (a, b) then there is a point $x \in (a, b)$ at which $f(b) - f(a) = (b - a)f'(x)$.

Proof: Put $g(x) = x$ in theorem 3.36. $\therefore g'(x) = 1 \Rightarrow (f(b) - f(a)) = (b - a)f'(x)$.

Theorem 3.38 Suppose f is differentiable in (a, b) .

- (a) If $f'(x) \geq 0 \forall x \in (a, b)$, then f is monotonically increasing.
- (b) If $f'(x) = 0 \forall x \in (a, b)$, then f is a constant.
- (c) If $f'(x) \leq 0 \forall x \in (a, b)$, then f is monotonically decreasing.

Proof: (a) By theorem 3.37, If $x_1 < x_2$, then there exists $x_1 < x < x_2$ such that $f(x_2) - f(x_1) = (x_2 - x_1)f'(x)$ (1)

If $f'(x) \geq 0$ then (1) $\Rightarrow f(x_2) - f(x_1) \geq 0$ ($\because (x_2 - x_1)f'(x) \geq 0$) $\Rightarrow f(x_1) \leq f(x_2)$ (i.e.) f is an increasing function

(b) If $f'(x) = 0$ then (1) $\Rightarrow f(x_2) - f(x_1) = 0 \Rightarrow f(x_2) = f(x_1)$. $\therefore f$ is constant.

(c) If $f'(x) \leq 0$ then (1) $\Rightarrow f(x_2) - f(x_1) \leq 0 \Rightarrow f(x_1) \geq f(x_2)$. $\therefore f$ is an decreasing function.

The Continuity Of Derivatives

Theorem 3.39 Suppose f is a real differentiable function on $[a, b]$ and suppose $f'(a) < \lambda < f'(b)$, then there is a point $x \in (a, b)$ such that $f'(x) = \lambda$. A similar result holds if $f'(a) > \lambda > f'(b)$.

Proof: Let $g(t) = f(t) - \lambda t, t \in [a, b]$ then, $g'(t) = f'(t) - \lambda; g'(a) = f'(a) - \lambda < 0$. \therefore there exists $a < t_1 < b$ such that $g(t_1) < g(a)$. Also, $g'(b) = f'(b) - \lambda > 0$. \therefore there exists $a < t_2 < b$ such that $g(t_2) < g(b)$. $\therefore g$ attains minimum at $x \in (a, b)$. $\therefore g'(x) = 0$ (by Theorem 3.35) (i.e.) $f'(x) - \lambda = 0 \Rightarrow f'(x) = \lambda$.

Corollary 3.40 If f is differentiable on $[a, b]$, then f' is cannot have any simple discontinuity on $[a, b]$. But f' may have discontinuity of second kind.

Proof: f' takes every value between $f'(a)$ and $f'(b)$. Let $a < x < b$. If f' is not continuous at x , then

1. $f'(x+), f'(x-)$ exists,

2. $f'(x+) \neq f'(x-)$,
3. $f'(x-) = f'(x+) \neq f'(x) \Rightarrow \Leftarrow$

$\therefore f'$ cannot have any simple discontinuity. In Example **3.33** f' has a discontinuity of second kind at $x \in [a, b]$.

Theorem 3.41 L'Hospital's Rule: Suppose f and g are differentiable in (a, b) and $g'(x) \neq 0 \forall x \in (a, b)$ where $-\infty \leq a < b \leq \infty$. Suppose $\frac{f'(x)}{g'(x)} \rightarrow A$ as $x \rightarrow a \dots \dots$ (1).

If $f(x) \rightarrow 0$ and $g(x) \rightarrow 0$ as $x \rightarrow a \dots \dots$ (2) (or) if $g(x) \rightarrow \infty$ as $x \rightarrow a \dots \dots$ (3), then $\frac{f(x)}{g(x)} \rightarrow A$ as $x \rightarrow a \dots \dots$ (4). (The analogous statement is true if $x \rightarrow b$ (or) if $g(x) \rightarrow -\infty$ in (3)).

Proof: Case(i): Let $-\infty \leq A < \infty$. We choose r and q such that $A < r < q$. Given

$$\lim_{x \rightarrow a} \frac{f'(x)}{g'(x)} = A$$

Then there exists $c \in (a, b)$ such that $a < x < c \Rightarrow \frac{f'(x)}{g'(x)} < r \dots \dots$ (i)

Now if $a < x < y < c$ then by generalised mean value theorem, there exists $t \in (a, b)$ such that $\frac{f(x)-f(y)}{g(x)-g(y)} = \frac{f'(t)}{g'(t)} < r \dots \dots$ (ii)

Suppose $f(x) \rightarrow 0$ and $g(x) \rightarrow 0$ as $x \rightarrow a$. Then by taking limits as $x \rightarrow a$, then (ii) we get $\frac{f(y)}{g(y)} \leq r < q \dots \dots$ (iii)

Suppose $g(x) \rightarrow \infty$ as $x \rightarrow a$, then by keeping y fixed in (ii) we can find $c_1 \in (a, y)$ such that $g(x) > g(y)$ and $g(x) > 0 \forall x \in (a, c_1)$. Multiply (ii) by $\frac{g(x)-g(y)}{g(x)}$, we get

$$\begin{aligned} \frac{f(x) - f(y)}{g(x)} &< r \left(\frac{g(x) - g(y)}{g(x)} \right) \\ \Rightarrow \frac{f(x)}{g(x)} - \frac{f(y)}{g(x)} &< r \left(1 - \frac{g(y)}{g(x)} \right) \\ \Rightarrow \frac{f(x)}{g(x)} &< r - r \frac{g(y)}{g(x)} + \frac{f(y)}{g(x)} \end{aligned}$$

Since $g(x) \rightarrow \infty$ as $x \rightarrow a$, there exists $c_2 \in (a, c_1)$ such that $\frac{f(x)}{g(x)} < r \forall x \in (a, c_2)$ (or) $\frac{f(x)}{g(x)} < q \forall x \in (a, c_2) \dots \dots$ (iv)

suppose $-\infty < A \leq \infty$. By choosing $p < A$ as above, we can show that there exists $c_3 \in (a, b)$ such that $p < \frac{f(x)}{g(x)} \forall a < x < c_3 \dots \dots$ (v)

Thus in all cases $\frac{f(x)}{g(x)} \rightarrow A$ as $x \rightarrow a$. Hence

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$$

Derivatives Of Higher Order

Definition 3.42 If f has a derivative f' on an interval and if f' is differentiable, we see the second derivative f'' exists. Similarly if $f^{(n-1)}(x)$ is differentiable we say $f^{(n)}$ exists.

Theorem 3.43 Taylor's Theorem: Suppose f is a real function on $[a, b]$, n is a positive integer, $f^{(n-1)}$ is continuous on $[a, b]$, $f^{(n)}(t)$ exists $\forall t \in (a, b)$. Let α, β be distinct points of $[a, b]$ and define

$$p(t) = \sum_{k=0}^{n-1} \frac{f^{(k)}(\alpha)}{k!} (t - \alpha)^k,$$

then there exists a point $x \in (\alpha, \beta)$ such that $f(\beta) = p(\beta) + \frac{f^{(n)}(x)}{n!} (\beta - \alpha)^n$.

Proof: If $n=1$, then $f(\beta) = f(\alpha) + f'(\alpha)(\beta - \alpha)$; $\frac{f(\beta)-f(\alpha)}{\beta-\alpha} = f'(\alpha)$. This is just the mean value theorem. Suppose $n > 1$. Define a number M such that $f(\beta) = p(\beta) + M(\beta - \alpha)^n$(1)

Let $g(t) = f(t) - p(t) - M(t - \alpha)^n$ (2)

Now,

$$\begin{aligned} g(\alpha) &= f(\alpha) - p(\alpha) - M(\alpha - \alpha)^n \\ &= f(\alpha) - p(\alpha) \\ g(\alpha) &= f(\alpha) - f(\alpha) (\because p(\alpha) = f(\alpha)) \\ &= 0 \end{aligned}$$

$$\begin{aligned} g(\beta) &= f(\beta) - p(\beta) - M(\beta - \alpha)^n \\ &= 0 \text{ (by (1))}.....(4) \end{aligned}$$

$$\text{Also } g^{(n)}(t) = f^{(n)}(t) - 0 - Mn!.....(5)$$

$$\begin{aligned} g^{(k)}(\alpha) &= f^{(k)}(\alpha) - p^{(k)}(\alpha) \\ &= f^{(k)}(\alpha) - f^{(k)}(\alpha) \\ &= 0.....(6) \end{aligned}$$

(i.e.) $g(\alpha) = g'(\alpha) = \dots = g^{(n-1)}(\alpha) = 0$. Since $g(\alpha) = 0$ and $g(\beta) = 0$, there exists $x_1 \in (\alpha, \beta)$, by mean value theorem, such that $g'(x_1) = 0$. Now since $g'(\alpha) = 0$; $g'(x_1) = 0$ again by mean value theorem there exists $x_2 \in (\alpha, x_1)$ such that $g''(x_2) = 0$. Proceeding this way we get $\alpha < x_n < x_{n-1}$, such that $g^{(n)}(x_n) = 0$ (i.e.) $f^{(n)}(x_n) - Mn! = 0$ (by (5)). $\therefore M = \frac{f^{(n)}(x_n)}{n!}$, sub M in (1) $\Rightarrow f(\beta) = p(\beta) + \frac{f^{(n)}(x_n)}{n!} (\beta - \alpha)^n, \forall x \in (\alpha, x_{n-1})$

UNIT V

RIEMANN INTEGRAL AND POINTWISE CONVERGENCE

The Riemann-Steiltjes integral and Sequences and series of functions

Definition 4.1 Let $[a, b]$ be an interval. By a partition P of $[a, b]$ we mean a finite set of points x_0, x_1, \dots, x_n , where $a = x_0 \leq x_1 \leq \dots \leq x_{i-1} \leq x_i \leq \dots \leq x_n = b$.

Remark 4.2 1. $\Delta x_i = x_i - x_{i-1} \forall i = 1, 2, \dots, n$.

2. Let f be a bounded real function on $[a, b]$ then $m_i = \inf f(x), M_i = \sup f(x) \forall x_{i-1} \leq x \leq x_i$.

3.

$$L(P, f) = \sum_{i=1}^n m_i \Delta x_i$$

$$U(P, f) = \sum_{i=1}^n M_i \Delta x_i$$

$$L(P, f) \leq \int_a^b f(x) dx \leq U(P, f)$$

$$L(P, f) \leq U(P, f).$$

4. $\int_a^b f(x) dx = \sup L(P, f)$

5. $\int_a^{\bar{b}} f(x) dx = \inf U(P, f)$ (The inf and sup are taken over all partition P of $[a, b]$).

6. If the upper and lower reimann interval over is same then f is said to be Reimann integrable over $[a, b]$. $f \in \mathcal{R}$ (\mathcal{R} is the set of all Reimann integrable functions)

7.

$$\int_a^b f(x) dx = \int_a^{\bar{b}} f(x) dx = \int_a^b f(x) dx$$

Result 4.3 For every partition P of $[a, b]$ and every bounded function f there exists 2 real numbers m, M such that $m(b - a) \leq L(P, f) \leq U(P, f) \leq M(b - a)$.

Solution: Let $m = \inf f(x)$ and $M = \sup f(x), a \leq x \leq b$. Let $P =$

$\{x_0, x_1, \dots, x_n\}$ be the given partition of $[a, b]$,

$$\begin{aligned}
 m &\leq m_i \leq M_i \leq M \\
 m\Delta x_i &\leq m_i\Delta x_i \leq M_i\Delta x_i \leq M\Delta x_i \quad (\Delta x_i \geq 0) \\
 \sum_{i=1}^n m\Delta x_i &\leq \sum_{i=1}^n m_i\Delta x_i \leq \sum_{i=1}^n M_i\Delta x_i \leq \sum_{i=1}^n M\Delta x_i \\
 m\left(\sum_{i=1}^n \Delta x_i\right) &\leq L(P, f) \leq U(P, f) \leq M\sum_{i=1}^n \Delta x_i \dots\dots\dots(1)
 \end{aligned}$$

Now, $\sum_{i=1}^n \Delta x_i = \Delta x_1 + \Delta x_2 + \dots + \Delta x_n$

$$\begin{aligned}
 &= (x_1 - x_0) + (x_2 - x_1) + \dots + (x_n - x_{n-1}) \\
 &= x_n - x_0 \\
 &= b - a \dots\dots\dots(2)
 \end{aligned}$$

sub (2) in (1) we get, $m(b - a) \leq L(P, f) \leq U(P, f) \leq M(b - a)$.

Definition 4.4 Let α be a monotonically increasing function on $[a, b]$. Corresponding to each partition P of $[a, b]$ we define $\Delta\alpha_i = \alpha(x_i) - \alpha(x_{i-1})$. Clearly, $\Delta\alpha_i \geq 0$

$$\begin{aligned}
 L(P, f, \alpha) &= \sum_{i=1}^n m_i \Delta\alpha_i \\
 U(P, f, \alpha) &= \sum_{i=1}^n M_i \Delta\alpha_i \\
 \sup L(P, f, \alpha) &= \int_a^b f d\alpha \\
 U(P, f, \alpha) &= \int_a^{\bar{b}} f d\alpha
 \end{aligned}$$

where infimum and supremum are taken over all partitions. If

$$\int_a^b f d\alpha = \int_a^{\bar{b}} f d\alpha,$$

then f is Riemann Stieljes integrable with respect to,

$$\int_a^b f d\alpha = \int_a^b f d\alpha = \int_a^{\bar{b}} f d\alpha,$$

we also write $f \in \mathcal{R}(\alpha)$.

Note 4.5 By taking $\alpha(x) = x$, we see that the Riemann integral is the special case of Riemann's Stieltjes integral.

Definition 4.6 The partition P^* of $[a, b]$ is called a refinement of P if $P \subset P^*$. Given two partition P_1 and P_2 , we say that $P = P_1 \cup P_2$ is the common refinement of P_1 and P_2 .

Theorem 4.7 If P^* is an refinement of P , then $L(P, f, \alpha) \leq L(P^*, f, \alpha)$ and $U(P^*, f, \alpha) \leq U(P, f, \alpha)$.

Proof: Let $P = \{x_0, x_1, \dots, x_{i-1}, x_i, \dots, x_n\}$ be a partition of $[a, b]$ and let $P^* = \{x_0, x_1, x_2, \dots, x_{i-1}, x^*, x_i, \dots, x_n\}$ be an refinement of P . Let

$$\begin{aligned} m_i &= \inf f(x), \quad x_{i-1} \leq x \leq x_i \\ w_1 &= \inf f(x), \quad x_{i-1} \leq x \leq x^* \\ w_2 &= \inf f(x), \quad x^* \leq x \leq x_i \end{aligned}$$

$\therefore w_1 \geq m_i$ and $w_2 \geq m_i$. Now,

$$\begin{aligned} L(P^*, f, \alpha) &= m_1 \Delta \alpha_1 + m_2 \Delta \alpha_2 + \dots + m_{i-1} \Delta \alpha_{i-1} + w_1(\alpha(x^*) - \alpha(x_{i-1})) \\ &\quad + w_2(\alpha(x_i) - \alpha(x^*)) + m_{i+1} \Delta \alpha_{i+1} \dots + m_n \Delta \alpha_n \dots \dots (1) \end{aligned}$$

$$\begin{aligned} L(P, f, \alpha) &= m_1 \Delta \alpha_1 + m_2 \Delta \alpha_2 + \dots + m_{i-1} \Delta \alpha_{i-1} + m_i \Delta \alpha_i \\ &\quad + m_{i+1}(\Delta \alpha_{i+1}) + \dots + m_n \Delta \alpha_n \dots \dots (2) \end{aligned}$$

(1)-(2) \Rightarrow

$$\begin{aligned} L(P^*, f, \alpha) - L(P, f, \alpha) &= w_1(\alpha(x^*) - \alpha(x_{i-1})) + w_2(\alpha(x_i) - \alpha(x^*)) - m_i \Delta \alpha_i \\ &= w_1(\alpha(x^*) - \alpha(x_{i-1})) + w_2(\alpha(x_i) - \alpha(x^*)) \\ &\quad - m_i(\alpha(x_i) - \alpha(x_{i-1})) \\ &= w_1(\alpha(x^*) - \alpha(x_{i-1})) + w_2(\alpha(x_i) - \alpha(x^*)) \\ &\quad - m_i(\alpha(x_i) - \alpha(x^*)) - m_i(\alpha(x^*) - \alpha(x_{i-1})) \\ &= (w_1 - m_i)(\alpha(x^*) - \alpha(x_{i-1})) \\ &\quad + (w_2 - m_i)(\alpha(x_i) - \alpha(x^*)) \\ &\geq 0 (\because w_1 \text{ and } w_2 \geq m_i) \end{aligned}$$

$$\begin{aligned} L(P^*, f, \alpha) - L(P, f, \alpha) &\geq 0 \\ \Rightarrow L(P, f, \alpha) &\leq L(P^*, f, \alpha) \\ \therefore L(P, f, \alpha) &\leq L(P^*, f, \alpha) \end{aligned}$$

Let $P^* = \{x_0, x_1, \dots, x_{i-1}, x^*, x_i, \dots, x_n\}$ be refinement of P . Let

$$\begin{aligned} M_i &= \sup f(x), \quad x_{i-1} \leq x \leq x_i \\ w_1 &= \sup f(x), \quad x_{i-1} \leq x \leq x^* \\ w_2 &= \sup f(x), \quad x^* \leq x \leq x_i \\ \therefore w_1 &\geq M_i \text{ and } w_2 \geq M_i \end{aligned}$$

Now

$$U(P^*, f, \alpha) = M_1\Delta\alpha_1 + M_2\Delta\alpha_2 + \dots + M_{i-1}\Delta\alpha_{i-1} + w_1(\alpha(x^*) - \alpha(x_{i-1})) \\ + w_2(\alpha(x_i) - \alpha(x^*)) + M_{i+1}\Delta\alpha_{i+1} + \dots + M_n\Delta\alpha_n \dots \dots (1)$$

$$U(P, f, \alpha) = M_1\Delta\alpha_1 + M_2\Delta\alpha_2 + \dots + M_{i-1}\Delta\alpha_{i-1} + M_i\Delta\alpha_i \\ + M_{i+1}(\Delta\alpha_{i+1}) + \dots + M_n\Delta\alpha_n \dots \dots (2)$$

(1)-(2) \Rightarrow

$$U(P^*, f, \alpha) - U(P, f, \alpha) = w_1(\alpha(x^*) - \alpha(x_{i-1})) + w_2(\alpha(x_i) \\ - \alpha(x^*)) - M_i\Delta\alpha_i \\ = w_1(\alpha(x^*) - \alpha(x_{i-1})) + w_2(\alpha(x_i) - \alpha(x^*)) \\ - M_i(\alpha(x_i) - \alpha(x_{i-1})) \\ = w_1(\alpha(x^*) - \alpha(x_{i-1})) + w_2(\alpha(x_i) - \alpha(x^*)) \\ - M_i(\alpha(x_i) - \alpha(x^*)) - M_i(\alpha(x^*) - \alpha(x_{i-1})) \\ = (w_1 - M_i)(\alpha(x^*) - \alpha(x_{i-1})) \\ + (w_2 - M_i)(\alpha(x_i) - \alpha(x^*)) \\ \leq 0 (\because w_1 \text{ and } w_2 \leq M)$$

(i.e.) $U(P^*, f, \alpha) - U(P, f, \alpha) \leq 0$

$$\Rightarrow U(P^*, f, \alpha) \leq U(P, f, \alpha)$$

$$\therefore U(P^*, f, \alpha) \leq U(P, f, \alpha)$$

If P^* contains k -points more than P , we repeat this reasoning k -times and get the result.

Theorem 4.8

$$\int_a^b f d\alpha \leq \int_a^{\bar{b}} f d\alpha.$$

Proof: Let P_1 and P_2 be two partition of $[a, b]$ and let $P^* = P_1 \cup P_2$. (i.e.) P^* is a common refinement of P_1 and P_2 . $L(P_1, f, \alpha) \leq L(P^*, f, \alpha) \leq U(P^*, f, \alpha) \leq U(P_2, f, \alpha) \Rightarrow L(P_1, f, \alpha) \leq U(P_2, f, \alpha)$. Keeping P_1 fixed and taking infimum over all partition P_2 , we get

$$L(P, f, \alpha) \leq \int_a^{\bar{b}} f d\alpha.$$

Now, by taking supremum over all partition P_1 we get

$$\int_a^b f d\alpha \leq \int_a^{\bar{b}} f d\alpha.$$

Theorem 4.9 Criterion for Riemann Integrability: Let $f \in \mathcal{R}(\alpha)$ iff $\forall \epsilon > 0$, there exists a partition P such that $U(P, f, \alpha) - L(P, f, \alpha) < \epsilon$.

Proof: Let $\epsilon > 0$, there exists a partition P such that $U(P, f, \alpha) - L(P, f, \alpha) < \epsilon$
 Claim: $f \in \mathcal{R}(\alpha)$. We know that

$$U(P, f, \alpha) \geq \int_a^{\bar{b}} f d\alpha \dots (1)$$

$$L(P, f, \alpha) \leq \int_{\underline{a}}^b f d\alpha \dots (2)$$

$$(2) \times -1 \Rightarrow -L(P, f, \alpha) \geq -\int_{\underline{a}}^b f d\alpha \dots (3)$$

$$(1) + (3) \quad U(P, f, \alpha) - L(P, f, \alpha) \geq \int_a^{\bar{b}} f d\alpha - \int_{\underline{a}}^b f d\alpha$$

$$(or) \quad \int_a^{\bar{b}} f d\alpha - \int_{\underline{a}}^b f d\alpha \leq U(P, f, \alpha) - L(P, f, \alpha) < \epsilon$$

Since ϵ is arbitrary,

$$\int_{\underline{a}}^b f d\alpha = \int_a^{\bar{b}} f d\alpha. (i.e.) \quad f \in \mathcal{R}(\alpha).$$

Conversely: Assume $f \in \mathcal{R}(\alpha)$. To Prove: let $\epsilon > 0$, there exists a partition P such that $U(P, f, \alpha) - L(P, f, \alpha) < \epsilon$

let $\epsilon > 0$ be given

Then there exists two partition P_1 and P_2 such that

$$U(P_1, f, \alpha) < \int_a^b f d\alpha + \frac{\epsilon}{2} \dots (4) \quad \text{and} \quad \int_a^b f d\alpha - \frac{\epsilon}{2} < L(P_2, f, \alpha) \dots (5)$$

Let $P = P_1 P_2$ (i.e.) P is the common refinement of P_1 and P_2

Now

$$\begin{aligned} U(P, f, \alpha) &\leq U(P_1, f, \alpha) \\ &\leq \int_a^b f d\alpha + \frac{\epsilon}{2} \quad (\text{by (4)}) \\ &< L(P_2, f, \alpha) + \frac{\epsilon}{2} + \frac{\epsilon}{2} \quad (\text{by (5)}) \\ &= L(P_2, f, \alpha) + \epsilon \\ &\leq L(P, f, \alpha) + \epsilon \end{aligned}$$

$$\therefore U(P, f, \alpha) - L(P, f, \alpha) < \epsilon$$

Theorem 4.10 Let P be a partition \in : $U(P, f, \alpha) - L(P, f, \alpha) < \epsilon \dots (1)$

(a) if (1) holds for some P and ϵ then (1) holds for every refinement of P .

(b) if (1) holds for $P = \{x_0, x_1, \dots, x_n\}$ and s_i, t_i are arbitrary points in $[x_{i-1}, x_i]$ then

$$\sum_{i=1}^n |f(s_i) - f(t_i)| \Delta \alpha_i < \epsilon$$

(c) if $f \in \mathcal{R}(\alpha)$ and the hypothesis of (b) holds then

$$\left| \sum_{i=1}^n f(t_i) \Delta \alpha_i - \int_a^b f d\alpha \right| < \epsilon.$$

Proof: (a) Let P^* be a refinement of P . We know that

$$U(P^*, f, \alpha) \leq U(P, f, \alpha) \dots (2)$$

$$L(P^*, f, \alpha) \leq L(P, f, \alpha) \text{ (by Theorem 4.7)}$$

$$-L(P^*, f, \alpha) \leq -L(P, f, \alpha) \dots (3)$$

(2)+(3) gives

$$\begin{aligned} U(P^*, f, \alpha) - L(P^*, f, \alpha) &\leq U(P, f, \alpha) - L(P, f, \alpha) \\ &< \epsilon \text{ (by (1))} \end{aligned}$$

$$(i.e.) U(P^*, f, \alpha) - L(P^*, f, \alpha) < \epsilon$$

(b) $s_i, t_i \in [x_{i-1}, x_i]$; $f(s_i), f(t_i) \in f[x_{i-1}, x_i]$; $m_i \leq f(s_i), f(t_i) \leq M_i$

$$\therefore |f(s_i) - f(t_i)| \leq M_i - m_i \text{ } (\because M_i - m_i \geq 0)$$

$$\Rightarrow |f(s_i) - f(t_i)| \Delta \alpha_i \leq (M_i - m_i) \Delta \alpha_i$$

$$\begin{aligned} \Rightarrow \sum_{i=1}^n |f(s_i) - f(t_i)| \Delta \alpha_i &= \sum_{i=1}^n (M_i - m_i) \Delta \alpha_i \\ &= \sum_{i=1}^n M_i \Delta \alpha_i - \sum_{i=1}^n m_i \Delta \alpha_i \\ &= U(P, f, \alpha) - L(P, f, \alpha) \text{ (by (1))} \end{aligned}$$

$$\therefore \sum_{i=1}^n |f(s_i) - f(t_i)| \Delta \alpha_i < \epsilon.$$

(c) We have

$$m_i \leq f(t_i) \leq M_i$$

$$\Rightarrow m_i \Delta \alpha_i \leq f(t_i) \Delta \alpha_i \leq M_i \Delta \alpha_i$$

$$\Rightarrow \sum_{i=1}^n m_i \Delta \alpha_i \leq \sum_{i=1}^n f(t_i) \Delta \alpha_i \leq \sum_{i=1}^n M_i \Delta \alpha_i$$

$$\Rightarrow L(P, f, \alpha) \leq \sum_{i=1}^n f(t_i) \Delta \alpha_i \leq U(P, f, \alpha) \dots (4)$$

$$L(P, f, \alpha) \leq \int_a^b f d\alpha \leq U(P, f, \alpha) \dots (5)$$

(4) and (5) \Rightarrow

$$\begin{aligned} \left| \sum_{i=1}^n f(t_i) \Delta \alpha_i - \int_a^b f d\alpha \right| &\leq U(P, f, \alpha) - L(P, f, \alpha) \\ &= \epsilon \text{ (by (1))} \\ \left| \sum_{i=1}^n f(t_i) \Delta \alpha_i - \int_a^b f d\alpha \right| &< \epsilon. \end{aligned}$$

Theorem 4.11 *If f is continuous on $[a, b]$ then $f \in \mathcal{R}(\alpha)$.*

Proof: Let $\epsilon > 0$ be given. Choose $\eta > 0$ such that $[\alpha(b) - \alpha(a)]\eta < \epsilon \dots (1)$

Since f is continuous on $[a, b]$ and $[a, b]$ is compact, f is uniformly continuous.

Then there exists $\delta > 0$ such that $|x - \epsilon| < \delta \Rightarrow |f(x) - f(\epsilon)| < \eta \dots (2)$

Let $P = \{x_0, x_1, \dots, x_n\}$ be a partition of $[a, b]$ such that $\Delta x_i < \delta \therefore (2)$ guarantees that $|M_i - m_i| < \eta$ (i.e.) $M_i - m_i < \eta \dots (3)$

Now,

$$\begin{aligned} U(P, f, \alpha) - L(P, f, \alpha) &= \sum_{i=1}^n M_i \Delta \alpha_i - \sum_{i=1}^n m_i \Delta \alpha_i \\ &= \sum_{i=1}^n (M_i - m_i) \Delta \alpha_i \\ &< \eta \left(\sum_{i=1}^n \Delta \alpha_i \right) \text{ (by (3))} \\ &= \eta [\Delta \alpha_1 + \Delta \alpha_2 + \dots + \Delta \alpha_n] \\ &= \eta [(\alpha(x_1) - \alpha(x_0)) + (\alpha(x_2) - \alpha(x_1)) + \dots + (\alpha(x_n) - \alpha(x_{n-1}))] \\ &= \eta (\alpha(x_n) - \alpha(x_0)) \\ &= \eta [\alpha(b) - \alpha(a)] \\ &< \epsilon \end{aligned}$$

$\therefore U(P, f, \alpha) - L(P, f, \alpha) < \epsilon$ (by Theorem [4.9](#))

By Theorem [4.9](#), $f \in \mathcal{R}(\alpha)$.

Theorem 4.12 *If f is monotonic on $[a, b]$ and if α is continuous in $[a, b]$, then $f \in \mathcal{R}(\alpha)$.*

Proof: Let

$\epsilonpsilon > 0$ be given. For every positive integer n , we choose a partition P such that $\Delta \alpha_i = \frac{\alpha(b) - \alpha(a)}{n}$. This is possible since α is continuous.

Case(i): f is monotonic increasing. $\therefore M_i = f(x_i); m_i = f(x_{i-1}) \forall i =$

1, 2, ..., n. Now,

$$\begin{aligned}
U(P, f, \alpha) - L(P, f, \alpha) &= \sum_{i=1}^n M_i \Delta \alpha_i - \sum_{i=1}^n m_i \Delta \alpha_i \\
&= \sum_{i=1}^n (M_i \Delta \alpha_i - m_i \Delta \alpha_i) \\
&= \sum_{i=1}^n (M_i - m_i) \Delta \alpha_i \\
&= \sum_{i=1}^n (f(x_i) - f(x_{i-1})) \left(\frac{\alpha(b) - \alpha(a)}{n} \right) \\
&= \frac{\alpha(b) - \alpha(a)}{n} \sum_{i=1}^n [f(x_i) - f(x_{i-1})] \\
&= \frac{\alpha(b) - \alpha(a)}{n} \{ (f(x_1) - f(x_0)) + (f(x_2) - f(x_1)) + \dots \\
&\quad + (f(x_n) - f(x_{n-1})) \} \\
&= \frac{\alpha(b) - \alpha(a)}{n} [f(x_n) - f(x_0)] \\
&= \frac{\alpha(b) - \alpha(a)}{n} (f(b) - f(a)) \\
&< \epsilon \text{ as } n \rightarrow \infty. \\
\therefore f &\in \mathcal{R}(\alpha).
\end{aligned}$$

Case(ii): f is monotonic decreasing. $\therefore M_i = f(x_i)$; $m_i = f(x_{i-1}) \forall i = 1, 2, \dots, n$. Now,

$$\begin{aligned}
U(P, f, \alpha) - L(P, f, \alpha) &= \sum_{i=1}^n (M_i \Delta \alpha_i - \sum_{i=1}^n m_i \Delta \alpha_i) \\
&= \sum_{i=1}^n (M_i \Delta \alpha_i - m_i \Delta \alpha_i) \\
&= \sum_{i=1}^n (M_i - m_i) \Delta \alpha_i \\
&= \sum_{i=1}^n (f(x_{i-1}) - f(x_i)) \left(\frac{\alpha(b) - \alpha(a)}{n} \right) \\
&= \frac{\alpha(b) - \alpha(a)}{n} \sum_{i=1}^n [f(x_{i-1}) - f(x_i)]
\end{aligned}$$

$$\begin{aligned}
&= \frac{\alpha(b) - \alpha(a)}{n} \{(f(x_0) - f(x_1)) + (f(x_1) - f(x_2)) + \dots \\
&\quad + (f(x_{n-1}) - f(x_n))\} \\
&= \frac{\alpha(b) - \alpha(a)}{n} [f(x_0) - f(x_n)] \\
&= \frac{\alpha(b) - \alpha(a)}{n} (f(a) - f(b)) \\
&< \epsilon \text{ as } n \rightarrow \infty. \\
\therefore f &\in \mathcal{R}(\alpha).
\end{aligned}$$

Hence the proof.

Theorem 4.13 Suppose f is bounded on $[a, b]$, f has only finitely many point of discontinuity on $[a, b]$ and α is continuous at every point at which f is discontinuous, then $f \in \mathcal{R}(\alpha)$.

Proof: Let $\epsilon > 0$ be given. Put $M = \sup|f(x)|$. Let E be the set of points at which f is discontinuous. Since E is finite and α is continuous at every point of E , we can cover E by finitely many disjoint $[u_j, v_j] \subset [a, b]$ such that the sum of the corresponding differences

$$\sum_j [\alpha(v_j) - \alpha(u_j)] < \epsilon.$$

Also we place these intervals in such a way that every point of $E \cap (a, b)$ lies in the interval of some $[u_j, v_j]$. Remove the segments (u_j, v_j) from $[a, b]$. The remaining set K is compact. hence f is uniformly continuous on K . \therefore there exists $\delta > 0$ such that $|s - t| < \delta \Rightarrow |f(s) - f(t)| < \epsilon \quad \forall s, t \in K$. We form a partition $P = \{x_0, x_1, \dots, x_n\}$ of $[a, b]$ as follows. Each u_j occurs in P , each v_j occurs in P . No point of any segment (u_j, v_j) occurs in P . If x_{i-1} is not one of the u_j 's then $\Delta x_i < \delta$. we observe that $M_i - m_i \leq 2\mu, \forall i$ and $M_i - m_i \leq \epsilon$ unless x_{i-1} is one of the u_j 's. $\therefore U(P, f, \alpha) - L(P, f, \alpha) \leq [\alpha(b) - \alpha(a)]\epsilon + 2M\epsilon$. (By Theorem 4.11) Since ϵ is arbitrary, Theorem 4.9 guarantees that $f \in \mathcal{R}(\alpha)$.

Theorem 4.14 Suppose $f \in \mathcal{R}(\alpha)$ on $[a, b], m \leq f \leq M, \phi$ is continuous on $[m, M]$ and $h(x) = \phi(f(x))$ on $[a, b]$, then $h \in \mathcal{R}(\alpha)$ on $[a, b]$.

Proof: Let $\epsilon > 0$ be given. Since $\phi : [m, M] \rightarrow R$ is continuous and $[m, M]$ is compact, ϕ is uniformly continuous. \therefore There exists $\delta > 0$ such that $\delta < \epsilon, |s - t| < \delta \Rightarrow |\phi(s) - \phi(t)| < \epsilon$ for $s, t \in [m, M]$ (1)

Since $f \in \mathcal{R}(\alpha)$, there exists a partition $P = \{x_0, x_1, \dots, x_n\}$ of $[a, b]$ such that $U(P, f, \alpha) - L(P, f, \alpha) < \delta^2$ (2)

To Prove: $h \in \mathcal{R}(\alpha)$. Let $M_i^* = \sup h(x), x_{i-1} \leq x \leq x_i$ and $m_i^* = \inf h(x), x_{i-1} \leq x \leq x_i$. Let $A = \{i | 1 \leq i \leq n, M_i - m_i < \delta\}$; $B =$

$$\{i | 1 \leq i \leq n, M_i - m_i \geq \delta\}$$

$$\text{for } i \in A, |M_i - m_i| < \delta \Rightarrow |\phi(M_i) - \phi(m_i)| < \epsilon \text{ (by (1))}$$

$$\Rightarrow |M_i^* - m_i^*| < \epsilon \dots (3)$$

$$\text{For } i \in B, |M_i^* - m_i^*| \leq |M_i^*| + |m_i^*|$$

$$\leq k + k \text{ where } k = \sup|\phi(t)|, t \in [m, M]$$

$$|M_i^* - m_i^*| \leq 2k \dots (4)$$

$$\text{Also } \delta \sum_{i \in B} \Delta\alpha_i \leq \sum_{i \in B} (M_i - m_i) \Delta\alpha_i$$

$$\leq \sum_{i=1}^n (M_i - m_i) \Delta\alpha_i$$

$$= \sum_{i=1}^n M_i \Delta\alpha_i - \sum_{i=1}^n m_i \Delta\alpha_i$$

$$= U(P, f, \alpha) - L(P, f, \alpha)$$

$$< \delta^2 \text{ (by (2))}$$

$$\text{(i.e.) } \delta \sum_{i \in B} \Delta\alpha_i < \delta^2$$

$$\Rightarrow \sum_{i \in B} \Delta\alpha_i < \delta \dots (5)$$

$$\begin{aligned} \text{Now } U(P, h, \alpha) - L(P, h, \alpha) &= \sum_{i=1}^n M_i^* \Delta\alpha_i - \sum_{i=1}^n m_i^* \Delta\alpha_i \\ &= \sum_{i=1}^n (M_i^* - m_i^*) \Delta\alpha_i \\ &= \sum_{i \in A} (M_i^* - m_i^*) \Delta\alpha_i + \sum_{i \in B} (M_i^* - m_i^*) \Delta\alpha_i \\ &< \epsilon \sum_{i \in A} \Delta\alpha_i + 2k \sum_{i \in B} \Delta\alpha_i \text{ (by (3) and (4))} \\ &< \epsilon \sum_{i=1}^n \Delta\alpha_i + 2k \sum_{i \in B} \Delta\alpha_i \\ &< \epsilon [\alpha(b) - \alpha(a)] + 2k\delta \\ &< \epsilon [\alpha(b) - \alpha(a)] + 2k\epsilon \text{ (}\because \delta < \epsilon\text{)} \\ &= \epsilon [\alpha(b) - \alpha(a) + 2k] \end{aligned}$$

$$\text{(i.e.) } U(P, h, \alpha) - L(P, h, \alpha) < \epsilon [\alpha(b) - \alpha(a) + 2k]$$

since ϵ is arbitrary, Theorem 4.9, implies that $h \in \mathcal{R}(\alpha)$.

Lemma 4.15 *If $f \in \mathcal{R}(\alpha)$ and $f \geq 0$ on $[a, b]$ then $\int_a^b f d\alpha \geq 0$.*

Proof: Since $f \geq 0$, $M_i \geq 0 \forall i$.

$$\begin{aligned} \therefore \sum_{i=1}^n M_i \Delta \alpha_i &\geq 0 \\ \Rightarrow U(P, h, \alpha) &\geq 0 \\ \Rightarrow \inf U(P, h, \alpha) &\geq 0 \\ \Rightarrow \int_a^b f d\alpha &\geq 0. \end{aligned}$$

Properties of Integral

Theorem 4.16 (a) If $f_1, f_2 \in \mathcal{R}(\alpha)$ on $[a, b]$ then $f_1 + f_2 \in \mathcal{R}(\alpha)$, $cf_1 \in \mathcal{R}(\alpha)$ for every constant c and $\int_a^b (f_1 + f_2) d\alpha = \int_a^b f_1 d\alpha + \int_a^b f_2 d\alpha$, $\int_a^b cf_1 d\alpha = c \int_a^b f_1 d\alpha$.

(b) If $f_1(x) \leq f_2(x)$ on $[a, b]$ then $\int_a^b f_1 d\alpha \leq \int_a^b f_2 d\alpha$.

(c) If $f \in \mathcal{R}(\alpha)$ on $[a, b]$ and $a < c < b$, then $f \in \mathcal{R}(\alpha)$ on $[a, c]$ and on $[c, b]$ and $\int_a^b f d\alpha = \int_a^c f d\alpha + \int_c^b f d\alpha$

(d) If $f \in \mathcal{R}(\alpha)$ on $[a, b]$ and if $|f(x)| \leq M$ then $|\int_a^b f d\alpha| \leq [\alpha(b) - \alpha(a)]$.

(e) If $f \in \mathcal{R}(\alpha_1)$ and $f \in \mathcal{R}(\alpha_2)$ then $f \in \mathcal{R}(\alpha_1 + \alpha_2)$ and $\int_a^b f d(\alpha_1 + \alpha_2) = \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2$. If $f \in \mathcal{R}(\alpha)$ and c is positive constant then $f \in \mathcal{R}(c\alpha)$ and $\int_a^b cf d\alpha = c \int_a^b f d\alpha$.

Proof: (a) Let $\epsilon > 0$ be given. Since $f_1 \in \mathcal{R}(\alpha)$ and $f_2 \in [a, b]$, there exists two partitions P_1 and P_2 of $[a, b]$ such that $U(P_1, f_1, \alpha) - L(P_1, f_1, \alpha) < \epsilon \dots$

(1) and $U(P_2, f_2, \alpha) - L(P_2, f_2, \alpha) < \epsilon \dots$ (2)

Let $P = P_1 \cup P_2$ be the common refinement of $[a, b]$.

$$\begin{aligned} \therefore U(P_1, f_1, \alpha) &\leq U(P_1, f_1, \alpha) \\ L(P_1, f_1, \alpha) &\leq L(P_1, f_1, \alpha) \\ \Rightarrow U(P, f_1, \alpha) + L(P_1, f_1, \alpha) &\leq U(P_1, f_1, \alpha) + L(P, f_1, \alpha) \\ \Rightarrow U(P, f_1, \alpha) - L(P_1, f_1, \alpha) &\leq U(P_1, f_1, \alpha) - L(P_1, f_1, \alpha) \\ U(P, f_1, \alpha) - L(P, f_1, \alpha) &< \epsilon \text{ (by (1))} \dots \dots (3) \end{aligned}$$

Similarly $U(P, f_2, \alpha) - L(P, f_2, \alpha) < \epsilon$ (by (2)) $\dots \dots$ (4)

(3)+(4) \Rightarrow

$$\begin{aligned} U(P, f_1, \alpha) + U(P, f_2, \alpha) - (L(P, f_1, \alpha) + L(P, f_2, \alpha)) \\ < 2\epsilon \dots \dots (5) \end{aligned}$$

$$\begin{aligned} \text{Now } L(P, f_1, \alpha) + L(P, f_2, \alpha) &\leq L(P, f_1 + f_2, \alpha) \\ &\leq U(P, f_1 + f_2, \alpha) \\ &\leq U(P, f_1, \alpha) + U(P, f_2, \alpha) \dots \dots (6) \end{aligned}$$

(5), (6) $\Rightarrow U(P, f_1 + f_2, \alpha) - L(P, f_1 + f_2, \alpha) < 2\epsilon$. $\therefore f_1 + f_2 \in \mathcal{R}(\alpha)$ on $[a, b]$.

To prove:

$$\int_a^b (f_1 + f_2) d\alpha = \int_a^b f_1 d\alpha + \int_a^b f_2 d\alpha$$

Since $f_1, f_2 \in \mathcal{R}(\alpha)$, there exists partition P_1 and P_2 of $[a, b]$

$$U(P_1, f_1, \alpha) < \int_a^b f_1 d\alpha + \epsilon \text{ (by Theorem 4.9).....(1*)}$$

$$U(P_2, f_2, \alpha) < \int_a^b f_2 d\alpha + \epsilon \text{.....(2*)}$$

(1)+(2) \Rightarrow

$$U(P_1, f_1, \alpha) + U(P_2, f_2, \alpha) < \int_a^b f_1 d\alpha + \int_a^b f_2 d\alpha + 2\epsilon \text{.....(3*)}$$

Let $P = P_1 \cup P_2$

$$U(P, f_1, \alpha) \leq U(P_1, f_1, \alpha) \text{.....(4*)}$$

$$U(P, f_2, \alpha) \leq U(P_2, f_2, \alpha) \text{.....(5*)}$$

(4*)+(5*) \Rightarrow

$$\begin{aligned} U(P, f_1, \alpha) + U(P, f_2, \alpha) &\leq U(P_1, f_1, \alpha) + U(P_2, f_2, \alpha) \\ &< \int_a^b f_1 d\alpha + \int_a^b f_2 d\alpha + 2\epsilon \text{.....(6*) (by (3*))} \end{aligned}$$

$$\begin{aligned} U(P, f_1 + f_2, \alpha) &\leq U(P, f_1, \alpha) + U(P, f_2, \alpha) \\ &< \int_a^b f_1 d\alpha + \int_a^b f_2 d\alpha + 2\epsilon \text{ (by (6*))} \end{aligned}$$

Taking infimum over all partition P ,

$$\int_a^b (f_1 + f_2) d\alpha < \int_a^b f_1 d\alpha + \int_a^b f_2 d\alpha + 2\epsilon$$

Since ϵ is arbitrary,

$$\int_a^b (f_1 + f_2) d\alpha \leq \int_a^b f_1 d\alpha + \int_a^b f_2 d\alpha \text{.....(7*)}$$

Replacing f_1 and f_2 in (7*) by $-f_1$ and $-f_2$ respectively we get,

$$\begin{aligned} \int_a^b (-f_1 - f_2) d\alpha &\leq \int_a^b (-f_1) d\alpha + \int_a^b (-f_2) d\alpha \\ \Rightarrow \int_a^b (f_1 + f_2) d\alpha &\geq \int_a^b f_1 d\alpha + \int_a^b f_2 d\alpha \text{.....(8*)} \end{aligned}$$

From (7*) and (8*) we get,

$$\int_a^b (f_1 + f_2) d\alpha = \int_a^b f_1 d\alpha + \int_a^b f_2 d\alpha$$

To Prove: $cf_1 \in \mathcal{R}(\alpha)$ where c is a constant.
 For any partition P , of $[a, b]$

$$U(P, cf_1, \alpha) = \begin{cases} cU(P, f_1, \alpha) & c \geq 0 \\ cL(P, f_1, \alpha) & c \leq 0 \end{cases}$$

and

$$L(P, cf_1, \alpha) = \begin{cases} cL(P, f_1, \alpha) & c \geq 0 \\ cU(P, f_1, \alpha) & c \leq 0 \end{cases}$$

$$U(P, cf_1, \alpha) - L(P, cf_1, \alpha) = \begin{cases} c(U(P, f_1, \alpha) - L(P, f_1, \alpha)) & c \geq 0 \\ -c(U(P, f_1, \alpha) - L(P, f_1, \alpha)) & c \leq 0 \end{cases}$$

$$U(P, cf_1, \alpha) - L(P, cf_1, \alpha) = |c|(U(P, f_1, \alpha) - L(P, f_1, \alpha)) \dots (1A)$$

Since $f_1 \in \mathcal{R}(\alpha)$ there exists a partition P of $[a, b]$ such that

$$U(P, f_1, \alpha) - L(P, f_1, \alpha) < \frac{\epsilon}{|c|} \dots (2A)$$

Sub (2A) in (1A), we get

$$\begin{aligned} U(P, cf_1, \alpha) - L(P, cf_1, \alpha) &< |c| \frac{\epsilon}{|c|} \\ U(P, cf_1, \alpha) - L(P, cf_1, \alpha) &< \epsilon \\ \therefore cf_1 &\in \mathcal{R}(\alpha). \end{aligned}$$

To Prove:

$$\int_a^b cf_1 d\alpha = \int_a^b cf_1 d\alpha$$

If $c \geq 0$, then $U(P, cf_1, \alpha) = cU(P, f_1, \alpha)$

$$\Rightarrow \inf U(P, cf_1, \alpha) = \inf(cU(P, f_1, \alpha))$$

$$\Rightarrow \inf U(P, cf_1, \alpha) = c \inf U(P, f_1, \alpha)$$

$$\Rightarrow \int_a^b cf_1 d\alpha = \int_a^b cf_1 d\alpha$$

If $c \leq 0$, then $L(P, cf_1, \alpha) = cU(P, f_1, \alpha)$

$$= -|c|U(P, f_1, \alpha) (\because c \leq 0)$$

$$\Rightarrow \sup L(P, cf_1, \alpha) = \sup(-|c|U(P, f_1, \alpha))$$

$$= |c| \sup(-U(P, f_1, \alpha))$$

$$= -|c| \inf(U(P, f_1, \alpha))$$

$$\Rightarrow \int_a^b cf_1 d\alpha = -|c| \int_a^b f_1 d\alpha$$

$$= c \int_a^b f_1 d\alpha$$

$$\text{When } c = 0, \int_a^b cf_1 d\alpha = \int_a^b f_1 d\alpha (= 0)$$

To Prove:

$$f_1 \leq f_2 \Rightarrow \int_a^b f_1 d\alpha \leq \int_a^b f_2 d\alpha$$

Proof of b: Given $f_1 \leq f_2 \Rightarrow f_2 - f_1 \geq 0$

$$\begin{aligned} &\Rightarrow \int_a^b (f_2 - f_1) d\alpha \geq 0 \\ &\Rightarrow \int_a^b f_2 + \int_a^b (-f_1) d\alpha \geq 0 \\ &\Rightarrow \int_a^b f_2 d\alpha + \int_a^b (-f_1) d\alpha \geq 0 \text{ (by (a))} \\ &\Rightarrow \int_a^b f_2 d\alpha - \int_a^b f_1 d\alpha \geq 0 \\ &\Rightarrow \int_a^b f_1 d\alpha \leq \int_a^b f_2 d\alpha \end{aligned}$$

Proof of (c): Given $f \in \mathcal{R}(\alpha)$ on $[a, b]$ and $a < c < b$ for $\epsilon < 0$, there exists a partition P of $[a, b]$ such that

$$U(P, f, \alpha) - L(P, f, \alpha) < \epsilon \dots (1B)$$

Let $P^* = P \cup \{c\}$. Now P^* is a refinement of P and induces two partitions P_1 and P_2 of $[a, c]$ and $[c, b]$ respectively. Now,

$$\begin{aligned} U(P, f, \alpha) &\geq U(P^*, f, \alpha) \\ &= U(P_1, f, \alpha) + U(P_2, f, \alpha) \dots (2B) \end{aligned}$$

$$\Rightarrow U(P_1, f, \alpha) \leq U(P, f, \alpha) \dots (3B)$$

$$\text{and } U(P_2, f, \alpha) \leq U(P, f, \alpha) \dots (4B)$$

$$\begin{aligned} L(P, f, \alpha) &\leq L(P^*, f, \alpha) \\ &= L(P_1, f, \alpha) + L(P_2, f, \alpha) \dots (5B) \end{aligned}$$

$$-L(P, f, \alpha) \geq -L(P_1, f, \alpha) - L(P_2, f, \alpha)$$

$$-L(P_1, f, \alpha) \leq -L(P, f, \alpha) \dots (6B)$$

$$\text{and } -L(P_2, f, \alpha) \leq -L(P, f, \alpha) \dots (7B)$$

$$\begin{aligned} (3B) + (6B) &\Rightarrow U(P_1, f, \alpha) - L(P_1, f, \alpha) \leq U(P, f, \alpha) - L(P, f, \alpha) \text{ (by (1B))} \\ &< \epsilon \end{aligned}$$

$$\therefore f \in \mathcal{R}(\alpha) \text{ on } [a, c].$$

$$\begin{aligned} (4B) + (7B) &\Rightarrow U(P_2, f, \alpha) - L(P_2, f, \alpha) \leq U(P, f, \alpha) - L(P, f, \alpha) \text{ (by (1B))} \\ &< \epsilon \end{aligned}$$

$$\therefore f \in \mathcal{R}(\alpha) \text{ on } [c, b].$$

To Prove:

$$\int_a^b f d\alpha = \int_a^c f d\alpha + \int_c^b f d\alpha$$

$$\begin{aligned}
(2B) \Rightarrow U(P, f, \alpha) &\geq U(P_1, f, \alpha) + U(P_2, f, \alpha) \\
&\geq \int_a^c f d\alpha + \int_c^b f d\alpha \\
\Rightarrow \inf U(P, f, \alpha) &\geq \int_a^c f d\alpha + \int_c^b f d\alpha \\
\int_a^b f d\alpha &\geq \int_a^c f d\alpha + \int_c^b f d\alpha \dots (8B) \\
(5B) \Rightarrow L(P, f, \alpha) &\leq L(P_1, f, \alpha) + L(P_2, f, \alpha) \\
&\leq \int_a^c f d\alpha + \int_c^b f d\alpha \\
\Rightarrow \sup U(P, f, \alpha) &\leq \int_a^c f d\alpha + \int_c^b f d\alpha \\
\int_a^b f d\alpha &\leq \int_a^c f d\alpha + \int_c^b f d\alpha \dots (9B)
\end{aligned}$$

\therefore (8B) and (9B), we get

$$\int_a^b f d\alpha = \int_a^c f d\alpha + \int_c^b f d\alpha$$

Proof of (d): Given $f \in \mathcal{R}(\alpha)$ and $|f(x)| \leq M$

To Prove: $|\int_a^b f d\alpha| \leq [\alpha(b) - \alpha(a)]$

we have, for any partition P of $[a, b]$,

$$\begin{aligned}
\int_a^b f d\alpha &\leq U(P, f, \alpha) \\
\left| \int_a^b f d\alpha \right| &\leq |U(P, f, \alpha)| \\
&= \left| \sum_{i=1}^n M_i \Delta\alpha_i \right| \\
&< \sum_{i=1}^n |M_i \Delta\alpha_i| \\
&= \sum_{i=1}^n |M_i| \Delta\alpha_i \quad (\because \Delta\alpha_i \geq 0) \\
&\leq \sum_{i=1}^n M \Delta\alpha_i \quad (\because |f(x)| \leq M) \\
&= M \sum_{i=1}^n \Delta\alpha_i \\
\left| \int_a^b f d\alpha \right| &\leq M[\alpha(b) - \alpha(a)]
\end{aligned}$$

Proof of (e): Given $f \in \mathcal{R}(\alpha_1)$ and $f \in \mathcal{R}(\alpha_2)$. To Prove: $f \in \mathcal{R}(\alpha_1 + \alpha_2)$.

Let $\alpha = \alpha_1 + \alpha_2$. For any partition p of $[a, b]$,

$$\begin{aligned} U(P, f, \alpha) &= \sum_{i=1}^n M_i \Delta \alpha_i \\ &= \sum_{i=1}^n M_i (\alpha(x_i) - \alpha(x_{i-1})) \\ &= \sum_{i=1}^n M_i [(\alpha_1 + \alpha_2)(x_i) - (\alpha_1 + \alpha_2)(x_{i-1})] \\ &= \sum_{i=1}^n M_i [\alpha_1(x_i) + \alpha_2(x_i)] - [\alpha_1(x_{i-1}) + \alpha_2(x_{i-1})] \\ &= \sum_{i=1}^n M_i [\alpha_1(x_i) - \alpha_1(x_{i-1})] + \sum_{i=1}^n M_i [\alpha_2(x_i) - \alpha_2(x_{i-1})] \end{aligned}$$

$$U(P, f, \alpha) = U(P, f, \alpha_1) + U(P, f, \alpha_2) \dots \dots (1C)$$

$$\text{Similarly } L(P, f, \alpha) = L(P, f, \alpha_1) + L(P, f, \alpha_2) \dots \dots (2C)$$

since $f \in \mathcal{R}(\alpha_1)$ and $f \in \mathcal{R}(\alpha_2)$, there exists partitions P_1 and P_2 of $[a, b]$ such that

$$\begin{aligned} U(P_1, f, \alpha_1) - L(P_1, f, \alpha_1) &< \epsilon \\ \text{and } U(P_2, f, \alpha_2) - L(P_2, f, \alpha_2) &< \epsilon \end{aligned}$$

Let P^* be the common refinement of P_1 and P_2 of $[a, b]$. $P^* = P_1 \cup P_2$

$$U(P^*, f, \alpha_1) - L(P^*, f, \alpha_1) < \epsilon \dots \dots (3C)$$

$$U(P^*, f, \alpha_2) - L(P^*, f, \alpha_2) < \epsilon \dots \dots (4C) \text{ (by Theorem 4.10)}$$

Now,

$$\begin{aligned} U(P^*, f, \alpha) - L(P^*, f, \alpha) &= U(P^*, f, \alpha_1) + U(P^*, f, \alpha_2) \\ &\quad - [L(P^*, f, \alpha_1) + L(P^*, f, \alpha_2)] \text{ (by (1C) and (2C))} \\ &= [U(P^*, f, \alpha_1) - L(P^*, f, \alpha_1)] \\ &\quad + [U(P^*, f, \alpha_2) - L(P^*, f, \alpha_2)] \\ &< \epsilon + \epsilon \text{ (by (3C) and (4C))} \end{aligned}$$

$$U(P^*, f, \alpha) - L(P^*, f, \alpha) < 2\epsilon.$$

Since ϵ arbitrary, we get $f \in \mathcal{R}(\alpha)$ (i.e.) $f \in \mathcal{R}(\alpha_1 + \alpha_2)$.

To Prove:

$$\int_a^b d(\alpha_1 + \alpha_2) = \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2$$

$$\begin{aligned}
(1C) \Rightarrow U(P, f, \alpha) &= U(P, f, \alpha_1) + U(P, f, \alpha_2) \\
&\geq \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2 \\
\Rightarrow \inf U(P, f, \alpha) &\geq \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2 \\
\int_a^b f d\alpha &\geq \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2 \dots (5C) \\
(2C) \Rightarrow L(P, f, \alpha) &= L(P, f, \alpha_1) + L(P, f, \alpha_2) \\
&\leq \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2 \\
\sup U(P, f, \alpha) &\leq \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2 \\
\int_a^b f d\alpha &\leq \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2 \dots (6C)
\end{aligned}$$

from (5C) and (6C) we get,

$$\begin{aligned}
\int_a^b f d\alpha &= \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2 \\
(i.e.) \int_a^b d(\alpha_1 + \alpha_2) &= \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2.
\end{aligned}$$

To Prove: Given $f \in \mathcal{R}(\alpha)$ and $c > 0$

To Prove: $f \in \mathcal{R}(c\alpha)$, for any partition P ,

$$\begin{aligned}
U(P, f, c\alpha) &= \sum_{i=1}^n M_i \Delta(c\alpha_i) \\
&= \sum_{i=1}^n M_i (c\alpha(x_i) - c\alpha(x_{i-1})) \\
&= \sum_{i=1}^n M_i c [\alpha(x_i) - \alpha(x_{i-1})] \\
&= \sum_{i=1}^n c M_i \Delta\alpha_i \\
&= cU(P, f, \alpha) \dots (7C)
\end{aligned}$$

Similarly $L(P, f, c\alpha) = cL(P, f, \alpha)$

$$\begin{aligned}
U(P, f, c\alpha) - L(P, f, c\alpha) &= cU(P, f, \alpha) - cL(P, f, \alpha) \\
&= c[U(P, f, \alpha) - L(P, f, \alpha)] \dots (8C)
\end{aligned}$$

Since $f \in \mathcal{R}(\alpha)$, given $\epsilon > 0$, there exists partition P of $[a, b]$ such that

$$U(P, f, \alpha) - L(P, f, \alpha) < \frac{\epsilon}{c} \dots (9C)$$

sub (9C) in (8C) we get

$$U(P, f, c\alpha) - L(P, f, c\alpha) < c \cdot \frac{\epsilon}{c} = \epsilon$$

$\therefore f \in \mathcal{R}(c\alpha)$. To Prove:

$$\int_a^b f d(c\alpha) = c \int_a^b f d\alpha$$

$$\begin{aligned} (7C) &\Rightarrow U(P, f, c\alpha) = cU(P, f, \alpha) \\ &\Rightarrow \inf U(P, f, c\alpha) = \inf cU(P, f, \alpha) \\ &= c \inf U(P, f, \alpha) \\ &\Rightarrow \int_a^b f d(c\alpha) = c \int_a^b f d\alpha \end{aligned}$$

Theorem 4.17 If $f, g \in \mathcal{R}(\alpha)$ on $[a, b]$, then

(a) $f \cdot g \in \mathcal{R}(\alpha)$

(b) $|f| \in \mathcal{R}(\alpha)$ and

$$\left| \int_a^b f d\alpha \right| \leq \int_a^b |f| d\alpha.$$

Proof: (a) Let $\phi(t) = t^2$, clearly ϕ is continuous

$$\begin{aligned} h(x) &= \phi(f(x)) \text{ (by Theorem 4.14)} \\ &= f(x)^2 \\ &= f^2(x) \end{aligned}$$

$$\therefore f^2 \in \mathcal{R}(\alpha) \dots \dots (1) \quad (\because f \in \mathcal{R}(\alpha))$$

Now, $f, g \in \mathcal{R}(\alpha)$

$$\Rightarrow f + g, f - g \in \mathcal{R}(\alpha) \text{ (by Theorem 4.16)}$$

$$\Rightarrow (f + g)^2, (f - g)^2 \in \mathcal{R}(\alpha)$$

$$\Rightarrow (f + g)^2 - (f - g)^2 \in \mathcal{R}(\alpha)$$

$$\Rightarrow 4fg \in \mathcal{R}(\alpha)$$

$$\Rightarrow fg \in \mathcal{R}(\alpha) \text{ (by Theorem 4.16)}$$

(b) $|f| \in \mathcal{R}(\alpha)$ and $\left| \int_a^b f d\alpha \right| \leq \int_a^b |f| d\alpha$.

To Prove: $|f| \in \mathcal{R}(\alpha)$. Let $\phi(t) = |t|$; $h(x) = \phi(f(x)) = |f(x)|$. \therefore By Theorem 4.14, $|f| \in \mathcal{R}(\alpha)$

To prove:

$$\left| \int_a^b f d\alpha \right| \leq \int_a^b |f| d\alpha.$$

Choose $c = \pm 1$ so that $c \int_a^b f d\alpha \geq 0$

$$\begin{aligned} \therefore \left| \int_a^b f d\alpha \right| &= c \int_a^b f d\alpha \\ &= \int_a^b c f d\alpha \quad (\text{by Theorem 4.16(a)}) \\ &\leq \int_a^b |f| d\alpha \quad (\because cf \leq |f|) \quad \text{by Theorem 4.16(b)} \end{aligned}$$

Hence the proof.

Definition 4.18 Unit Step Function:

$$I(x) = \begin{cases} 0 & \text{if } x \leq 0 \\ 1 & \text{if } x > 0 \end{cases}$$

Theorem 4.19 *If $a < s < b$, f is bounded on $[a, b]$, f is continuous at s and $\alpha(x) = I(x - s)$, then*

$$\int_a^b f d\alpha = f(s).$$

Proof: Consider partitions $P = \{x_0, x_1, x_2, x_b\}$ of $[a, b]$ where $x_0 = a, x_1 = s, x_2 < b, x_b = b$. Now,

$$\begin{aligned} U(P, f, \alpha) &= \sum_{i=1}^3 M_i \Delta \alpha_i \\ &= M_1 \Delta \alpha_1 + M_2 \Delta \alpha_2 + M_3 \Delta \alpha_3 \\ &= M_1[\alpha(x_1) - \alpha(x_0)] + M_2[\alpha(x_2) - \alpha(x_1)] + M_3[\alpha(x_b) - \alpha(x_2)] \\ &= M_1[I(x_1 - s) - I(x_0 - s)] + M_2[I(x_2 - s) - I(x_1 - s)] \\ &\quad + M_3[I(x_b - s) - I(x_2 - s)] \\ &= M_1[I(s - s) - I(a - s)] + M_2[I(x_2 - s) - I(s - s)] \\ &\quad + M_3[I(b - s) - I(x_2 - s)] \\ &= M_1[I(0) - I(a - s)] + M_2[I(x_2 - s) - I(0)] \\ &\quad + M_3[I(b - s) - I(x_2 - s)] \\ &= M_1[0 - 0] + M_2[1 - 0] + M_3[1 - 1] \quad (\text{by definition of } i) \\ &= M_2 \end{aligned}$$

In a similar fashion we can get $L(P, f, \alpha) = m_2$.

$$\begin{aligned} \int_a^b f d\alpha &= \inf U(P, f, \alpha) = \sup L(P, f, \alpha) \\ &= \inf M_2 = \sup m_2 \\ &= f(s) \quad (\because x_2 \rightarrow s, f(x_2) \rightarrow f(s) \text{ as } f \text{ is continuous at } s) \end{aligned}$$

Theorem 4.20 Suppose $c_n \geq 0$ for $1, 2, 3, \dots$, $\sum c_n$ converges, $\{s_n\}$ is a sequence of distinct point in (a, b) and $\alpha(x) = \sum_{n=1}^{\infty} c_n I(x - s_n)$. Let f be continuous on $[a, b]$, then

$$\int_a^b f d\alpha = \sum_{n=1}^{\infty} c_n f(s_n).$$

Proof: We have $|I(x - s_n)| \leq 1$. $\therefore |c_n I(x - s_n)| \leq c_n$. Since

$$\sum_{n=1}^{\infty} c_n$$

is convergent, by comparison test,

$$\sum_{n=1}^{\infty} c_n I(x - s_n)$$

also converges. Now,

$$\begin{aligned} \alpha(a) &= \sum_{n=1}^{\infty} c_n I(a - s_n) \\ &= 0 \dots \dots (1) \quad (\because I(a - s_n) = 0) \end{aligned}$$

and $\alpha(b) = \sum_{n=1}^{\infty} c_n I(b - s_n)$

$$= \sum_{n=1}^{\infty} c_n \dots \dots (2) \quad (\because I(b - s_n) = 0)$$

Claim: α is monotonically increasing. Let $x < y$ and let $x < s_k < y$

$$\begin{aligned} \alpha(x) &= \sum_{n=1}^{\infty} c_n I(x - s_n) \\ &= c_1 + c_2 + \dots + c_{k-1} \\ \alpha(y) &= \sum_{n=1}^{\infty} c_n I(y - s_n) \\ &= c_1 + c_2 + \dots + c_{k-1} + c_k \\ \therefore \alpha(x) &\leq \alpha(y) \end{aligned}$$

Hence the claim. Since

$$\sum_{n=1}^{\infty} c_n$$

is convergent, given $\epsilon > 0$, there exists $N >$ such that

$$\sum_{n=N+1}^{\infty} c_n < \epsilon \dots \dots (3)$$

Let

$$\alpha_1(x) = \sum_{n=1}^N c_n I(x - s_n)$$

$$\alpha_2(x) = \sum_{n=N+1}^{\infty} c_n I(x - s_n)$$

Clearly $\alpha(x) = \alpha_1(x) + \alpha_2(x)$. Let $\alpha_{1i} = I(x - s_i), i = 1, 2, \dots, N$.

$$\begin{aligned} \therefore \alpha_1(x) &= \sum_{n=1}^N c_n \alpha_{1n}(x) \\ &= (c_1 \alpha_{11} + c_2 \alpha_{12} + \dots + c_N \alpha_{1N})x \\ \text{(or) } \alpha_1 &= c_1 \alpha_{11} + c_2 \alpha_{12} + \dots + c_N \alpha_{1N} \end{aligned}$$

Now,

$$\begin{aligned} \int_a^b f d\alpha_1 &= \int_a^b f d(c_1 \alpha_{11} + c_2 \alpha_{12} + \dots + c_N \alpha_{1N}) \\ &= c_1 \int_a^b f d\alpha_{11} + c_2 \int_a^b f d\alpha_{12} + \dots + c_N \int_a^b f d\alpha_{1N} \text{ (by Theorem 4.16(e))} \\ &= c_1 f(s_1) + c_2 f(s_2) + \dots + c_N f(s_N) \text{ (by Theorem 4.19)} \\ &= \sum_{n=1}^N c_n f(s_n) \dots \dots (4) \end{aligned}$$

Now,

$$\begin{aligned} \alpha_2(a) &= \sum_{n=N+1}^{\infty} c_n I(a - s_n) \\ &= 0 \dots \dots (5) \\ \alpha_2(b) &= \sum_{n=N+1}^{\infty} c_n I(b - s_n) \\ &= \sum_{n=N+1}^{\infty} c_n \\ &< \epsilon \text{ (by (3))} \dots \dots (6) \end{aligned}$$

Let $M = |f(x)|, x \in [a, b]$. By Theorem 4.16(d),

$$\begin{aligned} \left| \int_a^b f d\alpha_2 \right| &\leq [\alpha_2(b) - \alpha_2(a)] \\ &\leq M\epsilon \text{ (by (5) and (6)),} \\ \text{(i.e.) } \left| \int_a^b f d\alpha_2 \right| &\leq M\epsilon \\ \Rightarrow \left| \int_a^b f d\alpha_1 + \int_a^b f d\alpha_2 - \int_a^b f d\alpha_1 \right| &\leq M\epsilon \\ \Rightarrow \left| \int_a^b f d(\alpha_1 + \alpha_2) - \int_a^b f d\alpha_1 \right| &\leq M\epsilon \text{ (by theorem 4.16(d))} \\ \Rightarrow \left| \int_a^b f d\alpha - \sum_{n=1}^N c_n f(s_n) \right| &\leq M\epsilon \text{ (by (4))} \end{aligned}$$

Taking limits as $N \rightarrow \infty$,

$$\begin{aligned} \left| \int_a^b f d\alpha - \sum_{n=1}^{\infty} c_n f(s_n) \right| &\leq M\epsilon \\ \therefore \left| \int_a^b f d\alpha \right| &= \sum_{n=1}^{\infty} c_n f(s_n) \end{aligned}$$

Theorem 4.21 Assume α increases monotonically and $\alpha' \in \mathcal{R}$ on $[a, b]$, Let f be a bounded real function on $[a, b]$, then $f \in \mathcal{R}(\alpha)$ iff $f\alpha' \in \mathcal{R}$. In that case $\int_a^b f d\alpha = \int_a^b f(x)\alpha'(x)dx$.

Proof: Let $\epsilon > 0$ be given. Since $\alpha' \in \mathcal{R}$, there exists a partition $P = \{x_1, x_2, \dots, x_n\}$ of $[a, b]$ such that $U(P, \alpha') - L(P, \alpha') < \epsilon \dots \dots$ (1)

By mean value theorem, there exists $t \in [x_{i-1}, x_i]$ such that $\alpha(x_i) - \alpha(x_{i-1}) = \alpha'(t)(x_i - x_{i-1})$ (i.e.) $\Delta\alpha_i = \alpha'(t_i)\Delta x_i \dots \dots$ (2)

By Theorem 4.10(b), $\forall s_i, t_i \in [x_{i-1}, x_i]$

$$\sum_{i=1}^n |\alpha'(s_i) - \alpha'(t_i)| \Delta x_i < \epsilon \dots \dots (3)$$

Now,

$$\begin{aligned}
& \left| \sum_{i=1}^n f(s_i) \Delta \alpha_i - \sum_{i=1}^n f(s_i) \alpha'(s_i) \Delta x_i \right| \\
&= \left| \sum_{i=1}^n f(s_i) \alpha'(t_i) \Delta x_i - \sum_{i=1}^n f(s_i) \alpha'(s_i) \Delta x_i \right| \\
&= \left| \sum_{i=1}^n f(s_i) [\alpha'(t_i) - \alpha'(s_i)] \Delta x_i \right| \\
& \left| \sum_{i=1}^n f(s_i) \Delta \alpha_i - \sum_{i=1}^n f(s_i) \alpha'(s_i) \Delta x_i \right| \\
&\leq \sum_{i=1}^n |f(s_i)| |\alpha'(t_i) - \alpha'(s_i)| \Delta x_i \\
&\leq \sum_{i=1}^n M |\alpha'(t_i) - \alpha'(s_i)| \Delta x_i \quad \text{where } M = \sup |f(x)| \\
&= M \sum_{i=1}^n |\alpha'(t_i) - \alpha'(s_i)| \Delta x_i \\
&\leq M \epsilon \quad (\text{by (3)}) \\
(i.e.) & \left| \sum_{i=1}^n f(s_i) \Delta \alpha_i - \sum_{i=1}^n f(s_i) \alpha'(s_i) \Delta x_i \right| \leq M \epsilon \\
& \left| \sum_{i=1}^n f(s_i) \Delta \alpha_i - \sum_{i=1}^n f(\alpha')(s_i) \Delta x_i \right| \leq M \epsilon \dots (4)
\end{aligned}$$

Since inequality (4) is true for any s_i in $[x_{i-1}, x_i]$, we can replace $(f\alpha')(s_i)$ by M'_i and m'_i , where $m'_i = \inf(f\alpha')_{s_i}$, $M'_i = \sup(f\alpha')(s_i)$, $s_i \in [x_{i-1}, x_i]$

$$\left| \sum_{i=1}^n f(s_i) \Delta \alpha_i - \sum_{i=1}^n M'_i \Delta x_i \right| \leq M \epsilon \dots (5)$$

$$\text{and } \left| \sum_{i=1}^n f(s_i) \Delta \alpha_i - \sum_{i=1}^n m'_i \Delta x_i \right| \leq M \epsilon \dots (6)$$

Again by replacing $f(s_i)$ by M_i in (5) and by m_i in (6) we get

$$\begin{aligned}
& \left| \sum_{i=1}^n M'_i \Delta \alpha_i - \sum_{i=1}^n M'_i \Delta x_i \right| \leq M \epsilon \quad \text{and} \\
& \left| \sum_{i=1}^n m'_i \Delta \alpha_i - \sum_{i=1}^n m'_i \Delta x_i \right| \leq M \epsilon \\
\Rightarrow & |U(P, f, \alpha) - U(P, f, \alpha')| \leq M \epsilon \dots (7) \quad \text{and} \\
& |L(P, f, \alpha) - L(P, f, \alpha')| \leq M \epsilon \dots (8)
\end{aligned}$$

Since ϵ is arbitrary, (7) and (8)

$$\begin{aligned} &\Rightarrow U(P, f, \alpha) = U(P, f, \alpha') \text{ and} \\ &\quad L(P, f, \alpha) = L(P, f, \alpha') \\ &\Rightarrow \inf U(P, f, \alpha) = \inf U(P, f, \alpha') \text{ and} \\ &\quad \sup L(P, f, \alpha) = \sup L(P, f, \alpha') \\ &\Rightarrow \int_a^{\bar{b}} f d\alpha = \int_a^{\bar{b}} (f\alpha') d\alpha \dots\dots (9) \text{ and} \\ &\quad \int_{\underline{a}}^b f d\alpha = \int_{\underline{a}}^b (f\alpha') d\alpha \dots\dots (10) \\ &\therefore f \in \mathcal{R}(\alpha) \Leftrightarrow \int_{\underline{a}}^b f d\alpha = \int_a^{\bar{b}} f d\alpha \\ &\Leftrightarrow \int_{\underline{a}}^b (f\alpha') d\alpha = \int_a^{\bar{b}} (f\alpha') d\alpha \text{ (by (9) and (10))} \\ &\quad \Leftrightarrow f(\alpha') \in \mathcal{R}. \end{aligned}$$

$$\begin{aligned} \text{Now, } \int_a^b f d\alpha &= \int_a^{\bar{b}} f d\alpha \\ &= \int_a^{\bar{b}} (f\alpha') dx \text{ (by(9))} \\ &= \int_a^b (f\alpha') dx \\ &= \int_a^b f(x)\alpha'(x) dx \\ \therefore \int_a^b f d\alpha &= \int_a^b f(x)\alpha'(x) dx \end{aligned}$$

Remark 4.22 *The above theorem gives the relation of \mathcal{R} integral and $\mathcal{R}(\alpha)$ integral.*

Theorem 4.23 Change of Variable: *Suppose ϕ is a strictly increasing function that maps an interval $[A, B]$ onto $[a, b]$. Suppose α is monotonically increasing on $[a, b]$ and $f \in \mathcal{R}(\alpha)$ on $[a, b]$. Define β and g on $[A, B]$ by $\beta(y) = \alpha(\phi(y))$, $g(y) = f(\phi(y))$, then $g \in \mathcal{R}(\beta)$ and $\int_A^B g d(\beta) = \int_a^b f d\alpha$.*

Proof: $g(y) = (f \cdot \phi)x = f(\phi(y)) = f(x)$

$$\begin{aligned} [A, B] &\xrightarrow{\phi} [a, b] \xrightarrow{f} \mathcal{R} \\ [A, B] &\xrightarrow{\phi} [a, b] \xrightarrow{\alpha} \mathcal{R} \\ \beta(y) &= (\alpha \cdot \phi)y \\ &= \alpha(\phi(y)) \\ &= \alpha(x) \end{aligned}$$

Let $P = \{x_0, x_1, x_2, \dots, x_n\}$ be any partition of $[a, b]$. Since ϕ is onto for each i , there exists $y_i \in [A, B]$ such that $\phi(y_i) = x_i$, $i = 0, 1, 2, \dots, n$. $\therefore \{y_0, y_1, y_2, \dots, y_n\}$ is a partition of $[A, B]$ every partition of $[A, B]$ can be obtained in this way (since ϕ is monotonically increasing)

$$\begin{aligned} \text{For } y &\in [y_{i-1}, y_i] \\ g(y) &= (f \cdot \phi)y \\ g(y) &= f(\phi(y)) \\ &= f(x) \text{ where } x = \phi(y), x \in [x_{i-1}, x_i] \end{aligned}$$

$$\begin{aligned} \Rightarrow \sup g(y) &= \sup f(x) \\ \Rightarrow M_{i'} &= M_i \dots \dots (1) \end{aligned}$$

Similarly $\inf g(y) = \inf f(x)$

$$m_{i'} = m_i \dots \dots (2)$$

$$\begin{aligned} \text{Now } \Delta\beta_i &= \beta(y_i) - \beta(y_{i-1}) \\ &= (\alpha \circ \phi)y_i - (\alpha \circ \phi)y_{i-1} \\ &= \alpha(\phi(y_i)) - \alpha(\phi(y_{i-1})) \\ &= \alpha(x_i) - \alpha(x_{i-1}) \\ &= \Delta\alpha_i \dots \dots (3) \end{aligned}$$

$$\begin{aligned} \therefore U(Q, g, \beta) &= \sum_{i=1}^n M_i' \Delta\beta_i \\ &= \sum_{i=1}^n M_i \Delta\alpha_i \text{ (by (1) and (3))} \\ &= U(P, f, \alpha) \dots \dots (4) \end{aligned}$$

Similarly $L(Q, g, \beta) = L(P, f, \alpha) \dots \dots (5)$

Since $f \in \mathcal{R}(\alpha)$, given $\epsilon > 0$, there exists a partition P of $[a, b]$ such that

$$\begin{aligned} U(P, f, \alpha) - L(P, f, \alpha) &< \epsilon \\ \Rightarrow U(Q, g, \beta) - L(Q, g, \beta) &< \epsilon \text{ (by (4) and (5))} \\ \therefore g &\in \mathcal{R}(\beta) \end{aligned}$$

$$\begin{aligned} \text{Also } \int_A^B g d\beta &= \inf U(Q, g, \beta) \\ &= \inf U(P, f, \alpha) \text{ (by (4))} \\ &= \int_a^b f d\alpha. \end{aligned}$$

Note 4.24 Let $\alpha(x) = x$ and $\phi' \in \mathcal{R}$ on $[A, B]$.

$$\begin{aligned} \therefore \beta(y) &= (\alpha \circ \phi)y, \\ &= \alpha(\phi(y)) \\ &= \phi(y) \quad \forall y \in [A, B] \\ \therefore \beta &= \phi \\ \int_A^B g d\beta &= \int_a^b f d\alpha \quad (\text{by previous theorem}) \\ \int_a^b f(x) dx &= \int_A^B g d\beta \\ &= \int_A^B g d\phi \\ &= \int_A^B g(y)\phi'(y) dy \quad (\text{by theorem } \boxed{4.21}) \end{aligned}$$

Integrations and Differentiations:

Theorem 4.25 Let $f \in \mathcal{R}$ on $[a, b]$, for $a \leq x \leq b$, put $F(x) = \int_a^x f(t) dt$, then F is continuous on $[a, b]$, further more if f is continuous at some point x_0 of $[a, b]$, then F is differentiable at x_0 and $F'(x_0) = f(x_0)$.

Proof: Given $F(x) = \int_a^x f(t) dt$. To Prove: $F(x)$ is continuous on $[a, b]$. Let $a \leq x \leq y \leq b$. Now,

$$\begin{aligned} F(y) - F(x) &= \int_a^y f(t) dt - \int_a^x f(t) dt \\ &= \int_a^x f(t) dt + \int_x^y f(t) dt - \int_a^x f(t) dt \\ &= \int_x^y f(t) dt \\ \Rightarrow |F(y) - F(x)| &= \left| \int_x^y f(t) dt \right| \\ &\leq \int_x^y |f(t)| dt \\ &\leq \int_x^y M dt \quad \text{where } M = \sup |f(t)|, t \in [a, b] \\ &= M(y - x) \end{aligned}$$

$$(i.e.) |F(y) - F(x)| \leq M|y - x| \quad (\because (y - x) = 0)$$

Given $\epsilon > 0$, there exists $\delta = \frac{\epsilon}{M}$ such that $|y - x| < \delta \Rightarrow |F(y) - F(x)| < \epsilon$ (i.e.) F is continuous on $[a, b]$. (infact F is uniformly continuous on $[a, b]$). Suppose f is continuous at $x_0 \in [a, b]$. To Prove: $F'(x_0) = f(x_0)$. Given $\epsilon > 0$, there exists $\delta > 0$ such that $|t - x_0| < \delta \Rightarrow |f(t) - f(x_0)| < \epsilon$ for $t \in [a, b]$ (1)

Let $x_0 - \delta < s \leq x_0 \leq t \leq x_0 + \delta$. Now,

$$\begin{aligned}
 F(t) - F(s) &= \int_a^t f(t)dt - \int_a^s f(t)dt \\
 &= \int_a^s f(t)dt + \int_s^t f(t)dt - \int_a^s f(t)dt \\
 F(t) - F(s) &= \int_s^t f(t)dt \\
 \Rightarrow \frac{F(t) - F(s)}{t - s} &= \frac{1}{t - s} \int_s^t f(t)dt \\
 \Rightarrow \frac{F(t) - F(s)}{t - s} - f(x_0) &= \frac{1}{t - s} \int_s^t f(t)dt - f(x_0) \\
 \frac{F(t) - F(s)}{t - s} - f(x_0) &= \frac{1}{t - s} \left\{ \int_s^t f(t)dt - (t - s)f(x_0) \right\} \\
 &= \frac{1}{t - s} \left\{ \int_s^t f(t)dt - \int_s^t f(x_0)dt \right\} \\
 &= \frac{1}{t - s} \int_s^t (f(t) - f(x_0))dt \\
 \left| \frac{F(t) - F(s)}{t - s} - f(x_0) \right| &= \left| \frac{1}{t - s} \int_s^t (f(t) - f(x_0))dt \right| \\
 &\leq \frac{1}{t - s} \int_s^t |f(t) - f(x_0)|dt \\
 &< \frac{\epsilon}{t - s} \int_s^t dt \text{ (by (1))} \\
 \left| \frac{F(t) - F(s)}{t - s} - f(x_0) \right| &< \epsilon
 \end{aligned}$$

It follows that $F'(x_0) = f(x_0)$.

Theorem 4.26 The Fundamental Theorem of Calculus: If $f \in R$ on $[a, b]$ and if there is a differentiable function F such that $F' = f$, then $\int_a^b f(x)dx = F(b) - F(a)$.

Proof: Since $f \in R$ on $[a, b]$, given $\epsilon > 0$, there exists a partition $P = \{x_0, x_1, x_2, \dots, x_n\}$ of $[a, b]$ such that $U(P, f) - L(P, f) < \epsilon \dots \dots$ (1)

Since F is differentiable we can apply the mean value theorem to it on $[x_{i-1}, x_i]$. There exists $t_i \in [x_{i-1}, x_i]$ such that

$$\begin{aligned}
 F(x_i) - F(x_{i-1}) &= (x_i - x_{i-1})F'(t_i) \\
 &= \Delta x_i f(t_i) \text{ } (\because F' = f)
 \end{aligned}$$

Summing over i , we get,

$$\begin{aligned}
 \sum_{i=1}^n [F(x_i) - F(x_{i-1})] &= \sum_{i=1}^n \Delta x_i f(t_i) \\
 F(b) - F(a) &= \sum_{i=1}^n f(t_i) \Delta x_i \dots \dots (2)
 \end{aligned}$$

By Theorem 4.10(c), (1) implies that

$$\left| \sum_{i=1}^n f(t_i) \Delta x_i - \int_a^b f(x) dx \right| < \epsilon \dots \dots (3)$$

Using (2) and (3) we get, $|(F(b) - F(a)) - \int_a^b f(x) dx| < \epsilon$. Since ϵ is arbitrary, $\int_a^b f(x) dx = F(b) - F(a)$. Hence the proof.

Theorem 4.27 Integration by parts: Suppose F and G are differentiable functions on $[a, b]$, $F' = f \in \mathcal{R}$, $G' = g \in \mathcal{R}$, then

$$\int_a^b f(x)g(x)dx = F(b)G(b) - F(a)G(a) - \int_a^b f(x)G(x)dx.$$

Proof: Let $H(x) = F(x)G(x)$. $\therefore H'(x) = F(x)G'(x) + F'(x)G(x) = F(x)g(x) + f(x)G(x) \dots \dots (1)$

Given f and $g \in \mathcal{R}$. Since F and G are differentiable, they are continuous. \therefore By Theorem 4.11, F and G are integrable ($\in \mathcal{R}$). \therefore By Theorem 4.16 $F(x)g(x) + f(x)G(x) \in \mathcal{R}$ (i.e.) $H'(x) \in \mathcal{R}$. By fundamental theorem of calculus,

$$\int_a^b H'(x)dx = H(b) - H(a)$$

$$(i.e.) \int_a^b (F(x)g(x) + f(x)G(x))dx = F(b)G(b) - F(a)G(a)$$

$$\Rightarrow \int_a^b F(x)g(x)dx + \int_a^b f(x)G(x)dx = F(b)G(b) - F(a)G(a)$$

$$\Rightarrow \int_a^b F(x)g(x)dx = F(b)G(b) - F(a)G(a) - \int_a^b f(x)G(x)dx$$

Hence the proof.

Definition 4.28 Integration of vector valued functions: Let f_1, f_2, \dots, f_k be real functions on $[a, b]$ and let $\bar{f} = (f_1, f_2, \dots, f_k)$ be a mapping of $[a, b] \rightarrow \mathbb{R}^k$. Suppose α increases monotonically on $[a, b]$, then $\bar{f} \in \mathcal{R}(\alpha) \Leftrightarrow$ for each $f_i \in \mathcal{R}(\alpha)$, and in this case

$$\int_a^b \bar{f} d\alpha = \left(\int_a^b f_1 d\alpha, \int_a^b f_2 d\alpha, \dots, \int_a^b f_k d\alpha \right)$$

Theorem 4.29 Fundamental Theorem of calculus for vector valued functions: If \bar{F}, \bar{f} map $[a, b]$ into \mathbb{R}^k and if $\bar{f} \in \mathcal{R}$ on $[a, b]$ and if $\bar{F}' = \bar{f}$ then $\int_a^b \bar{f}(t)dt = \bar{F}(b) - \bar{F}(a)$.

Proof: Let

$$\begin{aligned} \bar{f} &= (f_1, f_2, \dots, f_k) \\ \bar{F} &= (F_1, F_2, \dots, F_k) \\ \bar{F}' &= (F'_1, F'_2, \dots, F'_k) \end{aligned}$$

Given $\bar{F}' = \bar{f}$. $\therefore (F'_1, F'_2, \dots, F'_k) = (f_1, f_2, \dots, f_k) \Rightarrow F'_i = f_i \quad \forall i = 1, 2, \dots, k$.
 Since $\bar{f} \in \mathcal{R}$, each $f_i \in \mathcal{R}$. \therefore By fundamental theorem of calculus, for any i .

$$\int_a^b F'_i(t) dt = F_i(b) - F_i(a)$$

$$(i.e.) \int_a^b f_i(t) dt = F_i(b) - F_i(a) \dots \dots (1)$$

Now,

$$\int_a^b \bar{f}(t) dt = \left(\int_a^b f_1(t) dt, \int_a^b f_2(t) dt, \dots, \int_a^b f_k(t) dt \right) \text{ (by definition)}$$

$$(1) \Rightarrow = (F_1(b) - F_1(a), F_2(b) - F_2(a), \dots, F_k(b) - F_k(a))$$

$$= (F_1(b), F_2(b), \dots, F_k(b)) - (F_1(a), F_2(a), \dots, F_k(a))$$

$$= \bar{F}(b) - \bar{F}(a)$$

$$\therefore \int_a^b \bar{f}(t) dt = \bar{F}(b) - \bar{F}(a)$$

Note 4.30 Schwartz inequality:

$$\left| \sum_{j=1}^n a_j \bar{b}_j \right|^2 \leq \left(\sum_{j=1}^n |a_j|^2 \right) \left(\sum_{j=1}^n |b_j|^2 \right) \text{ (or)}$$

$$\left| \sum_{j=1}^n a_j \bar{b}_j \right| \leq \left(\sum_{j=1}^n |a_j|^2 \right)^{\frac{1}{2}} \left(\sum_{j=1}^n |b_j|^2 \right)^{\frac{1}{2}}$$

Theorem 4.31 If \bar{f} maps $[a, b]$ into \mathbb{R}^k and if $\bar{f} \in \mathcal{R}(\alpha)$ for some monotonically increasing function $[a, b]$, then $|\bar{f}| \in \mathcal{R}(\alpha)$ and $|\int_a^b \bar{f}(t) d\alpha| \leq \int_a^b |\bar{f}(t)| d\alpha$.

Proof:

$$\bar{f} = (f_1, f_2, \dots, f_k)$$

$$|\bar{f}| = (f_1^2 + f_2^2 + f_3^2 + \dots + f_k^2)^{1/2}$$

Since $\bar{f} \in \mathcal{R}(\alpha)$

$$\Rightarrow f_i \in \mathcal{R}(\alpha) \quad \forall i = 1, 2, \dots, k$$

$$\Rightarrow f_i^2 \in \mathcal{R}(\alpha)$$

$$\Rightarrow (f_1^2 + f_2^2 + f_3^2 + \dots + f_k^2) \in \mathcal{R}(\alpha)$$

$$\Rightarrow (f_1^2 + f_2^2 + f_3^2 + \dots + f_k^2)^2 \in \mathcal{R}(\alpha) \text{ (by Theorem 4.17, } \phi(t) = t^{1/2} \text{)}$$

$$\Rightarrow |\bar{f}| \in \mathcal{R}(\alpha)$$

To Prove:

$$\left| \int_a^b \bar{f}(t) d\alpha \right| \leq \int_a^b |\bar{f}(t)| d\alpha$$

Let $\bar{y} = \int_a^b \bar{f}(t) d\alpha$. If $\bar{y} = 0$, then the inequality is trivial (for, $\bar{y} = 0 \Rightarrow$ L.H.S=0 and $|\bar{f}| \geq 0 \Rightarrow \int_a^b |\bar{f}(t)| d\alpha \geq 0$ (i.e.) R.H.S ≥ 0)

Let $\bar{y} \neq 0$

$$\begin{aligned} \therefore \bar{y} &= \int_a^b \bar{f} d\alpha = \left(\int_a^b f_1 d\alpha, \int_a^b f_2 d\alpha, \dots, \int_a^b f_k d\alpha \right) \\ &= (y_1, y_2, \dots, y_k) \text{ where } y_i = \int_a^b f_i d\alpha \end{aligned}$$

$$\text{Now } |\bar{y}|^2 = y_1^2 + y_2^2 + \dots + y_k^2$$

$$\begin{aligned} \text{(i.e.) } |\bar{y}|^2 &= \sum_{i=1}^k y_i^2 \\ &= \sum_{i=1}^k y_i y_i \\ &= \sum_{i=1}^k y_i \left(\int_a^b f_i d\alpha \right) \\ &= \sum_{i=1}^k \int_a^b (y_i f_i) d\alpha \\ &= \int_a^b \left(\sum_{i=1}^k y_i f_i \right) d\alpha \\ &\leq \int_a^b \left(\sum_{i=1}^k |y_i|^2 \right)^{1/2} \left(\sum_{i=1}^k |f_i|^2 \right)^{1/2} d\alpha \text{ (by schwartz inequality)} \end{aligned}$$

$$\text{(i.e.) } |\bar{y}|^2 \leq \int_a^b \left(\sum_{i=1}^k y_i^2 \right)^{1/2} \left(\sum_{i=1}^k f_i^2 \right)^{1/2} d\alpha$$

$$= \int_a^b |\bar{y}| |\bar{f}| d\alpha$$

$$= |\bar{y}| \int_a^b |\bar{f}| d\alpha$$

$$\text{(i.e.) } |\bar{y}|^2 \leq |\bar{y}| \int_a^b |\bar{f}| d\alpha$$

$$\Rightarrow |\bar{y}| \leq \int_a^b |\bar{f}| d\alpha$$

$$\left| \int_a^b \bar{f} d\alpha \right| \leq \int_a^b |\bar{f}| d\alpha$$

Uniform Convergence:

Definition 4.32 Uniform Convergence: We say that $\{f_n\}$ of function $n = 1, 2, \dots$ converges uniformly on E to a function f is every $\epsilon > 0$ there is an integer N such that $n \geq N \Rightarrow |f_n(x) - f(x)| < \epsilon$.

Note 4.33 If $\{f_n\}$ converges pointwise on E , then there exists a function f such that for every $\epsilon > 0$ and for every x in E there is an integer N depending on ϵ and x such that $|f_n(x) - f(x)| < \epsilon \quad \forall n \geq N$. If $\{f_n\}$ converges uniformly on E , it is possible for each $\epsilon > 0$, to find one integer N which will do for all x in E . We say that the series $\sum_{n=1}^{\infty} f_n(x)$ converges uniformly on E if the $\{s_n\}$ of partial sums defined by $s_n(x) = \sum_{i=1}^n f_i(x)$ converges uniformly on E .

Theorem 4.34 Cauchy's Criterion for Uniform Convergence: The sequence of functions $\{f_n\}$, defined on E , converges uniformly on E iff for every $\epsilon > 0$ there exists an integer N such that $n, m \geq N, x \in E \Rightarrow |f_n(x) - f_m(x)| < \epsilon$.

Proof: For the 'only if' part we assume that $\{f_n\} \rightarrow f$ uniformly. To Prove: There exists N such that $x \in E \quad n, m \geq N \Rightarrow |f_n(x) - f_m(x)| < \epsilon$. Let $\epsilon > 0$ such that $|f_n(x) - f(x)| \leq \epsilon/2 \dots \dots (1) \quad \forall n \geq N \quad \forall x \in E$

Now, for $n, m \geq N$

$$\begin{aligned} |f_n(x) - f_m(x)| &= |f_n(x) - f(x) + f(x) - f_m(x)| \\ &\leq |f_n(x) - f(x)| + |f(x) - f_m(x)| \\ &\leq \epsilon/2 + \epsilon/2 \text{ (by (1))} \end{aligned}$$

$$(i.e.) |f_n(x) - f_m(x)| \leq \epsilon$$

For the 'if' part we assume that there exists $N > 0$ such that $n, m \geq N, x \in E \Rightarrow |f_n(x) - f_m(x)| \leq \epsilon \dots \dots (2)$

For fixed x , (2) implies that $\{f_n(x)\}$ is a Cauchy sequence $\therefore \{f_n(x)\} \rightarrow f(x) (|f_n(x) - f(x)| \rightarrow 0)$. To Prove: $\{f_n\} \rightarrow f$ uniformly. In (2), keeping n fixed and taking limit as $m \rightarrow \infty$ we get $|f_n(x) - f(x)| \leq \epsilon \quad \forall n \geq N \quad \forall x \in E$. $\therefore \{f_n\} \rightarrow f$ uniformly.

Theorem 4.35 Suppose

$$\lim_{n \rightarrow \infty} f_n = f(x), \quad (x \in E).$$

Put $M_n = \sup_{x \in E} |f_n(x) - f(x)|$, then $\{f_n\} \rightarrow f$ uniformly on E iff $M_n \rightarrow 0$ as $n \rightarrow \infty$.

Proof: For the 'only if' part, we assume that $\{f_n\} \rightarrow f$. To Prove: $M_n \rightarrow 0$ as $n \rightarrow \infty$. By hypothesis, given $\epsilon > 0$, there exists $N > 0$ such that $|f_n(x) - f(x)| \leq \epsilon \quad \forall n \geq N \quad \forall x \in E \Rightarrow \sup_{x \in E} |f_n(x) - f(x)| \leq \epsilon \quad \forall n \geq N \Rightarrow M_n \leq \epsilon \quad \forall n \geq N$ (i.e.) $M_n \rightarrow 0$ as $n \rightarrow \infty$. For the 'if' part, let $M_n \rightarrow 0$ as $n \rightarrow \infty$. Then there exists $N > 0$ such that $M_n \leq \epsilon \quad \forall n \geq N \Rightarrow \sup_{x \in E} |f_n(x) - f(x)| \leq \epsilon \quad \forall n \geq N \Rightarrow |f_n(x) - f(x)| \leq \epsilon \quad \forall n \geq N, x \in E \Rightarrow \{f_n\} \rightarrow f$ uniformly.

Theorem 4.36 Weierstrass M test for uniform convergence: Suppose $\{f_n\}$ is a sequence of function defined on E and suppose that $|f_1(x)| \leq M_n$

($x \in E, n = 1, 2, \dots$) then $\sum f_n$ converges uniformly on E if $\sum M_n$ converges.

Proof: Assume that $\sum M_n$ converges. To Prove: $\sum f_n$ converges uniformly. Let $\epsilon > 0$ be given. Let $\{s_n\}$ and $\{t_n\}$ be the sequences of partial sums of $\sum f_n$ and $\sum M_n$ respectively. Since $\sum M_n$ converges, $\{t_n\}$ also converges. Since any convergence sequence is a Cauchy sequence $\{t_n\}$ is also a Cauchy sequence. Then there exists $N > 0$ such that $|t_n - t_m| \leq \epsilon \quad \forall n, m \geq N$. Let $m > n (\geq N)$

$$|t_n - t_m| = \left| \sum_{k=n+1}^m M_k \right| \leq \epsilon \dots \dots (1)$$

Now, for $x \in E$,

$$\begin{aligned} |s_n(x) - s_m(x)| &= \left| \sum_{k=n+1}^m f_k(x) \right| \\ &\leq \sum_{k=n+1}^m |f_k(x)| \\ &\leq \sum_{k=n+1}^m M_k \leq \epsilon \text{ (by (1))} \end{aligned}$$

$$\therefore |s_n(x) - s_m(x)| < \epsilon$$

\therefore By Cauchy's criteria [4.34](#) the $\{s_n\}$ converges uniformly on E . $\therefore \sum f_n$ converges uniformly.

Theorem 4.37 [Uniform Convergence and Continuity] Suppose $\{f_n\}$ converges to f uniformly on a set E , in a metric space. Let x be a limit point of E and suppose that $\lim_{t \rightarrow x} f_n(t) = A_n (n = 1, 2, 3, \dots)$, then $\{A_n\}$ converges $\lim_{t \rightarrow x} f(t) = \lim_{n \rightarrow \infty} A_n$. In other words $\lim_{t \rightarrow x} \lim_{n \rightarrow \infty} f_n(t) = \lim_{n \rightarrow \infty} \lim_{t \rightarrow x} f_n(t)$.

Proof: Let $\epsilon > 0$ be given. Since $\{f_n\}$ converges to f uniformly on E , by Theorem [4.34](#), there exists an integer $N > 0$ such that $|f_n(t) - f_m(t)| \leq \epsilon \quad \forall n, m \geq N, t \in E \dots \dots (1)$

Letting $t \rightarrow x$ in (1) we get $|A_n - A_m| \leq \epsilon \quad \forall n, m \geq N (\because \lim_{t \rightarrow x} f_n(t) = A_n)$ (i.e.) $\{A_n\}$ is a Cauchy sequence of real numbers. Since \mathbb{R} is complete, $\{A_n\}$ converges to some A (in \mathbb{R}) (i.e.) $\{A_n\} \rightarrow A$. \therefore there exists $N_1 > 0$ such that $|A_n - A| \leq \epsilon/3, \quad \forall n \geq N_1 \dots \dots (2)$

Now,

$$\begin{aligned} |f(t) - A| &= |f(t) - f_n(t)| + |f_n(t) - A_n| + |(A_n - A)| \\ &\leq |f(t) - f_n(t)| + |f_n(t) - A_n| + |A_n - A| \dots \dots (3) \end{aligned}$$

Since $\{f_n\} \rightarrow f$ uniformly, there exists $N_2 > 0$ such that $|f_n(t) - f(t)| \leq \epsilon/3 \quad \forall n \geq N_2, t \in E \dots \dots (4)$

Since x is a limit point of E and $\therefore \lim_{t \rightarrow x} f_n(t) = A_n$, there exists a neighbourhood V of x such that $|f_n(t) - A_n| \leq \epsilon/3 \quad \forall t \in V \cap E \dots \dots$ (5)

Let $N_3 = \max\{N_1, N_2\}$. Now using (2),(4) and (5) in (3) we get

$$\begin{aligned} |f(t) - A| &\leq \epsilon/3 + \epsilon/3 + \epsilon/3 \quad \forall n \geq N_3 \quad \forall t \in V \cap E. \\ \text{(i.e.) } |f(t) - A| &\leq \epsilon \\ \text{(i.e.) } \lim_{t \rightarrow x} f(t) &= A \quad \text{(or)} \\ \lim_{t \rightarrow x} \lim_{n \rightarrow \infty} f_n(t) &= \lim_{n \rightarrow \infty} A_n \\ &= \lim_{n \rightarrow \infty} \lim_{t \rightarrow x} f_n(t) \end{aligned}$$

$$\therefore \lim_{t \rightarrow x} f(t) = \lim_{n \rightarrow \infty} A_n$$

Theorem 4.38 *If $\{f_n\}$ is a sequence of continuous functions on E , and if $\{f_n\}$ converges to f uniformly on E then f is continuous on E .*

Proof: Enough To Prove: $\lim_{t \rightarrow x} f(t) = f(x)$

$$\begin{aligned} \lim_{t \rightarrow x} f(t) &= \lim_{t \rightarrow x} \lim_{n \rightarrow \infty} f_n(t) \quad (\because f_n \rightarrow f \text{ uniformly}) \\ \lim_{t \rightarrow x} f(t) &= \lim_{n \rightarrow \infty} (\lim_{t \rightarrow x} f_n(t)) \quad \text{(by Theorem 4.37)} \\ &= \lim_{n \rightarrow \infty} f_n(x) \quad (\because f_n \text{ is continuous}) \\ &= f(x) \quad (\because f_n \rightarrow f \text{ uniformly}) \end{aligned}$$

Remark 4.39 *The converse of the above theorem need not be true. (i.e.) a sequence of continuous function may converge to a continuous function, although the convergence is not uniform.*

Example 4.40 $f_n(x) = n^2 x(1-x^2)^n$, $0 \leq x \leq 1$, $n = 1, 2, 3, \dots$. Clearly, each f_n is continuous. Also f is continuous. But the convergence is not uniform. By Theorem 4.33, for let

$$\begin{aligned} M_n &= \sup_{x \in [0,1]} |f_n(x) - f(x)| \\ &= \sup_{x \in [0,1]} |n^2 x(1-x^2)^n - 0| \\ &= n^2 \sup_{x \in [0,1]} \{x(1-x^2)^n\} \\ &\rightarrow 0 \text{ as } n \rightarrow \infty. \end{aligned}$$

By Theorem 4.33, the convergence is not uniform.

Theorem 4.41 [Dini's Theorem] *Suppose K is compact and*

- (a) $\{f_n\}$ is a sequence of continuous functions on K .
- (b) $\{f_n\}$ converges pointwise to a continuous functions f on K .
- (c) $f_n(x) \geq f_{n+1}(x) \quad \forall x \in K, n = 1, 2, 3, \dots$

then $f_n \rightarrow f$ uniformly on K .

Proof: Given K is compact. Let $g_n = f_n - f$. Since each f_n is continuous and f is continuous, g_n is continuous for all n . Since $\{f_n\}$ converges pointwise to f , $\{g_n\}$ converges pointwise to 0. Since $f_n(x) \geq f_{n+1}(x) \forall x \in K, n = 1, 2, \dots$ $f_n(x) - f(x) \geq f_{n+1}(x) - f(x)$. (i.e.) $g_n(x) \geq g_{n+1}(x) \forall x, n = 1, 2, \dots$ (i.e.) $\{g_n\}$ is also a monotonic decreasing sequence. To prove that $\{f_n\}$ converges to f uniformly. It is enough to prove that $\{g_n\}$ converges to 0 uniformly. Let $\epsilon > 0$ be given. For each n , let $K_n = \{x \in K | g_n(x) \geq \epsilon\}$. Now,

$$\begin{aligned} K_n &= \{x \in K | g_n(x) \geq \epsilon\} \\ &= \{x \in K | x \in g_n^{-1}[\epsilon, \infty)\} \\ &= g_n^{-1}[\epsilon, \infty). \end{aligned}$$

Since $[\epsilon, \infty)$ is closed in R and g_n is continuous, $g_n^{-1}[\epsilon, \infty)$ is closed in K . (i.e.) K_n is a closed subspace of the compact space K . $\therefore K_n$ is compact (\because every closed subspace of a compact space is compact). Claim: $K_n \supset K_{n+1}, n = 1, 2, 3, \dots$ Let $x \in K_{n+1} \Rightarrow g_{n+1}(x) \geq \epsilon$. But $g_n(x) \geq g_{n+1}(x)$ (by (1)). $\therefore g_n(x) \geq g_{n+1}(x) \geq \epsilon \Rightarrow g_n(x) \geq \epsilon \Rightarrow x \in K_n \therefore K_{n+1} \subset K_n$. Fix $x \in K$. Since $\{g_n\}$ converges pointwise to 0. $\{g_n(x)\} \rightarrow 0$. Then there exists $N(x) > 0$ such that $|g_n(x) - 0| < \epsilon \forall n \geq N(x) \Rightarrow g_n(x) < \epsilon \forall n \geq N(x) \Rightarrow x \notin K_n \forall n \geq N(x) \Rightarrow x \notin \bigcap_{n=1}^{\infty} K_n$. Since x is arbitrary, $\bigcap_{n=1}^{\infty} K_n = \phi \Rightarrow K_N = \phi$ for some N . $\therefore g_N(x) < \epsilon \forall x \in K$. But

$$\begin{aligned} 0 &\leq g_n(x) \leq g_N(x) < \epsilon \forall x \in K, \forall n \geq N \\ g_n(x) &< \epsilon \forall x \in K, \forall n \geq N \\ (\text{i.e.}) &|g_n(x) - 0| < \epsilon \forall x \in K, \forall n \geq N \end{aligned}$$

Hence $\{g_n\} \rightarrow 0$ uniformly.

Note 4.42 Compactness is really needed in the above theorem.

Example 4.43 $f_n(x) = \frac{1}{nx+1}, 0 < x < 1, n = 1, 2, 3, \dots$ $\{f_n\} \rightarrow f$ pointwise where $f(x) = 0 \forall x \in (0, 1)$ and $(0, 1)$ is not compact. Clearly, each f_n is continuous. Also f is continuous. Now,

$$\begin{aligned} n+1 &> n \\ \Rightarrow (n+1)x &> nx \\ \Rightarrow (n+1)x+1 &> nx+1 \\ \Rightarrow \frac{1}{(n+1)x+1} &< \frac{1}{nx+1} \\ \Rightarrow f_{n+1}(x) &< f_n(x) \end{aligned}$$

$\Rightarrow \{f_n\}$ is a decreasing sequence. But $\{f_n\} \rightarrow f$ uniformly. For, if $\{f_n\} \rightarrow f$ uniformly then, given $\epsilon > 0$, there exists $N > 0$ such that

$$\begin{aligned} |f_n(x) - f(x)| &\leq \epsilon \quad \forall n \geq N, \quad \forall x \in (0, 1) \\ \text{(i.e.) } \left| \frac{1}{nx+1} - 0 \right| &\leq \epsilon \quad \forall x \in (0, 1) \\ \left| \frac{1}{nx+1} \right| &\leq \epsilon \quad \forall x \in (0, 1) \\ \text{Put } x = \frac{1}{n}. \text{ Then } \frac{1}{2} &\leq \epsilon \\ &\Rightarrow \Leftarrow \end{aligned}$$

\therefore The convergence is not uniform.

Definition 4.44 If X is a metric space $\mathcal{C}(X)$ denotes the set of all complex valued continuous bounded functions with domain X . $\mathcal{C}(X) = \{f/f : X \rightarrow c, f \text{ is continuous and bounded}\}$. If X is compact, $\mathcal{C}(X) = \{f/f : X \rightarrow c, f \text{ is continuous}\}$ (\because any continuous function on a compact space is bounded). For any f in $\mathcal{C}(f)$, $\sup \|f\| = \sup_{x \in X} |f(x)|$, since f is bounded $\|f\| < \infty$.

Result 4.45 $\mathcal{C}(X)$ is a metric space. Given $f, g \in \mathcal{C}(X)$ define

$$\begin{aligned} \text{(i) } d(f, g) &= \|f - g\| \\ &= \sup_{x \in E} |f(x) - g(x)| \\ &\geq 0 \\ \therefore d(f, g) &\geq 0 \\ \text{(ii) } d(f, g) &= \sup_{x \in E} |f(x) - g(x)| \\ &= \sup_{x \in E} |g(x) - f(x)| \\ &= \|g - f\| \\ &= d(f, g) \\ \text{(iii) } d(f, g) = 0 &\Leftrightarrow \|f - g\| = 0 \\ &\Leftrightarrow \sup_{x \in E} |f(x) - g(x)| \\ &\Leftrightarrow |f(x) - g(x)| = 0 \quad \forall x \in E \\ &\Leftrightarrow f(x) = g(x) \\ &\Leftrightarrow f = g \end{aligned}$$

$$\begin{aligned}
(iv) \quad d(f, g) &= \|f - g\| \\
&= \sup_{x \in E} |f(x) - g(x)| \\
&= \sup_{x \in E} |(f(x) - h(x)) + (h(x) - g(x))| \\
&\leq \sup_{x \in E} \{|(f(x) - h(x))| + |(h(x) - g(x))|\} \\
&\leq \sup_{x \in E} |(f(x) - h(x))| + \sup_{x \in E} |(h(x) - g(x))| \\
&= \|f - h\| + \|h - g\| \\
&= d(f, h) + d(h, g) \\
(i.e.) \quad d(f, g) &\leq d(f, h) + d(h, g)
\end{aligned}$$

$\therefore (\mathcal{C}(X), d)$ is a metric space.

Result 4.46 (Analogue of Theorem 4.35) A sequence $\{f_n\} \rightarrow f$ with respect to the metric space $\mathcal{C}(X)$ iff $\{f_n\} \rightarrow f$ uniformly on X .

Proof: 'only if' part:

Assume that $\{f_n\} \rightarrow f$ in $\mathcal{C}(X)$. $\|f_n - f\| \rightarrow 0$ as $n \rightarrow \infty$ (i.e.) $\sup_{x \in E} |f_n(x) - f(x)| \rightarrow 0$ as $n \rightarrow \infty$ (i.e.) $M_n \rightarrow 0$ as $n \rightarrow \infty$ (Theorem 4.35). $\{f_n\} \rightarrow f$ uniformly (by Theorem 4.35)

'if' part:

Suppose $\{f_n\} \rightarrow f$ uniformly. Then $M_n \rightarrow 0$ as $n \rightarrow \infty$ (Theorem 4.35) (i.e.) $\sup_{x \in E} |f_n(x) - f(x)| \rightarrow 0$ as $n \rightarrow \infty$ (i.e.) $\|f_n - f\| \rightarrow 0$ as $n \rightarrow \infty$. $\therefore \{f_n\} \rightarrow f$ in $\mathcal{C}(X)$

Note 4.47 (i) Closed subsets of $\mathcal{C}(X)$ are called uniformly closed subsets.
(ii) If $A \subset \mathcal{C}(X)$ then the closure of A is called the uniform closure of A .

Theorem 4.48 $\mathcal{C}(X)$ is a complete metric space.

Proof: Let $\{f_n\}$ be a Cauchy sequence in $\mathcal{C}(X)$. Let $\epsilon > 0$ be given. Then there exists $N > 0$ such that $\|f_n - f_m\| < \epsilon \quad \forall n, m \geq N$ (1)

(i.e.) $\sup_{x \in E} |f_n(x) - f_m(x)| \leq \epsilon \quad \forall n, m \geq N. \Rightarrow |f_n(x) - f_m(x)| \leq \epsilon \quad \forall n, m \geq N, x \in X$. By Theorem 4.34, guarantees that $\{f_n\}$ converges uniformly, say f . (i.e.) $\lim_{n \rightarrow \infty} f_n(x) = f(x), x \in X$. Claim: $f \in \mathcal{C}(X)$. Since each f_n is continuous and $\{f_n\} \rightarrow f$ uniformly (Theorem 4.38). Theorem 4.38 demands that f is also continuous. Again, since $\{f_n\} \rightarrow f$ uniformly, there exists $N_1 > 0$ such that $|f_n(x) - f(x)| < 1 \quad \forall n \geq N_1, x \in X$. In particular, $|f_{N_1}(x) - f(x)| < 1$ (2) $\forall x \in X$

Since $f_{N_1}(x) \in \mathcal{C}(X), |f_{N_1}(x)| \leq K$ (3) $\forall x \in X$

Now,

$$\begin{aligned}
|f(x)| &= |(f(x) - f_{N_1}(x)) + f_{N_1}(x)| \\
|f(x)| &\leq |f(x) - f_{N_1}(x)| + |f_{N_1}(x)| \\
&< 1 + K \quad (\text{by (2) and (3)}) \quad \forall x \in X
\end{aligned}$$

$$(i.e.) |f(x)| < 1 + K \quad \forall x \in X.$$

$\therefore f$ is bounded. Hence $f \in \mathcal{C}(X)$. It remains to prove that $\{f_n\} \rightarrow f$ in $\mathcal{C}(X)$. For, $\{f_n\} \rightarrow f$ uniformly $\Rightarrow M_n \rightarrow 0 \Rightarrow \sup_{x \in X} |f_n(x) - f(x)| \rightarrow 0$ as $n \rightarrow \infty$ (by Theorem 4.35) $\Rightarrow \|f_n - f\| \rightarrow 0$ as $n \rightarrow \infty$. So $\{f_n\} \rightarrow f$ in the metric space $\mathcal{C}(X)$. $\therefore \mathcal{C}(X)$ is a complete metric space.

Uniform Convergence and Integration

Theorem 4.49 Let α be monotonically increasing on $[a, b]$. Suppose $f_n \in \mathcal{R}(\alpha)$ on $[a, b]$ for $n = 1, 2, 3, \dots$ and suppose $f_n \rightarrow f$ uniformly on $[a, b]$ then $f_n \in \mathcal{R}(\alpha)$ on $[a, b]$ and $\int_a^b f d\alpha = \lim_{n \rightarrow \infty} \int_a^b f_n d\alpha$.

Proof: Let $\epsilon_n = \sup_{a \leq x \leq b} |f(x) - f_n(x)| \dots \dots$ (1) (Theorem 4.35)

$$\begin{aligned} \therefore |f - f_n| &\leq \epsilon_n \quad \forall n = 1, 2, 3, \dots \\ &-\epsilon_n \leq f - f_n \leq \epsilon_n \\ \Rightarrow f_n - \epsilon_n &\leq f \leq f_n + \epsilon_n \\ \Rightarrow \int_a^b (f_n - \epsilon_n) d\alpha &\leq \int_a^b f d\alpha \leq \int_a^b (f_n + \epsilon_n) d\alpha \dots \dots (2) \\ \Rightarrow \int_a^b f_n d\alpha - \int_a^b \epsilon_n d\alpha &\leq \int_a^b f d\alpha \leq \int_a^b f_n d\alpha + \int_a^b \epsilon_n d\alpha \\ \Rightarrow \int_a^{\bar{b}} f d\alpha - \int_a^{\bar{b}} f_n d\alpha &\leq (\int_a^b f_n d\alpha + \int_a^b \epsilon_n d\alpha) - (\int_a^b f_n d\alpha - \int_a^b \epsilon_n d\alpha) \\ &= 2 \int_a^b \epsilon_n d\alpha \\ &= 2\epsilon_n \int_a^b d\alpha \\ &= 2\epsilon_n [\alpha(b) - \alpha(a)] \\ (i.e.) \int_a^{\bar{b}} f d\alpha - \int_a^{\bar{b}} f_n d\alpha &\leq 2\epsilon_n (\alpha(b) - \alpha(a)) \\ &\rightarrow 0 \quad (\because \epsilon_n \rightarrow 0 \text{ as } f_n \rightarrow f \text{ uniformly by theorem 4.35}) \\ \therefore \int_a^{\bar{b}} f d\alpha &= \int_a^{\bar{b}} f_n d\alpha \end{aligned}$$

Hence $f \in \mathcal{R}(\alpha)$. **II part:** To prove:

$$\int_a^b f d\alpha = \lim_{n \rightarrow \infty} \int_a^b f_n d\alpha$$

Now, (2) \Rightarrow

$$\begin{aligned}
 \int_a^b (f_n - \epsilon_n) d\alpha &\leq \int_a^b f d\alpha \leq \int_a^b (f_n + \epsilon_n) d\alpha \\
 \int_a^b f_n d\alpha - \int_a^b \epsilon_n d\alpha &\leq \int_a^b f d\alpha \leq \int_a^b f_n d\alpha + \int_a^b \epsilon_n d\alpha \\
 \Rightarrow \int_a^b f_n d\alpha - \epsilon_n \int_a^b d\alpha &\leq \int_a^b f d\alpha \leq \int_a^b f_n d\alpha + \epsilon_n \int_a^b d\alpha \\
 &\Rightarrow -\epsilon_n \int_a^b d\alpha \leq \int_a^b f d\alpha - \int_a^b f_n d\alpha \leq \epsilon_n \int_a^b d\alpha \\
 \Rightarrow \left| \int_a^b f d\alpha - \int_a^b f_n d\alpha \right| &\leq \epsilon_n \int_a^b d\alpha \\
 &= \epsilon_n (\alpha(b) - \alpha(a)) \\
 &\rightarrow 0 \text{ as } n \rightarrow \infty (\because \epsilon_n \rightarrow 0) \\
 \lim_{n \rightarrow \infty} \int_a^b f_n d\alpha &= \int_a^b f d\alpha.
 \end{aligned}$$

Corollary 4.50 *If $f_n \in \mathcal{R}(\alpha)$ on $[a, b]$ and if $f(x) = \sum_{n=1}^{\infty} f_n(x)$ ($a \leq x \leq b$), the series converges uniformly on $[a, b]$, then $\int_a^b f d\alpha = \sum_{n=1}^{\infty} \int_a^b f_n d\alpha$. (the series may be integrated term by term)*

Proof: Given $\sum f_n = f$ (uniformly). Let $s_n = \sum_{k=1}^n f_k$. By hypothesis $\{s_n\} \rightarrow f$ uniformly. By Theorem [4.49](#),

$$\begin{aligned}
 \int_a^b f d\alpha &= \lim_{n \rightarrow \infty} \int_a^b s_n d\alpha \\
 &= \lim_{n \rightarrow \infty} \int_a^b \left(\sum_{k=1}^n f_k \right) d\alpha \\
 &= \lim_{n \rightarrow \infty} \sum_{k=1}^n \left(\int_a^b f_k d\alpha \right) \\
 &= \sum_{k=1}^{\infty} \int_a^b f_k d\alpha
 \end{aligned}$$