MAR GREGORIOS COLLEGE OF ARTS & SCIENCE

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DEPARTMENT OF MATHEMATICS

SUBJECT NAME: GRAPH THEORY

SUBJECT CODE: TEM6B

SEMESTER: VI

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SYLLABUS

UNIT-1

Graphs and Subgraphs : introduction – definition and examples, degrees, sub graphs ,isomorphism, independent sets and covering, intersection graphs and line graphs , matrices, operation on graphs

UNIT-2

Degree sequences and connectedness : Degree sequences and graphic sequences – simple problems. Walks , trails, path , connectedness and components, blocks , connectivity - simple problems.

UNIT-3

Eulerian and Hamiltonian graphs

UNIT-4

Trees : characterization of trees , centre of a tree – simple problems.

Planarity : definition and properties, characterization of planar graphs .

UNIT-5

Directed graphs : definition and basic properties , path and connections , digraphs and matrices, tournaments.

TEXT BOOK : Invitation to graph theory by S. Arumugam and S. Ramachandran

UNIT-1 Graphs and Subgraphs

1.1 Introduction

Graph theory is a branch of mathematics which deals the problems, with the help of diagrams. There are may applications of graph theory to a wide variety of subjects which include operations research, physics, chemistry, computer science and other branches of science. In this chapter we introduce some basic concepts of graph theory and provide variety of examples. We also obtain some elementary results.

1.2 What is a graph ?

Definition 1.2.1. A graph G consists of a pair (V(G), X(G)) where V(G) is a non empty finite set whose elements are called **points or vertices** and X(G) is a set of unordered pairs of distinct elements of V(G). The elements of X(G) are called **lines or edges** of the graph G. If $x = \{u, v\} \in X(G)$, the line x is said to join u and v. We write x = uv and we say that the points u and v are **adjacent**. We also say that the point u and the line x are incident with each other. If two lines x and y are incident with a common point then they are called **adjacent lines**. A graph with p points and q lines is called a (p,q) graph. When there is no possibility of confusion we write V(G) = V and X(G) = X.



Figure 1.1: A an example of a (4,3) graph

1.3 Representation of a graph

It is customary to represent a graph by a diagram and refer to the diagram itself as the graph. Each point is represented by a small dot and each line is represented by a line segment joining the two points with which the line is incident. Thus a diagram of graph depicts the incidence relation holding between its points and lines. In drawing a graph it is immaterial whether the lines are drawn straight or curved, long or short and what is important is the incidence relation between its points and lines.

Example 1.3.1.

- Let V = {a, b, c, d} and X = {{a, b}, {a, c}{a, d}}, G = (V, X) is a (4, 3) graph. This graph can be represented by the diagram given in figure
 In this graph the points a and b are adjacent whereas b and c are nonadjacent.
- 2. Let $V = \{1, 2, 3, 4\}$ and $X = \{\{1, 2\}, \{1, 3\}, \{1, 4\}, \{2, 3\}, \{2, 4\}, \{3, 4\}\}$. Then G = (V, X) is a (4, 6) graph. This graph is represented by the diagram given in figure 1.2 Although the lines $\{1, 2\}$ and $\{2, 4\}$ intersect in the diagram, their intersection is not a point of the graph. Figure 1.3 is another diagram for the graph given in figure 1.2
- 3. The (10, 15) graph given in figure **1.4** is called the **Petersen graph**.

Remark 1.3.1. The definition of a graph does not allow more than one line joining two points. It also does not allow any line joining a point to itself. Such a line joining a point to itself is called a **loop**.



Figure 1.2: An example of a (4, 6) graph



Figure 1.3: Another representation of graph shown in figure **1.1**



Figure 1.4: Peterson graph



Figure 1.5: A multiple graph



Figure 1.6: A pseudograph

Definition 1.3.1. If more than one line joining two vertices are allowed, the resulting object is called a **multigraph**. Line joining the same points are called **multi lines**. If further loops are also allowed, the resulting object is called **Pseudo graph**.

Example 1.3.2. Figure 1.5 is a multigraph and figure 1.6 is a pseudo graph.

Remark 1.3.2. Let G be a (p,q) graph. Then $q \leq \begin{pmatrix} p \\ 2 \end{pmatrix}$ and $q = \begin{pmatrix} p \\ 2 \end{pmatrix}$ iff any two distinct points are adjacent.

Definition 1.3.2. A Graph in which any two distinct points are adjacent is called a **complete graph**. The complete graph with p points is denoted by K_p . K_3 is called a triangle. The graph given Fig. **1.3** is K_4 and K_5 is shown in Fig.**1.7**



Figure 1.7: K_5

Definition 1.3.3. A graph whose edge set is empty is called a **null graph** or a **totally disconnected graph**.

Definition 1.3.4. A graph G is called labeled if its p points are distinguished from one another by names such as $v_1, v_2 \cdots v_p$.

The graphs given in Fig. **1.1** and Fig. **1.3** are labelled graphs and the graph in Fig. **1.7** is an unlabelled graph.

Definition 1.3.5. A graph G is called a **bigraph** or **bipartite graph** if V can be partitioned into two disjoint subsets V_1 and V_2 such that every line of G joins a point of V_1 to a point of V_2 . (V_1, V_2) is called a **bipartition** of G. If further G contains every line joining the points of V_1 to the points of V_2 then G is called a **complete bigraph**. If V_1 contains m points and V_2 contains npoints then the complete bigraph G is denoted by $K_{m,n}$. The graph given in Fig. \square is $K_{1,3}$. The graph given in Fig. \square is $K_{3,3}$. $K_{1,m}$ is called a **star** for $m \ge 1$.

1.4 Exercise

- 1. Draw all graphs with 1, 2, 3 and 4 points.
- 2. Find the number of points and lines in $K_{m,n}$.
- 3. Let $V = \{1, 2, 3, \dots, n\}$. Let $X = \{\{i, j\} | i, j \in V \text{ and are relatively prime}\}$. The resulting graph (V, X) is denoted by G_n . Draw G_4 and G_5 .

1.5 Degrees

Definition 1.5.1. The **degree** of a point v_i in a graph G is the number of lines incident with v_i . The degree of v_i is denoted by $d_G(v_i)$ or deg v_i or $d(v_i)$.



Figure 1.8: bigraph

A point v of degree 0 is called an **isolated point**. A point v of degree 1 is called an endpoint.

Theorem 1.5.1. The sum of the degrees of the points of a graph G is twice the number of lines. That is, $\sum_i \deg v_i = 2q$.

Proof. Every line of G is incident with two points. Hence every line contribute 2 to the sum of the degrees of the points. Hence $\sum_i degv_i = 2q$.

Corollary 1.5.1. In any graph G the number of points of odd degree is even.

Proof. Let v_1, v_2, \dots, v_k denote the point of odd degree and w_1, w_2, \dots, w_m denote the points of even degree in G. By theorem [1.5.1], $\sum_{i=1}^k \deg(v_i) + \sum_{i=1}^w \deg w_i = 2q$ which is even. Further $\sum_{i=1}^m \deg w_i$ is even. Hence $\sum_{i=1}^m \deg v_i$ is also even. But $\deg v_i$ is odd for each i. Hence k must be even.

Definition 1.5.2. For any graph G, we define

$$\delta(G) = \min\{\deg v/v \in V(G)\} \text{ and}$$
$$\Delta(G) = \max\{\deg v/v \in V(G)\}.$$

It all the points of G have the same degree r, then $\delta(G) = \Delta(G) = r$ and this case G is called a **regular graph** of degree r. A regular graph of degree 3 is called a cubic graph. For example, the complete graph K_p is regular of degree p-1.

Theorem 1.5.2. Every cubic graph has an even number of points.

Proof. Let G be a cubic graph with p points, then $\sum \deg v = 3p$ which is even by theorem [1.5.1]. Hence p is even.

1.6 Solved Problems

Problem 1. Let G be a (p,q) graph all of whose points have degree k or k+1. If G has t > 0 points of degree k, show that t = p(k+1) - 2q. Solution

Since G has t points of degree k, the remaining p-t points have degree k+1. Hence $\sum_{v \in V} d(v) = tk + (p-t)(k+1)$.

$$\therefore tk + (p-t)(k+1) = 2q$$
$$\therefore t = p(k+1) - 2q.$$

Problem 2. Show that in any group of two or more people, there are always two with exactly the same number of friends inside the group.

Solution. We construct a graph G by taking the group of people as the set of points and joining two of them if they are friends, then degv is equal to number of friends of v and hence we need only to prove that at least two points of G have the same degree. Let $V(G) = \{v_1, v_2, \dots, v_p\}$. Clearly $0 \leq \deg v_i \leq p-1$ for each i. Suppose no two points of G have the same degree. Then the degrees of v_1, v_2, \dots, v_p . are the integers $0, 1, 2, \dots, p-1$ in some order. However a point of degree p-1 is joined to every other point of G and hence no point can have degree zero which is a contradiction. Hence there exist two points of G with equal degree.

Problem 3. Prove that $\delta \leq 2q/p \leq \Delta$

Solution

Let $V(G) = \{v_1, v_2, \cdots, v_p\}$. We have $\delta \leq \deg v_i \leq \Delta$. for all *i*. Hence

$$p\delta \leq \sum_{i=1}^{p} \deg v_i \leq p\Delta.$$

$$\therefore p\delta \leq 2q \leq p\Delta \text{ (by theorem 2.1)}$$

$$\therefore \delta \leq \frac{2q}{p} \leq \Delta$$

Problem 4. Let G be a k-regular bibgraph with bipartion (V_1, V_2) and k > 0. Prove that $|V_1| = |V_2|$.

Solution

Since every line of G has one end in V_1 and other end in V_2 it follows that

 $\sum_{v \in V_1} d(v) = \sum_{v \in V_2} d(v) = q. \text{ Also } d(v) = k \text{ for all } v \in V = V_1 \cup V_2. \text{ Hence}$ $\sum_{v \in V_1} d(v) = k|V_1| \text{ and } \sum_{v \in V_2} d(v) = k|V_2| \text{ so that } k |V_1| = k|V_2|. \text{ Since } k > 0,$ we have $|V_1| = |V_2|.$

1.7 Exercise

- 1. Given an example of a regular graph of degree 0
- 2. Give three examples for a regular graph of degree 1
- 3. Give three examples for a regular graph of degree 2
- 4. What is the maximum degree of any point in a graph with p points?
- 5. Show that a graph with p points is regular of degree p-1 if and only if it is complete
- 6. Let G be a graph with at least two points show that G contains two vertices of the same degree
- 7. A (p,q) graph has t points of degree m and all other points are of degree n. Show that (m-n)t + pn = 2q.

1.8 Subgraphs

Definition 1.8.1. A graph $H = (V_1, X_1)$ is called **subgraph** of G = (V, X). $V_1 \subseteq V$ and $X_1 \subseteq X$. If H is a subgraph of G we say that G is a **supergraph** of H. H is called a **spanning subgraph** of G if H is the maximal subgraph of G with point set V_1 . Thus, if H is an induced subgraph of G, two points are adjacent in H they are adjacent in G. If $V_2 \subseteq V$, then the induced subgraph of G induced by V_2 and is denoted by G[X]. If $X_2 \subseteq X$, then the sub graph of G with line set X_2 and is denoted by $G[X_2]$

Examples. Consider the petersen graph G given in Fig. 1.4. The graph given in Fig. 1.9 is a subgraph of G. The graph given in Fig. 1.10 is an induced subgraph of G. The graph given in Fig. 1.10 is an induced subgraph of G. The graph given in Fig. 1.11 is a spanning subgraph of G.



Figure 1.9: Subgraph



Figure 1.10: Induced subgraph



Figure 1.11: Spanning subgraph



Figure 1.12:

Definition 1.8.2. Let G = (V, X) be a graph.Let $v_i \in V$. The subgraph of G obtained by removing the point v_i and all the lines incident with v_i is called the **subgraph obtained by the removal of the point** v_i and is denoted by $G \cdot v_i$. Thus if $G - v_i = (V_i, X_i)$ then $V_i = V - v_i$ and $X_i = \{x/x \in X \text{ and } x \text{ is not incident with } v_i\}$. Clearly $G - v_i$ is an induced subgraph of G. Let $x_i \in X$. Then $G - x_i = (V, X - x_j)$ is called the subgraph of G obtained by the removal of the line x_j . Clearly $G - x_j$ is a spanning subgraph of Gwhich contains all the lines of G except x_j . The removal of a set of points or lines from G is defined to be the removal of single elements in succession.

Definition 1.8.3. Let G = (V, X) be a graph. Let v_i, v_j be two points which are not adjacent in G. Then $G + v_i v_j = (V, X \bigcup \{v_i, v_j\})$ is called the graph obtained by **the addition of the line** $v_i v_j$ to G

Clearly $G+v_iv_j$ is the smallest super graph of G containing the line v_iv_j .We listed these concepts in Fig1.12. The proof given in the following theorem is typical of several proofs in theory.

Theorem 1.8.1. The maximum number of lines among all p point graph no triangles is $\left[\frac{p^2}{4}\right]$. ([x] denotes the greatest integer not exceeding the the real number x).

Proof. The result can be easily verified for $p \le 4$. For p > 4, we will prove by induction separately for odd p and for every p.

Part 1. For odd p.

Suppose the result is true for all odd $p \leq 2n + 1$. Now let G be a (p, q) graph with p = 2n + 3 and no triangles. If q = 0, then $q \leq \left[\frac{p^2}{4}\right]$. Hence let q > 0. Let u and v be a pair of adjacent points. The subgraph $G' = G - \{u, v\}$ has

2n + 1 points and no triangles. Hence induction hypothesis,

$$q(G') \le \left[\frac{(2n+1)^2}{4}\right] = \left[\frac{4n^2 + 4n + 1}{4}\right]$$
$$= \left[n^2 + n + \frac{1}{4}\right] = n^2 + n$$

Since G has no triangles, no point of G' can be adjacent to both u and G. Now, lines in G are of three types.

- 1. Lines of $G'(\leq n^2 + n \text{ in number by}(1))$
- 2. Lines between G' and $\{u, v\} (\leq 2n + 1 innumber by(2))$

3. Line uv

Hence

$$q \le (n^2 + n) + (2n + 1) + 1 = n^2 + 3n + 2$$

= $\frac{1}{4}(4n^2 + 12n + 8)$
= $\left(\frac{4n^2 + 12n + 9}{4} - \frac{1}{4}\right)$
= $\left[\frac{(2n + 3)^2}{4}\right] = \left[\frac{p^2}{4}\right]$

Also for p = 2n + 3, the graph $K_{n+1,n+2}$ has no triangles and has $(n + 1)(n+2) = n^2 + 3n + 2 = \left[\frac{p^2}{4}\right]$ lines. Hence this maximum q is attained. **Part 2.** For even p.

Suppose the result is true for all even $p \leq 2n$. Now let G be a (p,q) graph with p = 2n + 2 and no triangles. As before, let u and v be a pair of adjacent points in G and let $G' = G - \{u, v\}$.

Now G' has 2n points and no triangles. Hence by hypothesis,

$$q(G') \le \left[\frac{(2n)^2}{4}\right] = n^2$$

Lines in G are of three types.

- (i) Lines of G'
- (ii) Lines between G' and $\{u, v\}$
- (iii) line uv.

Hence $q \leq n^2 + 2n + 1 = (n+1)^2 = \frac{(2n+2)^2}{4} = [p^2/4]$. Hence the result holds for even p also. We see that for p = 2n+2. $K_{n+1,n+1}$ is a $(p, [\frac{p^2}{4}]$ graph without triangles.

1.9 Exercise

- 1. Show that $K_p v = K_{p-1}$ for any point v of K_p .
- 2. Show that an induced subgraph of a complete graph is complete.
- 3. Let G = (V, X) be a (p, q) graph. Let $v \in V$ and $x \in X$. Find the number of points and lines in G v and G x.
- 4. If every induced proper subgraph of a graph G is complete and p > 2 then show that G is complete.
- 5. If every induced proper subgraph of a graph G is totally disconnected, then show that G is totally disconnected.
- 6. Show that in a graph G every induced graph is complete iff every induced graph with two points is complete.

1.10 Isomorphism

Definition 1.10.1. Two graphs $G_1 = (V_1, X_1)$ and $G_2 = (V_2, X_2)$ are said to be **isomorphic** if there exists a bijection $f : V_1 \to V_2$ such that u, v are adjacent in G_1 if and only if f(u), f(v) are adjacent in G_2 . If G_1 is isomorphic to G_2 , we write $G_1 \cong G_2$. The map f is called an isomorphism from G_1 to G_2 .

- **Example 1.10.1.** 1. The graph given in Fig. 2.2 and Fig. 2.3 are isomorphic.
 - 2. The two graphs given in Fig. 1.13 are isomorphic. $f(u_i) = v_i$ is an isomorphism between these two graphs.



Figure 1.13:



Figure 1.14:

3. The three graphs given in Fig. 1.14 are isomorphic with each other.

Theorem 1.10.1. Let f be an isomorphism of the graph $G_1 = (V_1, X_1)$ to the graph $G_2 = (V_2, X_2)$. Let $v \in V_1$. Then deg $v = \deg f(v)$. i.e., isomorphism preserves the degree of vertices.

Proof. A point $u \in V_1$ is adjacent to v in G_1 iff f(u) is adjacent to f(v) in G_2 . Also f is bijection. Hence the number of points in V_1 which are adjacent to v is equal to the number of points in V_2 which are adjacent to f(v). Hence deg $v = \deg f(v)$.

Remark 1.10.1. Two isomorphic graphs have the same number of points and the same number of lines. Also it follows from Theorem [1.10.]]that two isomorphic graphs have equal number of points with a given degree. However these conditions are not sufficient to ensure that two graphs are isomorphic. For example consider the two graphs given in figure [1.15]. By theorem [1.10.]], under any isomorphism w_4 must correspond to $v_3; w_1, w_5, w_6$ must correspond to v_1, v_5, v_6 in some order. The remaining two points w_2, w_3 are adjacent whereas v_2, v_4 are not adjacent. Hence there does not exist an isomorphism



Figure 1.15:



Figure 1.16:

between these two graphs. However both graphs have exactly one vertex of degree 3, three vertices of degree 1 and two vertices of degree 2.

Definition 1.10.2. An isomorphism of a graph G onto itself is called an **automorphism** of G.

Remark 1.10.2. Let $\Gamma(G)$ denote the set of all automorphism of G. Clearly the identity map $i : V \to V$ defined by i(v) = v is an automorphism of Gso that $i \in \Gamma(G)$. Further if α and β are automorphisms of G then $\alpha.\beta$ and α^{-1} are also automorphism of G. Hence $\Gamma(G)$ is a group and is called the **automorphism group** of G.

Definition 1.10.3. Let G = (V, X) be a graph. The **complement** \overline{G} of G is defined to be the graph which has V as its set of points and two points are adjacent in \overline{G} iff they are not adjacent in G. G is said to be a **self complementary** graph if G is isomorphic to \overline{G} .

For example the graphs given in Fig. 1.16 are self complementary graphs.

It has been conjectured by Ulam that the collection of vertex deleted subgraphs G - v determines G up to isomorphism.

Solved Problems

Problem 5. Prove that any self complementary graphs has 4n or 4n+1 points

Solution. Let G = (V(G), X(G)) be a self complementary graph with p points.

Since G is self complementary, G is isomorphic to \overline{G} . $\therefore |X(G)| = |X(\overline{G})|$. Also

$$|X(G)| + |X(\overline{G})| = {p \choose 2} = \frac{p(p-1)}{2}$$

$$\therefore 2|X(G)| = \frac{p(p-1)}{2}$$

$$\therefore |X(G)| = \frac{p(p-1)}{4} \text{ is an integer.}$$

Further one of p or p-1 is odd. Hence p or p-1 is a multiple of 4. $\therefore p$ is of the the form 4n or 4n + 1.

Problem 6. Prove that $\Gamma(G) = \Gamma(\overline{G})$.

Solution. Let $f \in \Gamma(G)$ and let $u, v \in V(G)$.

Then u, v are adjacent in $\overline{G} \Leftrightarrow u, v$ are not adjacent in G.

 $\Leftrightarrow \ f(u), f(v) \text{ are not adjacent in } G$

(since f is an automorphism of G)

 $\Leftrightarrow f(u), f(v) \text{ are adjacent in } \overline{G}.$

Hence f is an automorphism of \overline{G} .

 $\therefore f \in \Gamma(\overline{G})$ and hence $\Gamma(G) \subseteq \Gamma(\overline{G})$.

Similarly $\Gamma(\overline{G}) \subseteq \Gamma(G)$ so that $\Gamma(G) = \Gamma(\overline{G})$.

1.11 Exercise

- 1. Prove that any graph with p points is isomorphic to a subgraph of K_p .
- 2. Show that isomorphism is an equivalence relation among graphs.
- 3. Show that the two graphs given in Fig. 2.17 are not isomorphic.

- 4. Show that up to isomorphism there are exactly four graphs on three vertices.
- 5. Prove that a graph G is complete iff \overline{G} is totally disconnected.
- 6. Let G be (p,q) graph $deg_{\overline{G}}(v) = p 1 deg_G(v)$.
- 7. Prove that $\Gamma(K_n) \cong S_n$, the symmetric group of degree n.

1.12 Ramsey Numbers

We start by considering the following puzzle. In any set of six people there will always be either a subset of three who are mutually acquainted, or a subset of three who are mutually strangers. This situation may be represented by a graph G with six points representing the six people in which adjacency indicates acquaintances. The above puzzle then asserts that G contains three mutually adjacent points or three mutually non-adjacent points. Equivalently G or \overline{G} contains a triangle.

Theorem 1.12.1. For any graph G with 6 points, G or \overline{G} contains a triangle.

Proof. Let v be a point of G. Since G contains 5 points other than v, v must be either adjacent to three points in G or non-adjacent to three points in G.Hence v must be adjacent to three points either in G or in \overline{G} Without loss of generality, let us assume that v is adjacent to three points u_1, u_2, u_3 in G. If two of these three points are adjacent, G contains a triangle. Otherwise these three points from a triangle in \overline{G} . Hence G or \overline{G} contains a triangle. \Box

It is easy to see that the above theorem is not true for graphs with less than 6 points and we have this as an exercise to the reader. Thus 6 is the smallest positive integer such that any graph G on 6 points contains K_3 or $\overline{K_3}$. This suggests the following general question. What is the least positive integer r(m, n) such that for any graph G with r(m, n) points, G contains K_m or $\overline{K_n}$. For example r(3,3) = 6. The numbers r(m,n) are called Ramsey numbers after F. Ramsey who proved the existence of r(m, n). The determination of the Ramsey numbers is difficult unsolved problem. **Solved Problems** **Problem 7.** Prove that r(m, n) = r(n, m).

Solution Let r(m,n) = s. Let G be any graph on s points. Then \overline{G} also has s points. Since $r(m,n) = s,\overline{G}$ has either K_m or $\overline{K_n}$ as an induced subgraph. Hence G has K_n or $\overline{K_m}$ as an induced subgraph. Thus an arbitrary graph on s points contains K_n or $\overline{K_m}$ as an induced subgraph. $\therefore r(n,m) \leq s$. i.e, $r(n,m) \leq r(m,n)$. Interchanging m and n we get $r(m,n) \leq r(n,m)$. Hence r(m,n) = r(n,m).

Problem 8. Prove that r(2,2) = 2

Solution Let G be a graph on 2 points. Let $V(G) = \{u, v\}$. Then u and v are either adjacent in G or adjacent in \overline{G} . Hence G or \overline{G} contains K_2 . Thus if G is any graph on two points, then G or \overline{G} contains K_2 and clearly 2 is the least positive integer with this property. Hence r(2, 2) = 2.

1.13 Exercise

- 1. Prove, by suitable examples, that theorem [1.12.1] is not true graphs with less than 6 points.
- 2. Find r(1, 1).
- 3. Find r(k, 1) for any positive integer k.
- 4. Find r(2,3).
- 5. Find r(2, k) for any positive integer k.

1.14 Indepedent Sets and Coverings

Definition 1.14.1. A covering of a graph G = (V, X) is a subset K of V such that every line of G is incident with a vertex in K. A covering K is called a **minimum covering** if G has no covering K' with |K'| < |K|. The number of vertices in a minimum covering of G is called the **covering number** of G and is denoted by β .

A subset S of V is called an **independent set** of G if no two vertices S are adjacent in G. An independent set S is said to be **maximum** if G has

no independent set S' with |S'| > |S|. The number of vertices in a maximum independent set is called **independence number** of G and is denoted α .

Example

Consider the graph given in Fig. **1.18** $\{v_6\}$ is an independent set. $\{v_1, v_3\}$ is a maximum independent set. $\{v_1, v_2, v_3, v_4, v_5\}$ is a covering and $\{v_2, v_3, v_4, v_5\}$ is a minimum covering.

Theorem 1.14.1. A set $S \subseteq V$ is an independent set of G if and only if V is a covering of G.

Proof. By definition, S is independent iff no two vertices of S are adjacent. That is, iff every line of S is incident with at least one point of V - S. That is, iff V - S is a covering of G.

Corollary 1.14.1. $\alpha + \beta = p$

Proof. Let S be a maximu independent set of G and K be a minimum covering of G.

 $\therefore |S| = \alpha \text{ and } |K| = \beta.$

Now V - S is a covering of G and K is a minimum covering of G. Hence $|K| \leq |V - S|$ so that $\beta \leq p - \alpha$

$$\therefore \beta + \alpha \le p \tag{1.1}$$

Also V - K is an independent set and S is a maximum independent set Hence $|S| \leq |V - K|$ so that $\alpha \geq p - \beta$.

$$\alpha + \beta \ge p \tag{1.2}$$

From 1.1 and (1.2), we get $\alpha + \beta = p$.

In the following definition we give the line analogue of coverings independence. $\hfill \square$

Definition 1.14.2. A line covering of G is a subset L of X such that every vertex is incident with a line of L. The number of line in a minimum line covering of G is called the **line covering number** of G and is denoted by β' . A set of lines is called **independent** if no two of them are adjacent. The number of lines in a maximum independent set of lines is called the **edge independence number** and is denoted by α' . Gallai has proved that for any non-trivial graph, $\alpha' + \beta' = p$, though it is not true that the complement of an independent set of lines is a line covering.

Result $\alpha' + \beta' = p$.

Proof. Let S be a maximum independent set of lines of G so that $|S| = \alpha'$. Let M be a set of lines, one incident for each of the $p - 2\alpha'$ points of G not covered by any line of S. Clearly $S \bigcup M$ is a line covering of G.

$$\therefore |S \cup M| \ge \beta'$$

$$\therefore \alpha' + P - 2\alpha' \ge \beta'$$

$$\therefore p \ge \alpha' + \beta'$$
(1.3)

Now, let T be a minimum line cover of G, so that $|T| = \beta'$. T cannot have a line x both of whose ends are also incident with lines of T other than x (since, otherwise $T - \{x\}$ will become a line covering of G). Hence G|T|, the spanning subgraph of G induced by T, is the union of stars. Hence each line of T is incident with at least one endpoint of G[T]. Let W be a set of endpoints of G[T]consisting of exactly one end point for each line of T. Hence $|W| = |T| = \beta'$ and each star has exactly one point not in W. Hence

$$p = |W| + (number of stars in G[T])$$
(1.4)

$$\therefore p = \beta' + (number \ of \ stars \ in \ G[T])$$
(1.5)

By choosing one line from each star of G[T], we get set of independent lines of G. Hence

$$\alpha' \ge (number \ of \ stars \ in \ G[T])$$

Hence (1.5) gives $p \leq \beta' + \alpha'$. Therefore by ((1.3)), $\alpha' + \beta' = p$. This complete the proof.

1.15 Exercise

- 1. Find α, β, α' and β' for the complete graph K_p .
- 2. Prove or disprove. Every covering of a graph contains a minimum cover.
- 3. Prove or disprove. Every independent set of lines is contained in a maximum independent set of lines.
- 4. Give an example to show that the complement of an independent set of lines need not be a line covering.
- 5. Give an example to show that the complement of a line covering need be an independent set of lines.

1.16 Intersection graphs and line graphs

Definition 1.16.1. Let $F = \{S_1, S_2, \dots, S_p\}$ be a non- empty family of distinct non empty subsets of a given set S. The **intersection graph** of F, denoted $\Omega(F)$ is defined as follows:

The set of points V of $\Omega(F)$ is F itself and two points S_i, S_j are adjacent if $i \neq j$ and $S_i \bigcap S_j \neq \emptyset$. A graph G is called an intersection graph on S if there exist a family F of subsets of S such that G is isomorphic to $\Omega(F)$.

Theorem 1.16.1. Every graph is an intersection graph.

Proof. Let G = (V, X) be a graph. Let $V = \{v_1, v_2, \cdots, v_p\}$. Let $S = V \cup X$ For each $v_i \in V$, let $S_i = \{v_i\} \cup \{x \in X | v_i \in x\}$.

Cleary $F = \{S_1, S_2, \cdots, S_p\}$ is a family of distinct non-empty subsets of S

Further if v_i, v_j are adjacent in V then $v_i v_j \in Si \cap S_j$ and hence $Si \cap S_j \neq \emptyset$. Conversely if $Si \cap S_j \neq \emptyset$ then the element common to $Si \cap S_j$ is the line joining v_i and v_j so that v_i, v_j are adjacent in G. Thus $f: V \to F$ defined by $f(v_i) = S_i$ is an isomorphism of G to $\Omega(F)$. Hence G is an intersection graph. \Box

Definition 1.16.2. Let G = (V, X) be a graph with $X \neq \emptyset$. Then X can be thought of a family of 2 element subsets of V. The intersection graph $\Omega(X)$ is

called the **line graph** of G and is denoted by L(G). Thus the points of L(G) are lines of G and two points in L(G) are adjacent iff the corresponding lines are adjacent in G.

A example of a graph and line graph are given in Fig. 1.19.

Theorem 1.16.2. Let G be a (p,q) graph. L(G) is a (q,q_L) graph where $q_L = \frac{1}{2} (\sum_{i=1}^p d_i^2) - q.$

Proof. By definition, number of points in L(G) is q. To find the number of lines in L(G). Any two of the d_i lines incident with v_i are adjacent in L(G) and hence we get $\frac{d_i(d_i-1)}{2}$ lines in L(G).

Hence
$$q_L = \sum_{i=1}^p \frac{d_i(d_i - 1)}{2}$$

 $= \frac{1}{2} (\sum_{i=1}^p d_i^2) - \frac{1}{2} (\sum_{i=1}^p d_i)$
 $= \frac{1}{2} (\sum_{i=1}^p d_i^2) - \frac{1}{2} (2q)$
 $= \frac{1}{2} (\sum_{i=1}^p d_i^2) - q$

	L	

1.17 Exercise

Show that the line graphs of the two graphs given in Fig. 1.20 are isomorphic.

The two graphs given in figure 2.20 constitute the only pair of non-isomorphic connected graphs having isomorphic line graphs. In all other cases, $L(G) \cong L(G')$ implies $G \cong G'$ as claimed in the following theorem.

Theorem 1.17.1. (Whitney.) Let G and G' be connected graphs with isomorphic line graphs. Then G and G' are isomorphic unless one is K_3 and the other $K_{1,3}$.

Definition 1.17.1. A Graph G is called a **line graph** if $G \cong L(H)$ for some graph H.

Example $K_4 - x$ is a line graph as seen in Fig. 19. The following theorem is called Beineke's forbidden subgraph characteristics of line graphs.

Theorem 1.17.2. (Beineke.) G is a line graph iff none of the nine graphs of Fig. 2.20 is an induced subgraph of G.

1.18 Operations on graphs

Definition 1.18.1. Let $G_1 = (V_1, X_1)$ and $G_2 = (V_2, X_2)$ be two graphs with $V_1 \cap V_2 = \Phi$. We define:

• The union $G_1 \cup G_2$ to be (V, X) where

$$V = V_1 \cup V_2$$
 and $X = X_1 \cup X_2$

- The sum $G_1 + G_2$ as $G_{1 \cup G_2}$ together with all the lines joining points of V_1 to points of V_2 .
- The product $G_1 \times G_2$ having $V = V_1 \times V_2$ and $u = (u_1, u_2)$ and $v = (v_1, v_2)$ are adjacent to v_1 in G_1 and $u_2 = v_2$.
- The composition $G_1[G_2]$ as having $V = V_1 \times V_2$ and $u = (u_1, u_2)$ and $v = (v_1, v_2)$ are adjacent if u_1 is adjacent to v_1 in G_1 or $(u_1 = v_1$ and u_2 is adjacent to v_2 in G_2).

We note that $\overline{K_m} + \overline{K_n} = K_{m,n}$.

Theorem 1.18.1. Let G_1 be a (p_1, q_1) and G_2 a (p_2, q_2) graph.

- 1. $G_1 \cup G_2$ is a $(p_1 + p_2, q_1 + q_2)$ graph.
- 2. $G_1 + G_2$ is a $(p_1 + p_2, q_1 + q_2 + p_1p_2)$ graph.
- 3. $G_1 \times G_2$ is a $(p_1p_2, q_1p_2 + q_2p_1)$ graph.
- 4. $G_1[G_2]$ is $(p_1p_2, p_1q_2 + p_2^2q_1)$ graph.

Proof.

1. is obvious.

2.

- number of lines in $G_1 + G_2$ = number of lines in G_1 + number of lines in G_2 + number of lines joining points of V_1 of points of V_2 . = $q_1 + q_2 + p_1 p_2$. Hence we get (2)
- 3. Clearly number of points in $G_1 \times G_2$ is p_1p_2 . Now, let $(u_1, u_2) \in V_1 \times V_2$. The points adjacent to (u_1, u_2) are (u_1, v_2) where u_2 is adjacent to v_2 (v_1, u_2) where adjacent to u_1 .

$$\therefore deg(u_1, u_2) = degu_1 + degu_2$$

The total number of lines in $G_1 \times G_2$

$$= \frac{1}{2} \left[\sum_{i,j} \deg(u_i) + \deg(v_j) \right]$$

$$= \frac{1}{2} \sum_{i=1}^{p_1} \sum_{j=1}^{p_2} (\deg u_i + \deg v_j) \text{ where } u_i \in V_1, v_j \in V_2$$

$$= \frac{1}{2} \sum_{i=1}^{p_1} (p_2 \deg u_i + \sum_{j=1}^{p_2} \deg v_j)$$

$$= \frac{1}{2} \sum_{i=1}^{p_1} (p_2 \deg u_i + 2q_2)$$

$$= \frac{1}{2} (2p_2q_1 + 2p_1q_2)$$

$$= p_2q_1 + p_1q_2$$

The proof of (4) is left to the reader.

1.19 Exercise

- 1. Prove (4) of Theorem 1.17.1.
- 2. If G_1 and G_2 are regular, determine whether $G_1 + G_2, G_1 \times G_2$ and G_1 are regular.

- 3. What is $K_m + K_n$?
- 4. Express $K_4 x$ in terms of K_2 and $\overline{K_2}$.
- 5. Express the graph in Fig. 2.21 in terms of $\overline{K_3}$ and $\overline{K_2}$.
- 6. Express the graph G of Fig. 2.19 in terms of K_1 and K_3 .
- 7. Define two more binary operations on graphs in your own way.

Revision Questions Determine which of the following statements are true and which are false.

1. If G is a
$$(p,q)$$
 graph $q \leq \begin{pmatrix} p \\ 2 \end{pmatrix}$
2. If G is a (p,q) graph and $q = \begin{pmatrix} p \\ 2 \end{pmatrix}$ then G is complete.

- 3. A subgraph of a complete graph is complete.
- 4. An induced subgraph of a complete graph is complete.
- 5. A subgraph of a bipartite graph is bipartite.
- 6. In any graph G the number of points of odd degree is even.
- 7. Any complete graph is regular.
- 8. Any complete bigraph is regular.
- 9. A regular graph of degree 0 is totally disconnected.
- 10. The only regular graph of degree 1 is K_2 .
- 11. The only connected regular graph of degree i is K_2 .
- 12. A graph G is regular iff $\delta = \Delta$.
- 13. An induced subgraph of regular graph is regular.
- 14. If G is regular, then G V is regular.
- 15. If G is complete, then G V is complete.

- 16. Any two isomorphic graphs have the same number of points and same number of lines.
- 17. Any two graphs having the same number of points and same number of lines are isomorphic.
- 18. Isomorphism preserves the degree of vertices.
- 19. If G_1 and G_2 are regular, $G_1 + G_2$ is regular.
- 20. If G_1 and G_2 are regular $G_1[G_2]$ is regular.

Answers

 $1, 2, 4, 5, 6, 7, 9, 11, 12, 15, 16, 18 \ {\rm and} \ 20$ are true.

Matrices of a graph

We study about two representations of a graph in matrix form. A matrix is a convenient and useful way of representing a graph to a computer. Further the algebra of matrices can be used to identify certain properties of graphs.

Definition 1.4.10. Let G = (V(G), E(G)) be a graph with $V(G) = \{v_1, v_2, \dots, v_{\nu}\}$ and $E(G) = \{e_1, e_2, \dots, e_{\epsilon}\}$. Then the *incidence matrix* of G is the $\nu \times \epsilon$ matrix defined by $M(G) = [m_{ij}]$, where m_{ij} is the number of times (0, 1 or 2) that v_i and e_j are incident.



The incidence matrix of the above graph is as follows:

Remark 1.4.11. 1. Since each edge is incident with exactly two vertices, each column sum of M is 2.

2. Sum of the *i* th row of M is equal to the degree of v_i .

3. If G is simple, then the matrix M is a binary matrix with 0's and 1's.

Definition 1.4.12. Let G = (V(G), E(G)) be a graph with $V(G) = v_1, v_2, \dots v_{\nu}$. Then the adjacency matrix of G is the $\nu \times \nu$ matrix defined by

 $A(G) = [a_{ij}]$, where a_{ij} is the number of edges joining v_i and v_j .

The incidence matrix of the graph G shown in Figure 1.4.6 is as follows:

$$\mathbf{A(G)} = \begin{array}{cccc} v_1 & v_2 & v_3 & v_4 \\ v_1 & \begin{pmatrix} 0 & 2 & 1 & 1 \\ 2 & 0 & 1 & 0 \\ v_3 & 1 & 1 & 0 & 1 \\ 1 & 1 & 0 & 1 & 0 \end{pmatrix}$$

Remark 1.4.13. 1. The adjacency matrix A(G) is symmetric.

2. If G is simple, then the entries along the principal diagonal are zero.

3. The sum of the i^{th} row (column) of A(G) is equal to the degree of v_i .

Exercises

- 1. Find the degrees of the vertices of the graph G given in Figure 1.3.1.
- 2. Find the incidence matrix M and adjacency matrix A of the graph given in Figure 1.3.1.
- 3. If G is simple, prove that the entries on the diagonals of both MM' and A^2 are the degrees of the vertices of G.

UNIT-2

1.20 Walks, Trails and Paths

Definition 1.20.1. A walk of a graph G is an alternating sequence of points and lines $v_0, x_1, v_1, x_2, v_2, \dots, v_{n-1}, x_n, v_n$ beginning and ending with points such that each line x_i is incident with v_{i-1} and v_i .

We say that the walks join v_0 and v_n and it is called a v_0 - v_n walk. v_0 is called the **initial point** and v_1 is called the **terminal point** of the walk. The above walk is also denoted by v_0, v_1, \dots, v_n the lines of the walks being self evident. n, the number of lines in the walk, is called the length of this walk. A single point is considered as a walk of length 0. A walk is called a **trail** if all its lines are distinct and is called a **path** if all its points are distinct.

Example 1.20.1. For the graph given in **1.23** $v_1, v_2, v_3, v_4, v_2, v_1, v_2, v_5$ is a walk. $v_1, v_2, v_4, v_3, v_2, v_5$ is a trail but not a path. v_1, v_2, v_4, v_5 is a path. Obliviously, every path is a trail and a trail need not be a path. The graph consisting of a path with n points is denoted by P_n .

Definition 1.20.2. A $v_0 - v_n$ walk is called **closed** if $v_0 = v_n$. A closed walk $v_0, v_1, \dots, v_n = v_0$ in which $n \ge 3$ and v_0, v_1, \dots, v_{n-1} are is distinct is called of length n. A graph consisting of a **cycle** of length n is denoted by C_n . C_3 is called a **triangle**.

Theorem 1.20.1. In a graph G, any u - v walk contains a u - v path.

Proof. We prove the result by induction on the length of the walk. Any walk of length 0 or 1 is obviously a path. Now, assume the result for all walks of length less than n. If $u = u_0, u_1, \dots, u_n = v$ be a u - v walk of length n. If all the points of the walk are distinct it is already a path. If not, there exists i and j such that $0 \le i < j \le n$ and $u_i = u_j$. Now $u = u_0, \dots, u_i, u_{j+1}, \dots, u_n = v$ is a u - v walk of length less than n which by induction hypothesis contains a u - v path.

Theorem 1.20.2. If $\delta \geq k$, then G has a path of length k.

Proof. Let v_1 be an arbitrary point. Choose v_2 adjacent to v_1 . Since $\delta \geq k$, there exists at least k - 1 vertices other than v_1 which are adjacent to v_2 . Choose $v_1 \neq v_1$ such that v_3 is adjacent to v_2 . In general having chosen v_1, v_2, \dots, v_i where $1 < i \leq \delta$ there exist a point $v_{i+1} \neq v_0, v_1, \dots, v_n$ such that v_{i+1} is adjacent to v_i . This process yields a path of length k in G.

Aliter.Let $P = (v_0, v_1, \dots, v_n)$ be the longest path in G. Then every vertex adjacent to v_0 lies on P. Since $d(v_0) \ge \delta$ it follows that length of $P \ge \delta \ge k$. Hence $P_1 = (v_0, v_1, \dots, v_k)$ is a path of length k in G.

Theorem 1.20.3. A closed walk of odd length contains a cycle.

Proof. Let $v = v_0, v_1, \dots, v_n = v$ be a closed walk of odd length. Hence $n \ge 3$. If n = 3 this walk is itself the cycle C_3 and hence the result is trivial. Now assume the result for all walks of length less than n. If the given walk of length n is itself is a cycle there is nothing to prove. If not there exists two positive integers i and j such that $i < j, \{i, j\} \neq \{0, n\}$ and $v_i = v_j$. Now v_i, v_{i+1}, \dots, v_j and $v = v_0, v_1, \dots, v_i, v_{j+1}, \dots, v_n = v$ are closed walks contained in the given walk and the sum of their lengths is n. Sin ce n is odd at least one of these walks is of odd length which by induction hypothesis contains a cycle.

Solved Problem

Problem 9. If A is the adjacency matrix of a graph with $V = \{v_1, v_2, \dots, v_p\}$, prove that for any $n \ge 1$ the $(i, j)^{th}$ entry of A^n is the number of $v_i - v_j$ walks of length n in G.

Solution We prove the result by induction on n. The number of $v_i - v_j$ walks of length 1

$$= \begin{cases} 1, & \text{if } v_i \text{ and } v_j \text{ are adjacent}; \\ 0, & \text{otherwise.} \end{cases}$$
$$= a_{ij}.$$

Hence the result is true for n = 1.

We now assume that the result is true for n-1. Let $A^{n-1} = (a_{ij}^{(n-1)})$ so that $a_{ij}^{(n-1)}$ is number of $v_i - v_j$ walks of length n-1 in G. Now $A^{n-1}A = (a_{ij}^{(n-1)})a_{ij}$. Hence $(i, j)^t h$ entry of

$$A^{n} = \sum_{k=1}^{p} a_{ik}^{(n-1)} a_{kj}$$
(1.6)

Also every $v_i - v_j$ walk of length n inG consists of a $v_i - v_j$ walk of length n - 1 followed by a vertex v_j which is adjacent to v_k . Hence v_j is adjacent to v_k then $a_{kj} = 1$ and $a_{ij}^{(n-1)}$ represents the number of $v_i - v_j$ walks of length n whose last edge is $v_i v_j$. Hence the right hand side of equation (I.6) gives the number of $v_i - v_j$ walks of length n in G. This completes the induction and the proof.

1.21 Connectness and components

Definition 1.21.1. Two points u and v of a graph G are said to be **connected** if there exists a u - v path in G.

Definition 1.21.2. A graph G is said to be **connected** if every pair of its points are connected. A graph which is not connected is said to be **disconnected**.

For example, for n > 1 the graph $\overline{K_n}$ consisting of n points and no lines is disconnected. The union of two graphs is disconnected.

It is an easy exercise to verify that connectedness of points is an equivalence relation on the set of points V. Hence v is partitioned into nonempty subsets V_1, V_2, \dots, V_n such that two vertices u and v are connected iff both u and vbelongs to the same set V_i . Let G_i denote the induced subgraph of G with vertex set V_i . Clearly the subgraphs G_1, G_2, \dots, G_n are connected and are called the **Components of G**.

Clearly a graph G is connected iff it has exactly one component. **1.24** gives a disconnected graph with 5 components.

Theorem 1.21.1. A graph G with p points and $\delta \geq \frac{p-1}{2}$ is connected.

Proof. Suppose G is not connected. Then G has more than one component. Consider any component $G_1 = (V_1, X_1)$ of G. Let $v_1 \in V_1$. Since $\delta \geq \frac{p-1}{2}$ there exist at least $\frac{p-1}{2}$ points in G_1 adjacent to v_1 and hence V_1 contains at least $\frac{p-1}{2} + 1 = \frac{p+1}{2}$ points. Thus each component of G contains at least $\frac{p+1}{2}$ points and G has at least two components. Hence number of points in $G \geq p+1$ which is a contradiction. Hence G is connected.

Theorem 1.21.2. A graph G is connected iff for any partition of V into subsets V_1 and V_2 there is a line of G joining a point of V_1 to a point of V_2 .

Proof. Suppose G is connected.Let $V = V_1 \cup V_2$ be a partition of a V into two subset. Let $u \in V_1$ and $v \in V_2$. Since G is connected, there exists a u - vpath in G, say, $u = v_0, v_1, v_2, \cdots, v_n = v$. Let i be the least positive integer such that $v_i \in V_2$.(Such an i exists since $v_n = v \in V_2$). Then $v_{i-1} \in V_1$ and v_{i-1}, v_i are adjacent. Thus there is a line joining $v_{i-1} \in V_1$ and $v_i \in V_2$. To prove the converse, suppose G is not connected. Then G contains at least two components. Let V_1 denote the set of all vertices of one component and V_2 the remaining vertices of G. Clearly $V = V_1 \cup V_2$ is a partition of V and there is no line joining any point of V_1 to any point of V_2 . Hence the theorem.

Theorem 1.21.3. If G is not connected then \overline{G} is connected.

Proof. Since G is not connected, G has more than one component.Let u, v be any two points of G. We will prove that there is a u-v path in \overline{G} . If u, v belong to different components in G, they are not adjacent in G and hence they are adjacent in \overline{G} . If u, v lie in the same component of G, choose w in a different component. Then u, w, v is a u-v path in \overline{G} . Hence \overline{G} is connected. \Box

Definition 1.21.3. For any two points u, v of a graph we define the distance between u and v by $d(u, v) = \begin{cases} \text{the length of the shortest } u - v \text{ path }, & \text{if such a path exists;} \\ \infty, & \text{otherwise.} \end{cases}$ If G is a connected Graph, d(u, v) is always a non-negative integer. In this case d is actually a metric on the set of points V (See problem 2). **Theorem 1.21.4.** A graph G with at least two points is bipartite iff all its cycles are of even length.

Proof. Suppose G is a bipartite. Then V can be partitioned into two subsets V_1 and V_2 such that every line joins a point of V_1 to a point of V_2 . Now consider any cycle $v_0, v_1, v_2, \dots, v_n = v_0$ of length n. Suppose $v_0 \in V_1$. Then $v_2, v_4, v_6 \dots \in V_1$ and $v_1, v_3, v_5 \dots \in V_2$. Further $v_n = v_0 \in V_1$ and hence n is even. Conversely, suppose all cycles in G are of even length. We may assume without loss of generality that G is connected. (If not we consider the components of G separately). Let $v_1 \in V$. Define

$$V_1 = \{ v \in V | d(v, v_1) \text{ is even} \}$$

$$V_2 = \{ v \in V | d(v, v_1) \text{ is odd} \}.$$

Clearly, $V_1 \cap V_2 = \emptyset$ and $V_1 \cup V_2 = V$. We claim that every line of G joins a point of V_1 to a point of V_2 . Suppose two points $u, v \in V_1$ are adjacent. Let p be a shortest $v_1 - u$ path of length m and let Q be a shortest $v_1 - v$ path of length n. Since $u, v \in V_1$ both m and n are even. Now, let u_1 be the last point common to P and Q. Then the $v_1 - u_1$ path along P and the $v_1 - u_1$ path along Q are both shortest path and hence have the same length, say i. Now the $u_1 - u$ path along P, the line uv followed by the $v - u_1$ path along Q form a cycle of length (m - i) + 1 + (n - i) = m + n - 2i + 1 which is odd and this is a contradiction. Thus no two points of V_1 are adjacent.

To study the measure of connectedness of a graph G we consider the minimum number of points or lines to be removed from the graph in order to disconnect it.

Definition 1.21.4. A **cut point** of a graph G is a point whose removal increases the number of components. A **bridge** of a graph G is a line whose removal increases the number of components.

Clearly if v is a cut point of a connected graph, G - v is disconnected. For the graph given in Fig. 1.25, 1, 2, and 3 are cut points. The lines $\{1, 2\}$ and $\{3, 4\}$ are bridges. 5 is non-cut point. **Theorem 1.21.5.** Let v be a point of a connected graph G. The following statements are equivalent.

- 1. v is a cut-point of G.
- 2. There exists a partition of $V \{v\}$ into subsets U and W such that for each $u \in U$ and $w \in W$, the point v is on every u w path.
- 3. There exists two points u and w distinct from v such that v is on every u w path.

Proof. (1) \Rightarrow (2). Since v is a cut-point of G, G - v is disconnected. Hence G - v has at least two components. Let U consist of the points of one of the components of G - v and W consist of the points of the remaining components. Clearly $V - \{v\} = U \cup W$ is a partition of $V - \{v\}$. Let $u \in U$ and $w \in W$. Then u and w lie in different components of G - v. Hence there is no u - w path in G - v.

Therefore every u - w path in G contains in v.

 $(2) \Rightarrow (3)$. This is trivial.

(3) \Rightarrow (1). Since v is on every u - w path in G there is no u - w path in G - v. Hence G - v is not connected so that v is a cut point of G.

Theorem 1.21.6. Let x be a line of a connected graph G. The following statements are equivalent.

- 1. x is bridge of G.
- 2. There exists a partition of V into two subsets U and W such that for every point $u \in U$ and $w \in W$, the line x is on every u w path.
- 3. There exists two points u, w such that the line x is on every u w path.

Proof. The proof is analogous to that of theorem 1.21.5 and is left as an exercise.

Theorem 1.21.7. A line x of a connected graph G is a bridge iff x is not on any cycle of G.

Proof. Let x be a bridge of G. Suppose x lies on a cycle C of G. Let w_1 and w_2 be any two points in G. Since G is connected, there exists a $w_1 - w_2$ path P in G. If x is not on P, then P is a path in G - x. If x is on P, replacing x by C - x, we obtain a $w_1 - w_2$ walk in G - x. Walk contains a $w_1 - w_2$ path in G - x. Hence G - x is connected which is contradiction to (1). Hence x is not on any cycle on G. Conversely, let x = uv be not on any cycle of G. Suppose x is not a bridge. Hence G - x is connected.

 \therefore There is a u - v path in G - x. This path together with the line x = uv forms a cycle containing x and contradicts (2). Hence x is a bridge. \Box

Theorem 1.21.8. Every non-trivial connected graphs has at least two points which are not cut points.

Proof. Choose two points u and v such that d(u, v) is maximum. We claim that u and v are not cut points. Suppose v is a cut point.Hence G - v has more than one component. Choose a point w in a component that does not contain u. Then v lies on every u - w path and hence d(u, w) > d(u, v) which is impossible.Hence v is not a cut point. Similarly u is not a cut point. Hence the theorem.

1.22 Exercise

- 1. Prove that connectedness of points is an equivalence relation on the points of G.
- 2. Prove that for a connected graph G the distance function d(u, v) is actually a metric on G. i.e., $d(u, v) \ge 0$ and d(u, v) = 0 iff u = v, d(u, v) = d(v, u) and $d(u, w) \le d(u, v) + d(v, w)$ for all $u, v, w \in V$.
- 3. Prove theorem 4.9.
- 4. If x = uv is a bridge for a connected graph $G \neq K_2$, show that either u or v is a cut point of G.
- 5. Prove that if x is a bridge of a connected graph G, then G-x has exactly two components. Give an example to show that a similar result is not true for a cut point.
- 6. The girth of a graph is defined to be the length of its shortest cycle. Find the girths of (i) K_m $(ii)K_{m,n}$ $(iii)C_n$ (iv) The Peterson graph.
- 7. The circumference of a graph is defined to be the length of its longest cycle. Find the *circumference* of the graphs given in problem 6.
- 8. Prove that if G is connected then its line graph is also connected.
- 9. Prove that any graph G with $\delta \ge r \ge 2$ contains a cycle of length at least r + 1.
- 10. Prove that if there exists two distinct cycles each containing a line x, then there exists a cycle not containing x.
- 11. Prove that if a graph G has exactly two points of odd degree there must be a path joining these two points.
- 12. Give an example of a connected graph in which every line is a bridge.
- 13. Prove that any graph with p points satisfying the conditions of problem 12 must have exactly p-1 lines.
- 14. Give an example of a graph which has a cut point but does not have a bridge.
- 15. Prove that if v is a cut point of G, then v is not a cut point of \overline{G}

1.23 Blocks

Definition 1.23.1. A connected non-trivial graph having no cut point is a **block**. A block of a graph is a subgraph that is a block and is maximal with respect to this property.

A graph and its blocks are given in **1.26**. In the following theorem we give several equivalent conditions for a given block.

Theorem 1.23.1. Let G be a connected graph with at least three point, following statements are equivalent.

~ ·

1. G is a block.

- 2. Any two points of G lie on a common cycle.
- 3. Any point and any line of G lie on a common cycle.
- 4. Any two lines of G lie on a common cycle.

Proof. (1) ⇒ (2) Suppose G is a block. We shall prove by induction on the distance d(u, v) between u and v any two vertices u and v lie on a common cycle. Suppose d(u, v) = 1. Hence u and v are adjacent. By hypothesis, $G \neq K_2$ and G has no cut points. Hence the line x = uv is not a bridge and Theorem [1.21.7] x is on a cycle of G. Hence the points u and v lie on a common cycle of G. Now assume that the result is true for any two vertices at distance k and let $d(u, v) = k \ge 2$. Consider a u - v path of length k. Let w be the vertex that precedes v on this path. Then d(u, v) = k - 1. Hence by induction hypothesis there exists a cycle C that contains u and w. Now since G is a block, w is not a cut point of G and so G - w is. Hence there exists a u - v path P not containing w. Let v' be the last point common to P and C. (See FigI.27). Sinceu is common to P and C, such a v' exists. Now, let Q denote the u - v' path along the cycle C not containing the point w. Then, Q followed by the v' - v path along P, the line vw and the w - v path along the cycle that contains both u and v. This completes the induction.

Thus any two points of G lie on a common cycle of G. (2) \Rightarrow (1).Suppose any two points of G lie on a common cycle of G. Suppose vis a cut point of G. Then there exists two points u and w distinct from v such that every u - w path contains v.(Refer Theorem 4.8). Now, by hypothesis u and w lie on a common cycle and this cycle determines two u - w paths and at least one of these paths does not contain v which is a contradiction. Hence G has no cut points so that G is a block.

 $(2) \Rightarrow (3)$. Let u be a point and vw a line of G. By hypothesis u and v lie on a common cycle C. If w lies on C, then the line uw together with the v - wpath of C containing u is the required cycle containing u and the line vw. If wis not on C, let C' be a cycle containing u and w. This cycles determines two w - u paths and at least one of these paths does not contain v. Denote this path by P. Let u' be the first point common to P and C.(u' may be u itself). Then the line vw followed by the w - u' sub path of P and the u' - v path in C containing u form a cycle containing u and the line vw. (3) \Rightarrow (2) is trivial. $(3) \Rightarrow (4)$. The proof is analogous to the proof of $(2) \Rightarrow (3)$ and is left as an exercise. $(4) \Rightarrow (3)$ is trivial.

1.24 Exercise

- 1. Prove that each line of a graph lies in exactly one of its blocks.
- 2. Prove that the lines of any cycle of G lie entirely in a single block of G
- 3. Prove that if a point v is common to two distinct block of G, then v is a cut point of G.
- 4. Prove that a graph G is a block iff for any three distinct points of G, there is a path joining any two of them which does not contain the third.
- 5. Prove that a graph G is a block iff for any three distinct points of G, there is a path joining any two of them which contains the third.

1.25 Connectivity

We define two parameters of a graph, its connectivity and edge connectivity which measures the extend to which it is connected.

Definition 1.25.1. The **connectivity** $\kappa = \kappa(G)$ of a graph *G* is the minimum number of points whose removal results in a disconnected or trivial graph. The connectivity $\lambda = \lambda(G)$ of *G* is the minimum number of lines whose removal results in a disconnected or trivial graph.

Example 1.25.1.

- 1. The connectivity and line connectivity of a disconnected graph is 0.
- 2. The connectivity of a connected graph with a cut point is 1.
- 3. The line connectivity of a connected graph with a bridge is 1.
- 4. The complete graph K_p cannot be disconnected by removing any number of points, but the removal of p-1 points results in a trivial graph. Hence $\kappa(K_p) = p-1$

Theorem 1.25.1. For any graph $G, \kappa \leq \lambda \leq \delta$.

Proof. We first prove $\lambda \leq \delta$. If G has no lines, $\lambda = \delta = 0$. Other wise removal of all the lines incident with a point of minimum degree results in a disconnected graph. Hence $\lambda \leq \delta$. Now to prove $\kappa \leq \lambda$, we consider the following cases.

Case(i)*G* is disconnected or trivial. Then $\kappa = \lambda = 0$

Case(ii)*G* is a connected graph with a bridge *x*. Then $\lambda = 1$. Further in case $G = K_2$ or one of the points incident with *x* is a cut point. Hence $\kappa = 1$ so that $\kappa = \lambda = 1$.

Case(iii) $\lambda \geq 2$. Then there exist λ lines the removal of which disconnects graph. hence the removal of $\lambda - 1$ of lines results in a graph G with bridge x = uv. For each of these $\lambda - 1$ line select an incident point different from u or v. The removal of these $\lambda - 1$ points removes all the $\lambda - 1$ lines. If the resulting graph is disconnected, then $\kappa \leq \lambda - 1$. If not x is a bridge of this subgraph and hence the removal of u or v results in a disconnected or trivial graph. Hence $\kappa \leq \lambda$ and this completes the proof.

Remark 1.25.1. The inequalities in theorem 1.25.1 are often strict. For the graph given in fig 1.28 $\kappa = 2, \lambda = 3$ and $\delta = 4$.

Definition 1.25.2. A graph G is said to be **n-connected** if $\kappa(G) \ge n$ and **n-line connected** if $\lambda(G) \ge n$.

Thus a non trivial graph is 1- connected iff it is connected. A non trivial graph is 2- connected iff it is block having more than one line. Hence K_2 is the only block which is not 2- connected.

1.26 Solved Problems

Problem 10. Prove that G is k- connected graph then $q \ge \frac{pk}{2}$. Solution.Since G is k- connected, $k \le \delta$ (by theorem 1.25.1).

$$\therefore q = \frac{1}{2}$$

$$\geq \frac{1}{2}p\delta \text{ (since } d(v) \geq \delta \text{ for all } v$$

$$\geq \frac{pk}{2}.$$

Problem 11. Prove that there is no 3– connected graph with 7 edges. **Solution** Suppose G is a 3– connected graph with 7 edges.G has 7 edges $\Rightarrow p \geq 5$. Now $q \geq \frac{3p}{2}$. Therefore $q \geq \frac{15}{2}$. Hence $q \geq 8$ which is a contradiction. Hence there is no 3– connected graph with 7 edges.

1.27 Exercise

- 1. Find the connectivity of $K_{m,n}$.
- 2. Show that if G is n- line connected and E is a set of n lines, the the number of components in the graph G-E is either 1 or 2.
- 3. give an example to show that the analogue of the above result is not true for a n- connected graph.
- 4. Give an example of a closed walk of even length which does not contain a cycle.
- 5. Give an example to show that the union of two distinct u v walks need not contain a cycle.
- 6. Prove that the union of two distinct u v paths contain a cycle.
- 7. Show that if a line is in a closed trail of G then it is in a cycle of G.
- 8. Determine which of the following statements are true and which are false.
 - (a) Any u v walk contains a u v path.
 - (b) The union of any two distinct u v walks contains a cycle.
 - (c) The union of any two distinct u v paths contains a cycle.
 - (d) A graph is connected iff it has only one component.
 - (e) The complement of a connected graph is connected
 - (f) Any subgraph of a connected graph is connected
 - (g) An induced subgraph of a connected graph is connected
 - (h) If a graph has a cut point ,then it has a bridge.
 - (i) If a graph has a bridge ,then it has a cut point.

- (j) If v is a cut point of a G then $\omega(G-v)=\omega(G)+1$
- (k) If x is a bridge of G, then $\omega(G x) = \omega(G) + 1$
- (l) In a connected graph every line can be a bridge.
- (m) In a connected graph every point can be a cut point.
- (n) A point common to two distinct blocks of a graph G is a cut point of G.
- (o) Every line of a graph G lies in exactly one block of G.
- (p) If a graph is n- connected then it is n- line connected.
- (q) Every block is 2– connected. Answers

1,3,4,11,12,14,15 and 16 are true.



Figure 1.17:



Figure 1.18:



Figure 1.19:



Figure 1.20:



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Figure 1.21:



Figure 1.22:



Figure 1.23:



Figure 1.24:



Figure 1.25:



Figure 1.26:



Figure 1.27:



Figure 1.28:

1.4 Degree sequences

Definition 1.4.1. The degree of a vertex v in a graph G is the number of edges incident with v, each loop counting as two. It is denoted by $d_G(v)$ or simply d(v). The minimum degree of vertices of G is denoted by $\delta(G)$. The maximum degree of vertices of G is denoted by $\Delta(G)$.

- - -

The following theorem is often called as the fundamental theorem on graphs.

Theorem 1.4.2. The sum of the degrees of the vertices in any graph is twice the number of edges. That is, $\sum_{v \in V} d(v) = 2\epsilon$.

Proof. Every edge of G is incident with two vertices. Hence every edge contributes two to the sum of the degrees of the vertices.

Hence,
$$\sum_{v \in V} d(v) = 2\epsilon$$
.

Corollary 1.4.3. In any graph, the number of vertices of odd degree is even.

Proof. Let V_1 denote the set of vertices of even degree; let V_2 denote the set of vertices

of odd degree. Then, $\sum_{v \in V_1} d(v) + \sum_{v \in V_2} d(v) = \sum_{v \in V} d(v) = 2\epsilon$, which is even. Further, d(v) is even for all $v \in V_1$, $\sum_{v \in V_2} d(v)$ is even. Hence, $\sum_{v \in V_2} d(v)$ is even. Since d(v) is odd for all $v \in V_2$, we have $|V_1|$ is even.

For the graph shown in Figure 1.4.1, $\delta(G) = 3$ and $\Delta(G) = 4$.



Definition 1.4.4. A graph is said to be k-regular if d(v) = k for all $v \in V(G)$. A regular graph is one that is k-regular for some k. 3 -regular graphs are also known as *cubic graphs*.



Remark 1.4.5. 1. The complete graph K_n is regular of degree n-1.

- 2. The complete bipartite graph $K_{n,n}$ is regular of degree n.
- 3. The k-cube Q_k is regular of degree k-1.
- 4. Peterson graph is 3 -regular and hence a cubic graph.



Definition 1.4.6. Let G be any graph with $V(G) = v_1, v_2, \dots, v_{\nu}$. Then the sequence $d(v_1), d(v_2), \dots, d(v_{\nu})$ is called the *degree sequence* of G.

For example, the degree sequence of the graph in Figure 1.4.1 is (3, 3, 4, 4).



Theorem 1.4.7. A sequence $d(v_1), d(v_2), \dots, d(v_{\nu})$ of nonnegative integers is a degree sequence of G if and only if $\sum_{i=1}^{\nu} d(v_i)$ is even.

Proof. Assume that $d(v_1), d(v_2), \dots, d(v_{\nu})$, where $d_i \ge 0, 1 \le i \le \nu$ is the degree sequence of a graph G. Then by Theorem 1.4.2, $\sum_{i=1}^{\nu} d(v_i) = 2\epsilon$, which is even. Conversely, assume that $d(v_1), d(v_2), \dots, d(v_{\nu})$ are nonnegative integers such that

Conversely, assume that $d(v_1), d(v_2), \dots, d(v_{\nu})$ are nonnegative integers such that $\sum_{i=1}^{\nu} d(v_i)$ is even. It is enough to construct a graph with vertex set v_i and $d(v_i) = d_i$ for all *i*. Since $\sum_{i=1}^{\nu} d(v_i)$ is even, the number of odd integers is even. First form an arbitrary pairing of the vertices in $\{v_i \mid d(v_i) \text{ is even}\}$ and join each pair by an edge. Now the

remaining degree needed at each vertex is even, which can be obtained by adding loops at v_i .

d

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Definition 1.4.8. A sequence $D = (d_1, d_2, \dots, d_n)$ is said to be *graphic* if there is a simple graph G with degree sequence D. Then G is called the realization of D. For example, the sequence (4, 4, 2, 2, 1, 1) is graphic since it is the degree sequence of the graph G given below.



Figure 1.4.5

Theorem 1.4.9. If $d = (d_1, d_2, \dots, d_n)$ is graphic and $d_1 \ge d_2 \ge \dots d_n$, then $\sum_{i=1}^n d(v_i)$ is even and $\sum_{i=1}^n d(v_i) \le k(k-1) + \sum_{i=k+1}^n d(v_i)d_i \min\{k, d_i\}$ for $1 \le k \le n$.

Proof. Since d is graphic, it has a realization graph G. Let $V(G) = \{v_1, v_2, \dots, v_n\}$ and $d(v_i) = d_i$. Then by Theorem 1.4.2,

 $\sum_{i=1}^{\nu} d(v_i) = 2\epsilon, \text{ which is even.}$ $\sum_{i=1}^{\nu} d(v_i) \text{ is the sum of the degrees of the vertices } v_1, v_2, \cdots, v_n.$

It can be divided into two parts, the first part is the contribution to this sum by edges joining the vertices v_1, v_2, \dots, v_k and the second part is the contribution to this sum by edges joining one of the vertices $v_{k+1}, v_{k+2}, \dots, v_n$.

Hence,
$$\sum_{i=1}^{n} d(v_i) \le k(k-1) + \sum_{i=k+1}^{n} d(v_i) d_i \min\{k, d_i\}$$
 for $1 \le k \le n$.

Solved problems

Problem 1. Find a function $f : \mathbb{N} \to \mathbb{N}$ such that, for all $k \in \mathbb{N}$, every graph of average degree at least f(k) has a bipartite subgraph of minimum degree at least k.

Solution. Define a map $f : \mathbb{N} \to \mathbb{N}$ by f(k) = 4k; $\forall k \in \mathbb{N}$. The idea behind to consider this function is following: Every graph with an average degree of 4k have a

subgraph H with minimum degree 2k, and we will lose another factor of 2 in moving H to its bipartite subgraph. Let H' be the bipartite subgraph of H with the maximal number of edges. My claim is that H' have minimum degree at least k. If not, let $v \in H'$ such that $d_{H'}(v) < k$: This means v lost more than half of its neighbours in the process to form H to H'. This means v is on the same partition with its looses neighbours. But in that case if we consider v in the other partition we can able to connect those previously looses vertices to v and form a new bipartite subgraph of H with more edges then H' have, a contradiction. Hence it proves of my claim.

Problem 2. Determine the order and the size of the hypercube Q_k . Prove also that Q_k is k-regular and bipartite.

Solution. Clearly, $V(Q_k)$ is the set of all ordered k -tuples of 0' s and 1' s. Number of such tuples is 2^k . Therefore, $\nu(Q_k) = 2^k$.

Since two vertices are joined if and only if they differ in exactly one coordinate, it follows that each vertex is adjacent to exactly k vertices. Thus,

$$\epsilon(Q_k) = \frac{k + k + \ldots + k \ (2^k \text{ times})}{2}, \text{ since each edge is incident with two vertices.}$$
$$= k \cdot \frac{2^k}{2}$$
$$= k 2^{k-1}$$

Since two k -tuples form an edge if and only if they differ in exactly one position. Thus each vertex has degree k and so Q_k is k -regular.

Now, let $X = \{$ k-tuples with even number of 0's $\}$

 $Y = \{$ k-tuples with odd number of 0's $\}$. Now,

 $X \cup Y = Q_k$ and $X \cap Y = \phi$

Also, any two vertices of X(or Y) differ at least in two coordinates and hence they are not adjacent. Thus any edge must have one end in X and the other end in Y. Thus (X, Y) is a bipartition of Q_k , which completes the proof.

Problem 3. Prove that $\delta \leq 2 \frac{\epsilon}{\nu} \leq \Delta$. Solution. For any vertex v in any graph G, $\delta(G) \leq d(v) \leq \Delta(G)$. Taking the sum over all the vertices of V, we get

$$\begin{aligned} |V|\delta(G) &\leq \sum_{v \in V} d(v) \leq |V|\Delta(G) \\ \Rightarrow \nu \delta \leq 2\epsilon \leq \Delta \nu \end{aligned}$$

Dividing by ν , we get $\delta \leq 2 \frac{\epsilon}{\nu} \leq \Delta$.

Problem 4. If a k- regular bipartite graph with k > 0 has bi-partition (X, Y), prove that |X| = |Y|.

Solution Let G be a k- regular bipartite graph with k > 0. Since G is bipartite, every edge has one end in X and another end in Y.

Hence the number of edges incident with the vertices of X is equal to the number of edges incident with the vertices of Y. Therefore,

$$k.|X| = k.|Y|$$
, since each vertex is of degree k .
 $\Rightarrow |X| = |Y|$, since $k > 0$.

Problem 5. In any group of two or more people, prove that there are always two with the same number of friends.

Solution We construct a graph G by taking the group of n people as the set of vertices and joining two of them if they are friends. Then d(v) = number of friends of v and hence we need only to prove that at least two vertices of G have the same degree.

Let $V(G) = \{v_1, v_2, ..., v_n\}$. Clearly $0 \le d(v_i) \le n - 1$ for each *i*.

Suppose no two vertices of G have the same degree. Then the degrees of v_1, v_2, \ldots, v_n are the integers $0, 1, 2, \ldots, n-1$ in some order. However a vertex of degree n-1 is joined to every other vertex of G and hence no point can have degree 0, which is a contradiction.

Hence there exist two vertices of G with equal degree.

Problem 6. Prove that the sequence (7, 6, 5, 4, 3, 3, 2) is not graphic.

Solution. Let d = (7, 6, 5, 4, 3, 3, 2).

Suppose d is graphic. Let G be a realization of d.

Since there are 7 digits in the sequence, G has seven vertices and hence the maxi-

mum degree in G cannot exceed 7-1=6.

This contradicts the first digit in d.

Hence the given sequence is not graphic.

Problem 7. Prove that the sequence (6, 6, 5, 4, 3, 3, 1) is not graphic.

Solution. Let d = (6, 6, 5, 4, 3, 3, 1).

Suppose d is graphic. Let G be a realization of d.

Since there are 7 digits in the sequence, G has seven vertices.

The first two digits of d shows that there are two vertices which are adjacent to all the remaining 6 vertices.

Thus every vertex is adjacent to these two vertices and hence every vertex is of degree at least two.

This contradicts the last digit in d.

Hence the given sequence is not graphic.

UNIT-3

Eulerian graphs, Hamiltonian graphs

2.1 Eulerian graphs

Definition 2.1.1. A closed trail containing all the points and lines is called an eulerian trail. A graph having an eulerian trail is called an eulerian graph.

Remark 2.1.1. In an eulerian graph, for every pair of points u and v there exists at least two edge disjoint u - v trails and consequently there are at least two edge disjoint u - v paths. The graph shown in figure 2.1 is eulerian.

Theorem 2.1.1. If G is a graph in which the degree of every vertex is at least two then G contains a cycle.

Proof. First, we construct a sequence of vertices v_1, v_2, v_3, \ldots as follows. Choose any vertex v. Let v_1 be any vertex adjacent to v. Let v_2 be any vertex adjacent



Figure 2.1: A Eulerian graph

to v_1 other than v. At any stage, if the vertex v_i , $i \ge 2$ is already chosen, then choose v_{i+1} to be any vertex adjacent to v_i other than v_{i-1} . Since degree of each vertex is at least 2, the existence of v_{i+1} is always guaranteed. G has only finite number of vertices, at some stage we have to choose a vertex which has been chosen before. Let v_k be the first such vertex and let $v_k = v_i$ where i < k. Then $v_i v_{i+1} \dots v_k$ is a cycle.

Theorem 2.1.2. Let G be a connected graph. Then the following statements are equivalent.

- (1) G is eulerian.
- (2) every point has even degree.
- (3) the set of edges of G can be partitioned into cycles.

Proof.

- $(1) \Rightarrow (2)$ Assume that G is eulerian. Let T be an eulerian trail in G, with origin and terminus u. Each time a vertex v occurs in T in a place other than the origin and terminus, two of the edges incident with v are accounted for. Since an eulerian trail contains every edges of G, d(v) is even for $v \neq u$. For u, one of the edges incident with u is accounted for by the origin of T, another by the terminus of T and others are accounted for in pairs. Hence d(u) is also even.
- $(2) \Rightarrow (3)$ Since G is connected and nontrivial every vertex of G has degree at least 2. Hence G contains a cycle Z. The removal of the lines of Z results in a spanning subgraph G_1 in which again vertex has even degree. If G_1 has no edges, then all the lines of G form one cycle and hence (3) holds. Otherwise, G_1 has a cycle Z_1 . Removal of the lines of Z_1 from G_1 results in spanning subgraph G_2 in which every vertex has even degree. Continuing the above process, when a graph G_n with no edge is obtained, we obtain a partition of the edges of G into n cycles.
- $(3) \Rightarrow (1)$ If the partition has only one cycle, then G is obviously eulerian, since it is connected. Otherwise let z_1, z_2, \ldots, z_n be the cycles forming a partition of the lines of G. Since G is connected there exists a cycle $z_i \neq z_1$ having a common point v_1 with z_1 . Without loss of generality,

let it be z_2 . The walk beginning at v_1 and consisting of the cycles z_1 and z_2 in succession is a closed trail containing the edges of these two cycles. Continuing this process, we can construct a closed trail containing all the edges of G. Hence G is eulerian.

Corollary 2.1.1. Let G be a connected graph with exactly $2n(n \ge 1)$, odd vertices. Then the edge set of G can be partitioned into n open trails.

Proof. Let the odd vertices of G be labelled $v_1, v_2, \ldots, v_n; w_1, w_2, \ldots, w_n$ in any arbitrary order. Add n edges to G between the vertex pairs $(v_1, w_1), (v_2, w_2), \ldots, (v_n, w_n)$ to form a new graph G'. No two of these n edges are incident with the same vertex. Further every vertex of G' is of even degree and hence G' has an eulerian trail T. If the n edges that we added to G are now removed from T, it will split into n open trails. These are open trails in G and form a partition of the edges of G.

Corollary 2.1.2. Let G be a connected graph with exactly two odd vertices. Then G has an open trail containing all the vertices and edges of G.

Corollary 2.1.2 answers the question: Which diagrams can be drawn without lifting one's pen from the paper not covering any line segment more than once?

Definition 2.1.2. A graph is said to be arbitrarily traversable(traceable)from a vertex v if the following procedure always results in an eulerian trail. Start at v by traversing any incident edge. On arriving at a vertex u, depart through any incident edge not yet traversed and continue until all the lines are traversed.

If a graph is arbitrary traversable from a vertex then it obviously eulerian.

The graph shown in figure 2.1 is arbitrarily traversable from v. From no other point it is arbitrarily traversable.

Theorem 2.1.3. An eulerian graph G is arbitrarily traversable from a vertex v in G iff every cycle in G contains v.



Figure 2.2: A theta graph

2.1.1 Exercise

- 1. For what values of n, is K_n eulerian?
- 2. For what values of m and n is $K_{n,m}$ is eulerian?
- 3. Show that if G has no vertices of odd degree, then there are edge disjoint cycles C_1, C_2, \ldots, C_n such that

$$E(G) = E(C_1) \cup E(C_2) \cup \ldots \cup E(C_m)$$

4. Show that every block of a connected graph G is eulerian then G is eulerian.

2.2 Hamiltonian Graphs

Definition 2.2.1. A spanning cycle in a graph is called a hamiltonian cycle. A graph having a hamiltonian cycle is called a hamiltonian graph.

Definition 2.2.2. A block with two adjacent vertices of degree 3 and all other vertices of degree 2 is called a theta graph.

Example 2.2.1. The graph shown in figure 2.2 is a theta graph. A theta graph is obviously nonhamiltonian and every nonhamiltonian 2-connected graph has a theta subgraph.

Theorem 2.2.1. Every hamiltonian graph is 2-connected.

Proof. Let G be a hamiltonian graph and let Z be a hamiltonian cycle in G. For any vertex v of G, Z - v is connected and hence G - v is also connected. Hence G has no cutpoints and thus G is 2-connected.

Theorem 2.2.2. If G is hamiltonian, then for every nonempty proper subset S of V(G), $\omega(G-S) \leq |S|$ where $\omega(H)$ denote the number of components in any graph H.

Proof. Let Z be a hamiltonian cycle of G. Let S be any nonempty proper subset of V(G). Now, $\omega(Z - S) \leq |S|$. Also Z - S is a spanning subgraph of G - S and hence $\omega(G - S) \leq \omega(Z - S)$. Hence $\omega(G - S) \leq |S|$.

Theorem 2.2.3. The bipartite graph $K_{m,n}$ is nonhamiltonian.

Proof. Let (V_1, V_2) be a bipartition of the graph with $|V_1| = m$ and $|V_2| = n$. The graph $K_{m,n} - V_1$ is the totally disconnected graph with n points. Hence $\omega(K_{m,n} - V_1) = n > m = |V_1|$. Therefore $K_{m,n}$ is non hamiltonian.

Remark 2.2.1. The converse of theorem [2.2.2] is not true. For example, Petersen graph satisfies the condition of the theorem but is nonhamiltonian.

Theorem 2.2.4. If G is a graph with $p \ge 3$ vertices and $\delta \ge p/2$, then G is hamiltonian.

Proof. Suppose the theorem is false. Let G be a maximal nonhamiltonian graph with p vertices and $\delta \geq p/2$. Since $p \geq 3$, G can not be complete. Let u and v be nonadjacent vertices in G. By the choice of G, G + uv is hamiltonian. Moreover, since G is nonhamiltonian, each hamiltonian cycle of G + uv must contain the line uv. Thus G has a spanning path v_1, v_2, \ldots, v_p with origin $u = v_1$ and terminus $v = v_p$. Let $S = \{v_i : uv_{i+1} \in E\}$ and $T = \{v_i : i where E is the edge set of G. Clearly <math>v_p \notin S \cup T$ and hence

$$|S \cup T|$$

Again if $v_i \in S \cap T$, then $v_1 v_2 \dots v_i v_p v_{p-1} \dots v_{i+1} v_i$ is a hamiltonian cycle in G, contrary to the assumption. Hence $S \cap T = \emptyset$ so that

$$|S \cap T| = 0. \tag{2.2}$$

Also by the definition of S and T, d(u) = |S| and d(v) = |T|. Hence by equations (2.1) and (2.2), $d(u) + d(v) = |S| + |T| = |S \cup T| < p$. Thus d(u) + d(v) < p. But since $\delta \ge p/2$, we have $d(u) + d(v) \ge p$ which gives a contradiction.

Figure 2.3: A tree(left) and a forest(right)

Lemma 1. Let G be a graph with p points and let u and v be nonadjacent points in G such that $d(u) + d(v) \ge p$. Then G is hamiltonian if and only if G + uv is hamiltonian.

Proof. First, assume that G is hamiltonian. Then obviously G + uv is hamiltonian. Conversely, assume that G + uv is hamiltonian, but G is not. Then, as in the proof of theorem [2.2.4], we obtain d(u) + d(v) < p. This contradicts the hypothesis that $d(u) + d(v) \ge p$. Thus G + uv is hamiltonian implies G is hamiltonian.

UNIT-4

2.3 Trees

2.3.1 Characterization of Trees

Definition 2.3.1. A graph that contains no cycles is called a an acyclic graph. A connected acyclic graph is called a tree. A graph without cycles is also called a forest so that the components of a forest are trees.

Example 2.3.1. An example of a tree and a forest is shown in figure 2.3.

Theorem 2.3.1. Let G be a (p,q) graph. The following statements are equivalent.

- (1) G is a tree.
- (2) every two points of G are joined by a unique path.
- (3) G is connected and p = q + 1

(4) G is acyclic and p = q + 1

Proof.

(1) \Rightarrow (2) Assume that G is a tree. Let u and v be any two points of G. Since G is connected there exists a u - v path in G. Now suppose that there exists two distinct u - v paths, say:

$$P_1: u = v_0, v_1, v_2, \dots, v_n = v \text{ and } P_2: u = w_0, w_1, \dots, w_m = v$$

Let *i* be the least positive integer such that $1 \leq i < m$ and $w_i \notin P_1$ (such an *i* exists since P_1 and P_2 are distinct). Hence $w_{i-1} \in P_1 \cap P_2$. Let *j* be the least positive integers such that $i < j \leq m$ and $w_j \in P_1$. Then the $w_{i-1} - w_j$ path along P_2 followed by the $w_j w_{i-1}$ path along P_1 form a cycle which is a contradiction. Hence there exists a unique u - v path in *G*.

 $(2) \Rightarrow (3)$ Assume that every two points of G are joined by a unique path. This implies that G is connected. We will show that p = q+1 by induction on p. The result is trivial for connected graphs with 1 or 2 points. Assume that the result is true for all graphs with fewer than p points. Let G be a graph with p points. Let x = uv be any line in G. Since there exists a unique u - v path in G, G - x is a disconnected graph with exactly two components G_1 and G_2 . Let G_1 be a (p_1, q_1) graph and G_2 be a (p_2, q_2) graph. Then $p_1 + p_2 = p$ and $q_1 + q_2 = q - 1$. Further by induction hypothesis $p_1 = q_1 + 1$ and $p_2 = q_2 + 1$. Hence

$$p = p_1 + p_2 = q_1 + q_2 + 2 = q - 1 + 2 = q + 1$$

(3) \Rightarrow (4) Assume that G is connected and p = q + 1. We will show that G is acyclic. Suppose G contains a cycle of length n. There are n points and n lines on this cycle. Fix a point u on the cycle. Consider any one the remaining p - n points not on the cycle, say v. Since G is connected we can find a shortest u - v path in G. Consider the line on this shortest path incident with v. The p - n lines thus obtained are all distinct. Hence $q \ge (p - n) + n = p$ which is a contradiction since q + 1 = p. Thus G is acyclic.

(4) \Rightarrow (1) Assume that G is acyclic and p = q + 1. We will prove that G is a tree. Since G is acyclic to prove that G is a tree we need only prove that G is connected. Suppose G is not connected. Let $G_1, G_2, \ldots, G_k (k \ge 2)$ be the components of G. Since G is acyclic each of these components is a tree. Thus $q_i + 1 = p_i$ where G_i is a (p_i, q_i) graph. This implies that $\sum_{i=1}^k q_i + 1$ = $\sum_{i=1}^k p_i$. That is, q + k = p and $k \ge 2$, which is a contradiction. Hence G is connected.

Corollary 2.3.1. Every non trivial tree G has at least two vertices of degree one.

Proof. Since G is non trivial, $d(v) \ge 1$ for all points v. Also $\sum d(v) = 2q = 2(p-1) = 2p-2$. Hence d(v) = 1 for at least two vertices.

Theorem 2.3.2. Every connected graph has a spanning tree.

Proof. Let G be a connected graph. Let T be a minimal connected spanning subgraph of G. Then for any line x of T, T - x is disconnected and hence x is a bridge of T. Hence T is acyclic. Further T is connected and hence is a tree.

Corollary 2.3.2. Let G be a (p,q) connected graph. Then $q \ge p-1$.

Proof. Let T be a spanning tree of G. Then the number of lines in T is p-1. Hence $q \ge p-1$.

Theorem 2.3.3. Let T be a spanning tree of a connected graph G. Let x = uv be an edge of G not in T. Then T + x contains a unique cycle.

Proof. Since T is acyclic every cycle in T + x must contain x. Hence there exists a one to one correspondence between cycles in T + x and u - v paths in T. As there is a unique u - v path in tree T, there is a unique cycle in T + x.

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2.3.2 Centre of a Tree

Definition 2.3.2. Let v be a point in a connected graph G. The eccentricity e(v) of v is defined by $e(v) = \max\{d(u, v) : u \in V(G)\}$. The radius r(G) is defined by $r(G) = \min\{e(v) : v \in V(G)\}$. The point v is called the central point if e(v) = r(G) and the set of central points is called the centre of G.

Theorem 2.3.4. Every tree has a centre consisting of either one point or two adjacent points.

Proof. The result is trivial if $G = K_1$ or K_2 . So assume that let T be any tree with $p \ge 2$ points. T has at least two end points and maximum distance from a given point u to any other point v occurs only when v is an end point. Now delete all the end points from T. The resulting graph T' is also a tree and eccentricity of each point in T' is exactly one less than the eccentricity of the same point in T. Hence T and T' have the same centre. If the process of removing the end points is repeated, we obtain successive trees having the same centres as T and we eventually obtain a tree which is either K_1 or K_2 . Hence the centre of T consists of either one point or two adjacent points.

2.3.3 Exercise

- 1. Show that there does not exists a nonhamiltonian graph with arbitrarily high eccentricity.
- 2. Prove that a graph G is tree iff G is connected and every line of G is a bridge.
- 3. Prove that if G is a forest with p points and k components then G has p k lines.
- 4. Prove that the origin and terminus of a longest path in a tree have degree one.
- 5. Show that every tree with exactly 2 vertices of degree one is a path.
- 6. Show that every tree is a bipartite graph. Which trees are complete bipartite graphs.

- 7. Prove that every block of a tree is K_2 .
- 8. Draw all trees with 4 and 5 vertices.
- 9. Prove that any edge of a connected graph G one of whose end point is of degree one is contained in every spanning tree of G.
- 10. Prove that a line x of a connected graph is in every spanning tree of G iff x is a bridge.

3.6 Planarity

Definition 3.6.1. A graph is said to be embedded in a surface S when it is drawn on S such that no two edges intersect(meetins of edges at a vertex is not considered an intersection). A graph is called planar if it can be drawn on a plane without intersecting edges. A graph is called non planar if it is not planar. A graph that is drawn on the plane without intersecting edges is called a plane graph.

Example 3.6.1. The graph shown in figure (3.4) is planar.

Theorem 3.6.1. The complete graph K_5 is non planar.

Proof. If possible, let K_5 be planar. Then K_5 contains a cycle of length 5 say (s, t, u, v, w, s). Hence, without loss of generality, any plane embedding of K_5 can be assumed to contain this cycle drawn in the form of a regular pentagon. Hence the edge wt must lie either wholly inside the pentagon or wholly outside it.

Suppose that wt is wholly inside the pentagon(the argument when it lies wholly outside the pentagon is quite similar). Since the edge sv and su do not cross the edge wt, they must be both lie outside the pentagon. The edge vtcannot cross the edge su. Hence vt must be inside the pentagon. But now, the edge uw crosses one of the edges already drawn, giving a contradiction. Hence K_5 is not planar.

Definition 3.6.2. Let G be a graph embedded on a plane π . Then $\pi - G$ is the union of disjoint regions. Such regions are called faces of G. each plane graph has exactly one unbounded face and it is called the exterior face. Let Fbe a face of plane graph G and e be an edge of G. Let P be a point in F. eis said to be in the boundary of F if for every point Q of π on e there exists a curve joining P and Q which lies entirely in F.

Theorem 3.6.2. A graph can be embedded in the surface of a sphere iff it can be embedded in a plane.

Proof. Let G be a graph embedded on a sphere. Place the sphere on the plane L and call the point of contact S(south pole). At point S, draw a normal to the plane and let N (North pole) be the point where this normal intersects the surface of the sphere.

Assume that the sphere is placed in such a way that N is disjoint from G. For each point P on the sphere, let P' be the unique point on the plane where the line NP intersects the surface of the plane. There is a one to one correspondence between the points of the sphere other than N and the points on the plane. In this way, the vertices and the edges of G can be projected on the plane L, which gives an embedding of G in L.

The reverse process obviously gives an embedding in the sphere for any graph that is embedded in the plane L. This completes the proof.

Theorem 3.6.3. Every planar graph can be embedded in a plane such that all edges are straight line segments

Definition 3.6.3. A graph is ployhedral if its vertices and edges may be identified with the vertices and edges of a convex polyhedron in the three dimensional space.

Theorem 3.6.4. A graph is polyhedral if and only if it is planar and 3 connected.

Theorem 3.6.5. Every polyhedron that has at last two faces with the same number of edges on the boundary.

Proof. The corresponding graph G is 3 connected. Hence $\delta(G) \geq 3$ and the number of faces adjacent to any chosen face f is equal to the number of edges in the boundary of the face f (if two faces have the edges u and vw with $r \neq w$ in common, then $G - \{r, w\}$ is disconnected contradicting 3 connectedness). Let f_1, f_2, \ldots, f_m be the faces of the polyhedron and e_i be the number of edges on the boundary of the ith face. Let the faces be labelled so that $e_i \leq e_{i+1}$ for every i. If no two faces have the same number of edges in their boundaries, then $e_{i+1} - e_i \geq 1$ for every i. Hence $e_m - e_1 = \sum_{i=1}^{m-1} (e_{i+1} - e_i) \geq m - 1$ so that $e_m \geq e_1 + m - 1$. Since $e_1 \geq 3$, this implies that $e_m \geq m + 2$ so that the mth face is adjacent to at least m+2 faces. This gives a contradiction as there are only m faces. This proves the theorem.

Theorem 3.6.6 (Euler Theorem). If G is a connected plane graph having V, E, and F as the set of vertices, edges and faces respectively, then |V| - |E| + |F| = 2.

Proof. The proof is by induction on the number of edges of G. Let |E| = 0. Since G is connected, it is K_1 so that |V| = 1, |F| = 1 and hence |V| - |E| + |F| = 2. Now let G be a graph as in theorem and suppose that the theorem is true for all connected plane graphs with at most |E| - 1 edges.

If G is a tree, then |E| = |V| - 1 and |F| = 1 and hence |V| - |E| + |F| = 2. If G is not a tree, let x be an edge contained in some cycle of G. Then G' = G - xis a connected plane graph such that |V(G')| = |V|, |E(G')| = |E| - 1 and |F(G')| = |F| - 1. Hence by induction hypothesis |V(G')| - |E(G')| + |F(G')| =2 so that |V| - (|E| - 1) + |F| - 1 = 2. Hence |V| - |E| + |F| = 2.

Theorem 3.6.7. If G is a plane (p,q) graph with r faces and k components then p - q + r = k + 1.

Proof. Consider a plane embedding of G such that the exterior face of each component contains all other components. Now let the *i*th component be a (p_i, q_i) graph with r_i faces for each *i*. By the theorem $p_i - q_i + r_i = 2$. Hence

$$\sum p_i - \sum q_i + \sum r_i = 2k \tag{3.5}$$

But $\sum p_i = p, \sum q_i = q$ and $\sum r_i = r + (k - 1)$. Since the infinite face is

counted k times in $\sum r_i$, hence equation (3.5) gives p - q + r + k - 1 = 2k so that p - q + r = k + 1.

Corollary 3.6.1. If G is a (p,q) plane graph in which every face is an n cycle then q = n(p-2)/(n-2).

Proof. Every face is an *n*-cycle. Hence each edge lies on the boundary of exactly two faces. Let f_1, f_2, \ldots, f_r be the faces of G. Therefore

$$2q = \sum_{i=1}^{r} (\text{number of edges in the boundary of the face } f_i) = nr$$

This implies that r = 2q/n. By Eulers formula p - q + r = 2. That is

$$p-q+2q/n=2$$

 $q(2/n-1)=2-pq$ $= n(p-2)/(n-2)$

Corollary 3.6.2. In any connected plane (p,q) graph $(p \ge 3)$ with r faces $q \ge 3r/2$ and $q \le 3p - 6$.

Proof.

- **Case 1** Let G be a tree. Then r = 1, q = p 1 and $p \ge 3$. Hence $q \ge 3r/2$ and $q \le 3p - 6$ since $p - 1 \le 3p - 6$ (as $p \ge 3$).
- **Case 2** Let G have a cycle. let f_i i = 1, 2, ..., r be the faces of G. Since each edge lies on the boundary of almost two faces,

$$2q \ge \sum_{i=1}^{r} (\text{number of edges in the boundary of face } f_i)$$

That is,

 $2q \ge 3r$

That is

$$q \le 3r/2 \tag{3.6}$$

By Euler's formula, p - q + r = 2. Substituting for r in equation (3.6), we get $q \ge 3/2(2 + q - p)$. After simplification we get, $q \le 3p - 6$.

Definition 3.6.4. A graph is called maximal planar if no line can be added to it without losing planarity. In a maximal planar graph, each face is a triangle and such a graph is sometimes called a triangulated graph.

Corollary 3.6.3. If G is a maximal planar (p,q) graph then q = 3p - 6.

Corollary 3.6.4. If G is a plane connected (p,q) graph without triangles and $p \ge 3$, then $q \le 2p - 4$.

Proof. If G is a tree, then q = p - 1. Hence we have $p - 1 = q \leq 2p - 4$. Now let G have a cycle. Since G has no triangles, the boundary of each face has at least four edges. Since each edge lies on at most two faces we have, $2q \geq \sum_{i=1}^{r}$ (number of edges in the boundary of the ith face). That is,

$$2q \ge 4r. \tag{3.7}$$

By Euler's formula, we have p-q+r=2. Substituting for r in equation (3.7), we get $2q \ge 4(2+q-p)$. Hence $4p-8 \ge 2q$ so that $q \le 2p-4$.

Corollary 3.6.5. The graphs K_5 and $K_{3,3}$ are not planar.

Proof. Note that K_5 is a (5, 10) graph. For any planar (p, q) graph, $q \leq 3p-6$. But q = 10 and p = 5 do not satisfy this inequality. Hence K_5 is not planar. Also note that $K_{3,3}$ is a (6,9) bipartite graph and hence has no triangles. If such a graph is planar, then by Corollary refq12, $q \leq 2p - 4$. But p = 6 and q = 9 do not satisfy this inequality. Hence $K_{3,3}$ is not planar.

Corollary 3.6.6. Every planar graph G with $p \ge 3$ points has at least three points of degree less than 6.

By Corolary 3.6.2, $q \leq 3p-6$. That is, $2q \leq 6p-12$. That is, $\sum d_i \leq 6p-12$ where d_i are the degrees of the vertices of G. Since G is connected, $d_i \leq 1$ for every i. If at most two d_i are less than 6, then $\sum d_i \geq 1+1+6+\ldots+(p-2) =$ 6p-10 which is a contradiction. Hence $d_i < 6$ for at least three values of i.

Theorem 3.6.8. Every planar graph G with at least 3 points is a subgraph of a triangulated graph with the same number of points.

Proof. Let G have p vertices. If $p \leq 4$, then G must be a subgraph of K_p which is a triangulated graph. Hence let $p \geq 5$.

We construct a triangulated graph G' which contains G as a subgraph as follows:

Consider a plane embedding of G. If R is a face of G and v_1 and v_2 are two vertices on the boundary of R without a connecting edge we connect v_1 and v_2 with an edge lying entirely in R. This yields a new plane graph. This yields a new plane graph. This operation is continued until every pair of vertices on the boundary of the same face are connected by an edge. The number of vertices remains the same under these operation. Hence the process terminates after some time yielding a plane triangulated graph G'. G is obviously a subgraph of G'.

3.6.1 Characterization of Planar Graphs

Definition 3.6.5. Let x = uv be an edge of a graph G. Line x is said to be subdivided when a new point w is adjoined to G and the line x is replaced by the lines uw and wv. This process is also called an elementary subdivision of the edge x. Two graphs are called homeomorphic if both can be obtained from the same graph by a sequence of subdivisions of the lines.

Example 3.6.2. Any two cycles are homeomorphic.

Theorem 3.6.9 (Kuratowski Theorem). A graph is planar if and only if it has no subgraph homeomorphic to K_5 or $K_{3,3}$.

Remark 3.6.1. The graphs K_5 and $K_{3,3}$ are called Kuratowski's graphs.

Definition 3.6.6. Let u and v be two adjacent points in a graph G. The graph obtained from G by the removal of u and v and the addition of a new point w adjacent to those points to which u or v was adjacent is called an elementary contraction of G. A graph G is contractible to a graph H if H can be obtained from G by a sequence of elementary contractions.

Example 3.6.3. The Petersen graph given in figure 3.5 is contractible to K_5 by contracting the lines 1a, 2b, 3c, 4d and 5e.



Figure 3.5: Petersen Graph

Theorem 3.6.10. A graph is planar if and only if it does no have a subgraph contractible to K_5 or $K_{3,3}$.

Since the Petersen graph is contractible to K_5 , it is not planar according to the theorem [3.6.10].

Definition 3.6.7. Given a plane graph G, its geometrical dual G^* is constructed as follows: Place a vertex in each face of G(including the exterior face). For each edge x of G, draw an edge x^* joining the vertices representing the faces on both sides x such that x^* crosses only the edge x. The result is always a plane graph $G^*($ possibly with loops and multiple edges).

UNIT- 5 DIGRAPHS

This chapter and the following one deal with digraphs and their applications. In Section 22 we give some basic definitions, and discuss whether we can 'direct' the edges of a graph so that the resulting digraph is strongly connected. This is followed by a brief discussion of critical path analysis, and, in Section 23, by a discussion of Eulerian and Hamiltonian trails and cycles, with particular reference to tournaments. We conclude the chapter by studying the classification of states of a Markov chain.

22 Definitions

A **directed graph**, or **digraph**, *D* consists of a non-empty finite set V(D) of elements called **vertices**, and a finite family A(D) of ordered pairs of elements of V(D) called **arcs**. We call V(D) the **vertex set** and A(D) the **arc family** of *D*. An arc (v, w) is usually abbreviated to *vw*. Thus in Fig. 22.1, V(D) is the set $\{u, v, w, z\}$ and A(D) consists of the arcs *uv*, *vv*, *vw* (twice), *wv*, *wu* and *zw*, the ordering of the vertices in an arc being indicated by an arrow. If *D* is a digraph, the graph obtained from *D* by 'removing the arrows' (that is, by replacing each *arc* of the form *vw* by a corresponding *edge vw*) is the **underlying graph** of *D* (see Fig. 22.2).



D is a **simple digraph** if the arcs of D are all distinct, and if there are no 'loops' (arcs of the form vv). Note that the underlying graph of a simple digraph need not be a simple graph (see Fig. 22.3).


We can imitate many of the definitions given in Section 2 for graphs. For example, two digraphs are **isomorphic** if there is an isomorphism between their underlying graphs that preserves the ordering of the vertices in each arc. Note that the digraphs in Figs. 22.1 and 22.4 are not isomorphic.

Two vertices *v* and *w* of a digraph *D* are **adjacent** if there is an arc in *A*(*D*) of the form *vw* or *wv*. The vertices *v* and *w* are **incident** to such an arc. If *D* has vertex set $\{v_1, \ldots, v_n\}$, the **adjacency matrix** of *D* is the $n \times n$ matrix $\mathbf{A} = (a_{ij})$, where a_{ij} is the number of arcs from v_i to v_i .

There are also natural generalizations to digraphs of the definitions of Section 5. A walk in a digraph *D* is a finite sequence of arcs of the form $v_0v_1, v_1v_2, \ldots, v_{m-1}v_m$. We sometimes write this sequence as $v_0 \rightarrow v_1 \rightarrow \cdots \rightarrow v_m$, and speak of a **walk from v_0 to** v_m . In an analogous way, we can define directed trails, directed paths and directed cycles or, simply, trails, paths and cycles, if there is no possibility of confusion. Note that, although a trail cannot contain a given arc vw more than once, it can contain both vw and wv; for example, in Fig. 22.1, $z \rightarrow w \rightarrow v \rightarrow w \rightarrow u$ is a trail.

We can also define connectedness. The two most useful types of connected digraph correspond to whether or not we take account of the direction of the arcs. These definitions are the natural extensions to digraphs of the definitions of connectedness given in Sections 2 and 5.

A digraph D is **connected** if it cannot be expressed as the union of two digraphs, defined in the obvious way. This is equivalent to saying that the underlying graph of D is a connected graph. D is **strongly connected** if, for any two vertices v and w of D, there is a path from v to w. Every strongly connected digraph is connected, but not all connected digraphs are strongly connected; for example, the connected digraph of Fig. 22.1 is not strongly connected since there is no path from v to z.

The distinction between a connected digraph and a strongly connected one becomes clearer if we consider the road map of a city, all of whose streets are one-way. If the road map is connected, then we can drive from any part of the city to any other, ignoring the direction of the one-way streets as we go. If the map is strongly connected, then we can drive from any part of the city to any other, always going the 'right way' down the one-way streets.

Since every one-way system should be strongly connected, it is natural to ask when we can impose a one-way system on a street map in such a way that we can drive from any part of the city to any other. If, for example, the city consists of two parts connected only by a bridge, then we cannot impose such a one-way system on the city, since whatever direction we give to the bridge, one part of the city must be cut off. If, on the other hand, there are no bridges, then we can always impose such a one-way system. This result is stated formally in Theorem 22.1.

For convenience, we define a graph G to be **orientable** if each edge of G can be directed so that the resulting digraph is strongly connected. For example, if G is the graph shown in Fig. 22.5, then G is orientable, since its edges can be directed to give the strongly connected digraph of Fig. 22.6.



Note that any Eulerian graph is orientable, since we simply follow any Eulerian trail, directing the edges in the direction of the trail as we go. We now give a necessary and sufficient condition (due to H.E. Robbins) for a graph to be orientable.

THEOREM 22.1. Let G be a connected graph. Then G is orientable if and only if each edge of G is contained in at least one cycle.

Proof. The necessity of the condition is clear. To prove the sufficiency, we choose any cycle C and direct its edges cyclically. If each edge of G is contained in C, then the proof is complete. If not, we choose any edge e that is not in C but which is adjacent to an edge of C. By hypothesis, e is contained in some cycle C' whose edges we may direct cyclically, except for those edges that have already been directed – that is, those edges of C' that also lie in C. It is not difficult to see that the resulting digraph is strongly connected; the situation is illustrated in Fig. 22.7, with dashed lines denoting edges of C'. We proceed in this way, at each stage directing at least one new edge, until all edges are directed. Since the digraph remains strongly connected at each stage, the result follows. //



Fig. 22.7

We conclude this section by discussing a 'critical path' problem relating to the scheduling of a series of operations. Suppose that we have a job to perform, such as the building of a house, and that this job can be divided into a number of activities, such as laying the foundations, putting on the roof, doing the wiring, etc. Some of these activities can be performed simultaneously, whereas some may need to be completed before others can be started. Can we find an efficient method for determining which activities should be performed at which times so that the entire job is completed in minimum time?



In order to solve this problem, we construct a 'weighted digraph', or **activity network**, in which each arc represents the length of time taken for an activity. Such a network is given in Fig. 22.8. The vertex *A* represents the beginning of the job, and the vertex *L* represents its completion. Since the entire job cannot be completed until each path from *A* to *L* has been traversed, the problem reduces to that of finding the longest path from *A* to *L*. This is accomplished by using a technique known as programme evaluation and review technique (PERT), which is similar to that we used for the shortest path problem in Section 8, except that as we move across the digraph from left to right, we associate with each vertex *V* a number l(V) indicating the length of the *longest* path from *A* to *V*. So for the digraph of Fig. 22.8, we assign:

to vertex A, the number 0;

to vertex *B*, the number l(A) + 3 – that is, 3;

- to vertex C, the number l(A) + 2 that is, 2;
- to vertex D, the number l(B) + 2 that is, 5;
- to vertex E, the number max $\{l(A) + 9, l(B) + 4, l(C) + 6\}$ that is, 9;
- to vertex F, the number l(C) + 9 that is, 11;
- to vertex G, the number max $\{l(D) + 3, l(E) + 1\}$ that is, 10;
- to vertex H, the number max $\{l(E) + 2, l(F) + 1\}$ that is, 12;
- to vertex *I*, the number l(F) + 2 that is, 13;
- to vertex J, the number max $\{l(G) + 5, l(H) + 5\}$ that is, 17;
- to vertex K, the number max $\{l(H) + 6, l(I) + 2\}$ that is, 18;
- to vertex *L*, the number max $\{l(H) + 9, l(J) + 5, l(K) + 3\}$ that is, 22.

As in the shortest path problem, we keep track of these numbers by writing each one next to the vertex it represents. Note that, unlike the problem that we considered in Section 8, there is no 'zig-zagging', since all arcs are directed from left to right. Thus, the longest path has length 22, and is given in Fig. 22.9. The job cannot therefore be completed until time 22.

This longest path is often called a **critical path**, since any delay in an activity on this path creates a delay in the whole job. In scheduling a job, we therefore need to pay particular attention to the critical paths.

We can also calculate the latest time by which any given operation must be completed if the work is not to be delayed. Working back from *L*, we see that we must reach *K* by time 22 - 3 = 19, *J* by time 22 - 5 = 17, *H* by time min $\{17 - 5, 22 - 9, 19 - 6\} = 12$, and so on.





Exercises 22

22.1^s Two of the digraphs in Fig. 22.10 are isomorphic. Which two are they?



Fig. 22.10

- **22.2**^s Let D be a simple digraph with n vertices and m arcs.
 - (i) Prove that if *D* is connected, then $n 1 \le m \le n(n 1)$.
 - (ii) Obtain corresponding bounds for m if D is strongly connected.
- **22.3**^s Write down adjacency matrices for the digraphs in Figs 22.1 and 22.6.
- **22.4** The converse \tilde{D} of a digraph *D* is obtained by reversing the direction of each arc of *D*.
 - (i) Give an example of a digraph that is isomorphic to its converse.
 - (ii) What is the connection between the adjacency matrices of D and \tilde{D} ?
- 22.5 (i) Without using Theorem 22.1, prove that every Hamiltonian graph is orientable.
 - (ii) Show, by finding an orientation for each, that K_n $(n \ge 3)$ and $K_{r,s}$ $(r, s \ge 2)$ are orientable.
 - (iii) Find orientations for the Petersen graph and the graph of the dodecahedron.
- **22.6**^s In the above scheduling problem, calculate the latest times at which we can reach the vertices G, E and B.
- **22.7** Find the longest path from *A* to *G* in the network of Fig. 22.11.



Fig. 22.11

23 Eulerian digraphs and tournaments

In this section we obtain digraph analogues of some results of Sections 6 and 7. In particular, we study Hamiltonian cycles in a type of digraph called a tournament.

A connected digraph D is **Eulerian** if there exists a closed trail containing every arc of D. Such a trail is an **Eulerian trail**. For example, the digraph in Fig. 23.1 is not Eulerian, although its underlying graph is an Eulerian graph.



Fig. 23.1

Our first aim is to give a necessary and sufficient condition, analogous to the one in Theorem 6.2, for a connected digraph to be Eulerian. Note that a necessary condition is that the digraph is strongly connected.

We need some preliminary definitions. The **out-degree** of a vertex v of D is the number of arcs of the form vw, and is denoted by outdeg(v). Similarly, the **in-degree** of v is the number of arcs of D of the form wv, and is denoted by indeg(v). Note that the sum of the out-degrees of all the vertices of D is equal to the sum of their in-degrees, since each arc of D contributes exactly 1 to each sum. We call this result the **hand-shaking dilemma**!

For later convenience, we define a **source** of D to be a vertex with in-degree 0, and a **sink** of D to be a vertex with out-degree 0. Thus, in Fig. 23.1, v is a source and w is a sink. Note that any Eulerian digraph with at least one arc has no sources or sinks. We can now state the basic theorem on Eulerian digraphs.

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THEOREM 23.1. A connected digraph is Eulerian if and only if for each vertex v of D outdeg(v) = indeg (v).
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Proof. The proof is entirely analogous to that of Theorem 6.2 and is left as an exercise. //

We leave it to you to define a semi-Eulerian digraph, and to prove results analogous to Corollaries 6.3 and 6.4.

The corresponding study of Hamiltonian digraphs is, as may be expected, less successful than for Eulerian digraphs. A digraph D is **Hamiltonian** if there is a cycle that includes every vertex of D. A non-Hamiltonian digraph that contains a path passing through every vertex is **semi-Hamiltonian**. Little is known about Hamiltonian digraphs, and several theorems on Hamiltonian graphs do not generalize easily, if at all, to digraphs.

It is natural to ask whether there is a generalization to digraphs of Dirac's theorem (Corollary 7.2). One such generalization is due to Ghouila-Houri; its proof is considerably more difficult than that of Dirac's theorem, and can be found in Bondy and Murty [7].

THEOREM 23.2. Let D be a strongly connected digraph with n vertices. If $outdeg(v) \ge n/2$ and $indeg(v) \ge n/2$ for each vertex v, then D is Hamiltonian.

It seems that such results will not come easily, and so we consider instead which types of digraph are Hamiltonian. In this respect, the tournaments are particularly important, the results in this case taking a very simple form.

A **tournament** is a digraph in which any two vertices are joined by exactly one arc (see Fig. 23.2). Such a digraph can be used to record the result of a tennis tournament, or any other game in which draws are not allowed. In Fig. 23.2, for example, team z beats team w, but is beaten by team v, and so on.



Fig. 23.2

Because tournaments may have sources or sinks, they are not in general Hamiltonian. However, the following theorem, due to L. Rédei and P. Camion, shows that every tournament is 'nearly Hamiltonian'.

THEOREM 23.3. (*i*) Every non-Hamiltonian tournament is semi-Hamiltonian; (*ii*) every strongly connected tournament is Hamiltonian.

Proof. (i) The statement is clearly true if the tournament has fewer than four vertices. We prove the result by induction on the number of vertices, and assume that every non-Hamiltonian tournament on n vertices is semi-Hamiltonian.

Let *T* be a non-Hamiltonian tournament on n + 1 vertices, and let *T'* be the tournament on *n* vertices obtained by removing from *T* a vertex *v* and its incident arcs. By the induction hypothesis, *T'* has a semi-Hamiltonian path $v_1 \rightarrow v_2 \rightarrow \cdots \rightarrow v_n$. There are now three cases to consider:

(1) if vv_1 is an arc in *T*, then the required path is

 $v \to v_1 \to v_2 \cdots \to v_n$.

(2) if vv_1 is not an arc in *T*, which means that v_1v is, and if there exists an *i* such that vv_i is an arc in *T*, then choosing *i* to be the first such, the required path is (see Fig. 23.3)

 $v_1 \rightarrow v_2 \rightarrow \cdots \rightarrow v_{i-1} \rightarrow v \rightarrow v_i \rightarrow \cdots \rightarrow v_n.$

(3) if there is no arc in T of the form vv_i , then the required path is

 $v_1 \rightarrow v_2 \rightarrow \cdots \rightarrow v_n \rightarrow v.$



Fia. 23.3

(ii) We prove the stronger result that a strongly connected tournament T on n vertices contains cycles of length 3, 4, \ldots , *n*. To show that *T* contains a cycle of length 3, let v be any vertex of T, and let W be the set of all vertices w such that vw is an arc in T, and Z be the set of all vertices z such that zv is an arc. Since T is strongly connected, W and Z must both be non-empty, and there must be an arc in T of the form w'z'. where w' is in W and z' is in Z (see Fig. 23.4). The required cycle of length 3 is then $v \to w' \to z' \to v$.

It remains only to show that, if there is a cycle of length k, where $k \le n$, then there is one of length k + 1. Let $v_1 \rightarrow \cdots \rightarrow v_k \rightarrow v_1$ be such a cycle. Suppose first that there exists a vertex v not contained in this cycle, such that there exist arcs in T of the form vv_i and of the form v_iv . Then there must be a vertex v_i such that both $v_{i-1}v$ and vv_i are arcs in T. The required cycle is then (see Fig. 23.5)

 $v_1 \rightarrow v_2 \rightarrow \cdots \rightarrow v_{i-1} \rightarrow v \rightarrow v_i \rightarrow \cdots \rightarrow v_k \rightarrow v_1.$



Fig. 23.5

Fig. 23.6

If no vertex exists with the above-mentioned property, then the set of vertices not contained in the cycle may be divided into two disjoint sets W and Z, where W is the set of vertices w such that $v_i w$ is an arc for each i, and Z is the set of vertices z such that zv_i is an arc for each *i*. Since *T* is strongly connected, *W* and *Z* must both be non-empty, and there must be an arc in T of the form w'z', where w' is in W and z' is in Z. The required cycle is then (see Fig. 23.6)

$$v_1 \to w' \to z' \to v_3 \to \cdots \to v_k \to v_1. //$$

Exercises 23

23.1^s Verify the handshaking dilemma for the tournaments of Figs. 23.2 and 23.7.



Fig. 23.7

- 23.2^s In the tournament of Fig. 23.7, find
 - (i) cycles of length 3, 4 and 5;
 - (ii) an Eulerian trail;
 - (iii) a Hamiltonian cycle.
- 23.3⁵ Prove that a tournament cannot have more than one source or more than one sink.
- **23.4** Let *T* be a tournament on *n* vertices. If \sum denotes a summation over all the vertices of *T*, prove that
 - (i) $\sum \text{outdeg}(v) = \sum \text{indeg}(v);$
 - (ii) $\sum \text{outdeg}(v)^2 = \sum \text{indeg}(v)^2$.
- 23.5 Let *D* be the digraph whose vertices are the pairs of integers

11, 12, 13, 21, 22, 23, 31, 32, 33,

and whose arcs join *ij* to *kl* if and only if j = k. Find an Eulerian trail in *D* and use it to obtain a circular arrangement of nine 1s, nine 2s and nine 3s in which each of the 27 possible triples (111, 233, etc.) occurs exactly once. (Problems of this kind arise in communication theory.)

- **23.6** A tournament T is **irreducible** if it is impossible to split the set of vertices of T into two disjoint sets V_1 and V_2 so that each arc joining a vertex of V_1 and a vertex of V_2 is directed from V_1 to V_2 .
 - (i) Give an example of an irreducible tournament.
 - (ii) Prove that a tournament is irreducible if and only if it is strongly connected.
- **23.7** A tournament is **transitive** if the existence of arcs *uv* and *vw* implies the existence of the arc *uw*.
 - (i) Give an example of a transitive tournament.
 - (ii) Show that in a transitive tournament the teams can be ranked so that each team beats all the teams which follow it in the ranking.
 - Deduce that a transitive tournament with at least two vertices cannot be strongly connected.
- **23.8*** The score of a vertex of a tournament is its out-degree, and the score sequence of a tournament is the sequence formed by arranging the scores of its vertices in non-decreasing order; for example, the score-sequence of the tournament in Fig. 23.2 is (0, 2, 2, 2, 4). Show that if (s_1, \ldots, s_n) is the score-sequence of a tournament *T*, then
 - (i) $s_1 + \dots + s_n = n(n-1)/2;$
 - (ii) for each positive integer $k < n, s_1 + \dots + s_k \ge k(k-1)/2$, with strict inequality for all *k* if and only if *T* is strongly connected;
 - (iii) *T* is transitive if and only if $s_k = k 1$ for each *k*.